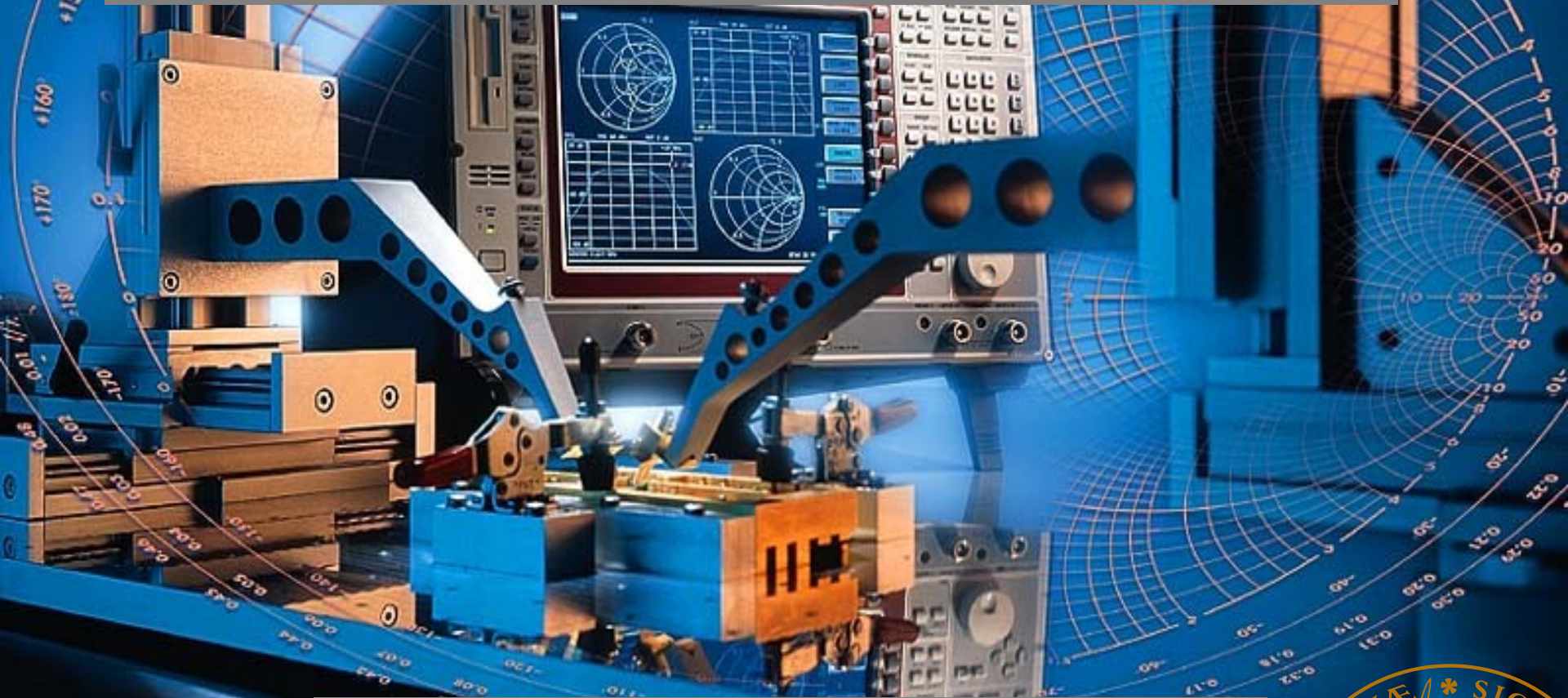


RF Amplifier Design



Lars Ohlsson Fhager
Electrical and Information Technology




Application: Millimetre Wave Radar

- Courses at LU
 - ETIN90 – Radar and Remote Sensing
- Work in Lund
 - Acconeer, www.acconeer.com
- Work abroad
 - Google SOLI, www.atap.google.com/soli

Lecture 6

- Amplifier Design
 - S-Parameters
 - Definitions
 - Power Waves
 - Applications
 - Parameter Conversion
 - Signal Flow Graphs
 - Stability Analysis
 - Power Gain Definitions
 - Design Methods
 - Maximum Gain
 - Minimum Noise Figure
 - The Vector Network Analyser (refresher from Introduction to...)



Toughest week
in the course,
hang in there

S-Parameters

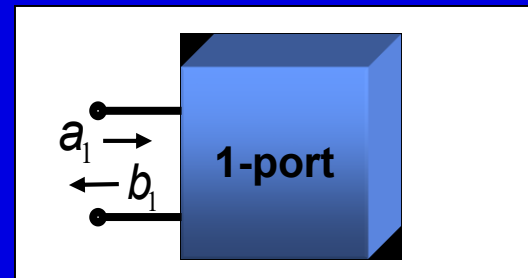
- The circuit is characterized by wave quantities

- 1-port network

- reflection coefficient

a_x = incident wave

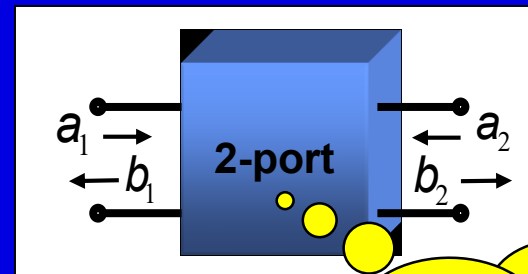
b_x = reflected wave



- N-port network

(the course only deals with 2-ports)

- S-parameters
(scattering parameters)
- T, transmission parameters
- X, large signal scattering parameters

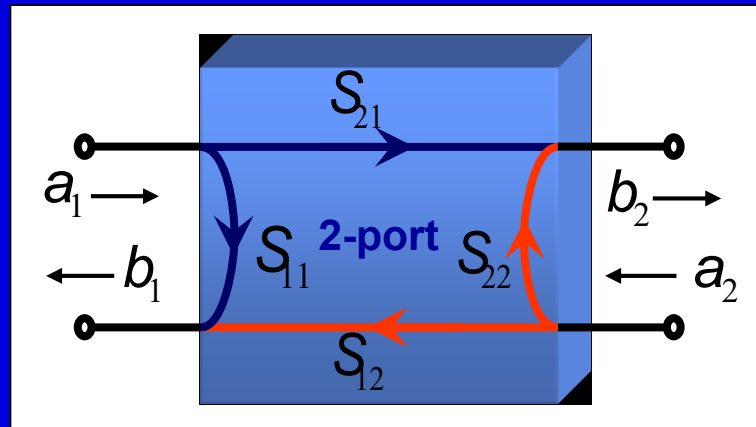


NOTE!

The definition typically utilizes $Z_0 = 50 \Omega$ as reference impedance

S-Parameters Definition

- Model:



or in matrix format:

- Definition:
$$\begin{cases} b_1 = s_{11} \cdot a_1 + s_{12} \cdot a_2 \\ b_2 = s_{21} \cdot a_1 + s_{22} \cdot a_2 \end{cases}$$

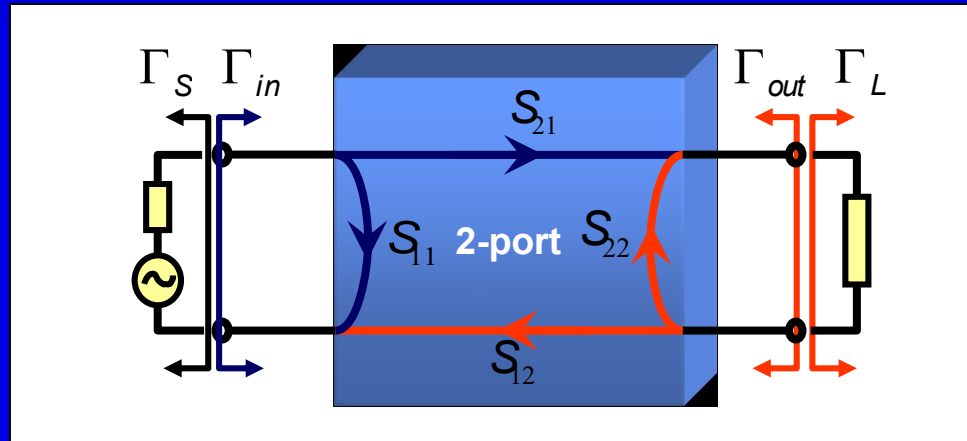
$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

- Boundary conditions:

$$\begin{aligned} s_{11} &= \left. \frac{b_1}{a_1} \right|_{a_2=0} & s_{12} &= \left. \frac{b_1}{a_2} \right|_{a_1=0} \\ s_{21} &= \left. \frac{b_2}{a_1} \right|_{a_2=0} & s_{22} &= \left. \frac{b_2}{a_2} \right|_{a_1=0} \end{aligned}$$

NOTE!
The definition typically utilizes $Z_0 = 50 \Omega$ as reference impedance

Measurement of S-Parameters



$$\Gamma_{in} = S_{11} + S_{12} S_{21} \frac{\Gamma_L}{1 - S_{22} \Gamma_L} = S_{11} \Big|_{\Gamma_L=0}$$

$$\Gamma_{out} = S_{22} + S_{12} S_{21} \frac{\Gamma_s}{1 - S_{11} \Gamma_s} = S_{22} \Big|_{\Gamma_s=0}$$

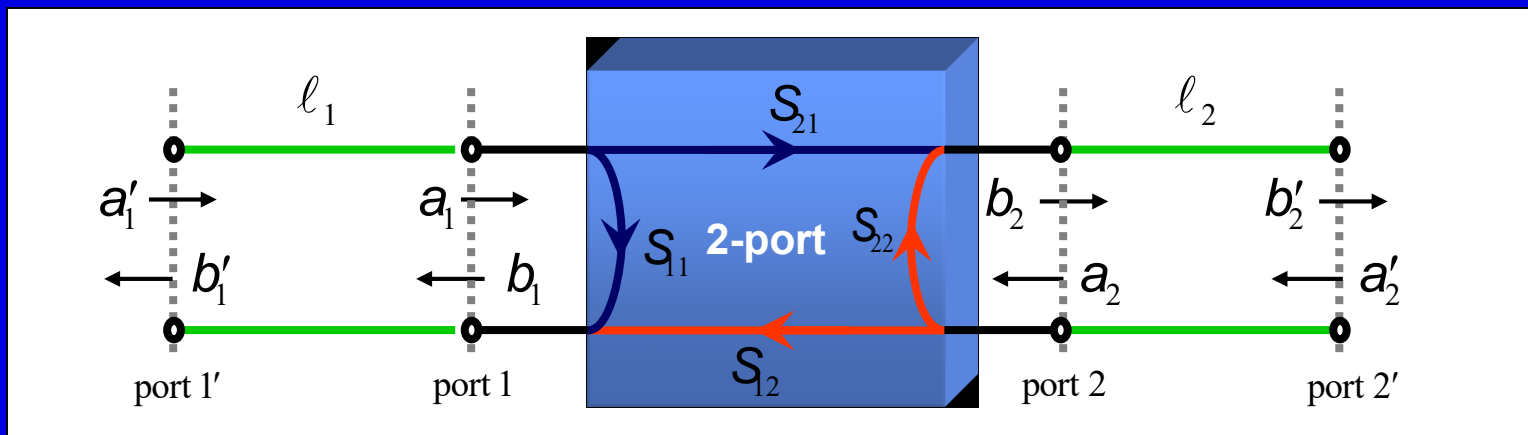
S-parameters are easily measured if the ports are terminated by the reference impedance $Z_0 = 50 \Omega$ ($\Gamma_L = 0$ respectively $\Gamma_s = 0$)

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} \quad S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0}$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} \quad S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0}$$

Transfer of the Reference Plane

A simple example when you need to compensate for the effect of the test cables:



S-parameters including test cables:

$$\begin{bmatrix} b_1' \\ b_2' \end{bmatrix} = \begin{bmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{bmatrix} \begin{bmatrix} a_1' \\ a_2' \end{bmatrix}$$

The change of the waves between the reference planes:

$$\begin{aligned} b_1 &= b_1' \exp(\gamma l_1) & a_1 &= a_1' \exp(-\gamma l_1) \\ b_2 &= b_2' \exp(\gamma l_2) & a_2 &= a_2' \exp(-\gamma l_2) \end{aligned}$$

Substitute:

$$\begin{bmatrix} b_1 \cdot e^{-\gamma l_1} \\ b_2 \cdot e^{-\gamma l_2} \end{bmatrix} = \begin{bmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{bmatrix} \begin{bmatrix} a_1 \cdot e^{\gamma l_1} \\ a_2 \cdot e^{\gamma l_2} \end{bmatrix}$$

Result:

$$\begin{bmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{bmatrix} = \begin{bmatrix} s_{11} \cdot e^{2\gamma l_1} & s_{12} \cdot e^{\gamma l_1 + \gamma l_2} \\ s_{21} \cdot e^{\gamma l_1 + \gamma l_2} & s_{22} \cdot e^{2\gamma l_2} \end{bmatrix}$$

Power Waves

- At any port:

$$V = V^+ + V^-, \quad I = I^+ - I^- = \frac{V^+}{Z_0} - \frac{V^-}{Z_0}, \quad \Gamma = \frac{V^-}{V^+} = -\frac{I^-}{I^+}$$

- Apply normalized quantities:

$$v = \frac{V}{\sqrt{2Z_0}}, \quad i = \sqrt{\frac{Z_0}{2}} I, \quad a = \frac{V^+}{\sqrt{2Z_0}}, \quad b = \frac{V^-}{\sqrt{2Z_0}}$$

where a and b are referred as power waves

- The first equations may now be written:

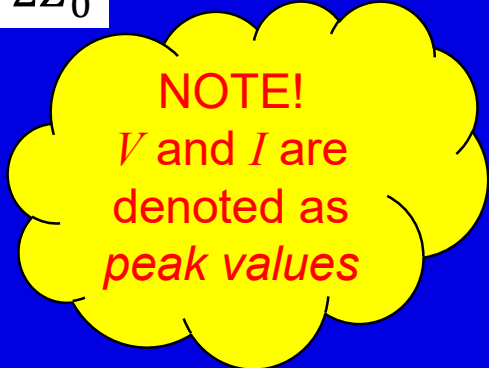
$$v = a + b, \quad i = a - b \quad \text{and} \quad b = \Gamma a$$

- The power in the waves are:

$$P^+ = \frac{|V^+|^2}{2Z_0} = |a|^2 \quad \text{and} \quad P^- = \frac{|V^-|^2}{2Z_0} = |b|^2$$

- The power delivered to the two-port is then:

$$P_{IN} = P^+ - P^- = |a|^2 - |b|^2$$

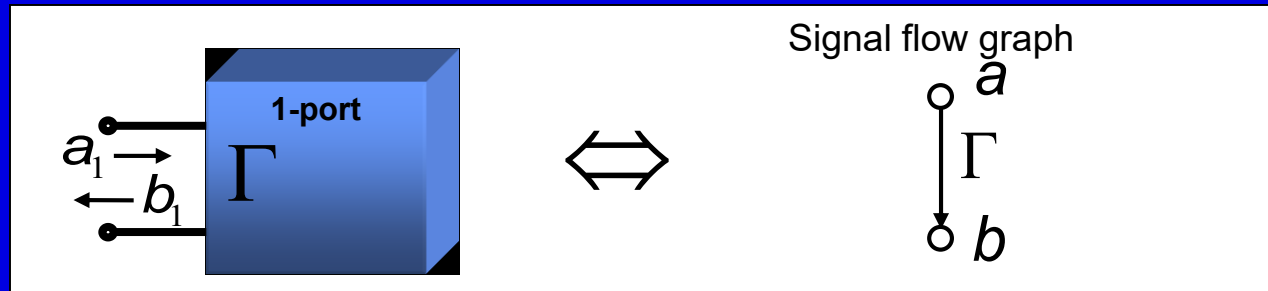


NOTE!
 V and I are denoted as *peak values*

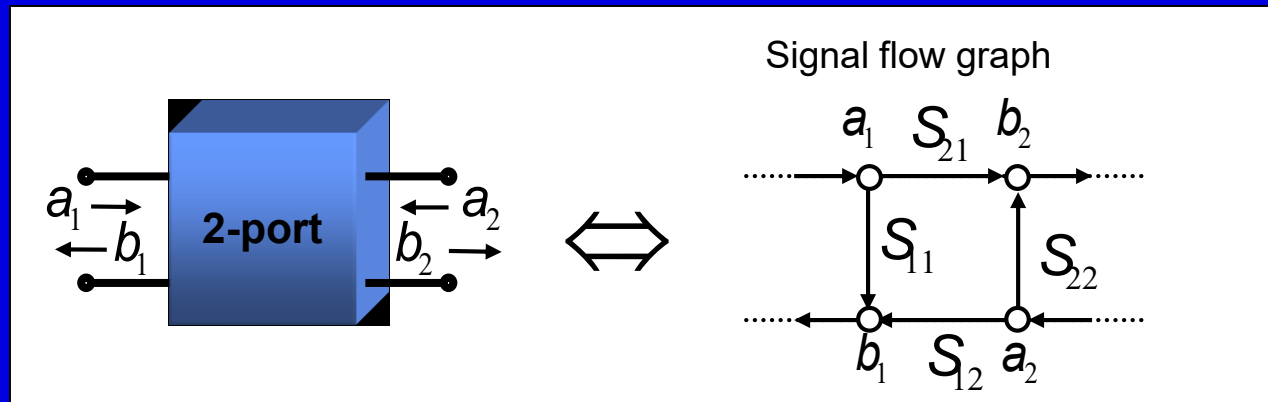
Graphic Representation of Waves in Circuits

- Ordinary circuit diagrams are not effective as they only represent nodes (voltages) and branches (currents).
- **Signal flow graphs** are useful tools as waves in different directions are separated and represented by nodes.

example:
1-port



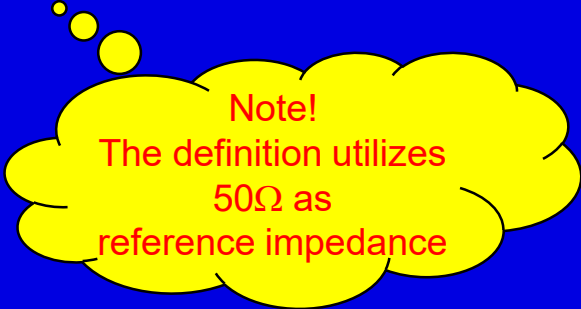
2-port



- Methods for systematic analysis by signal flow graphs are depicted in chapter 8.4.3

S-Parameters, Parameter Conversion

- The S-parameters may be converted into y, z or ABCD parameters and vice versa without any loss of information
- Conversion of S-parameters results in normalised y, z and ABCD parameters
- Example: 1) Convert S-parameters to z parameters
2) Denormalise: $Z = z \cdot 50\Omega$



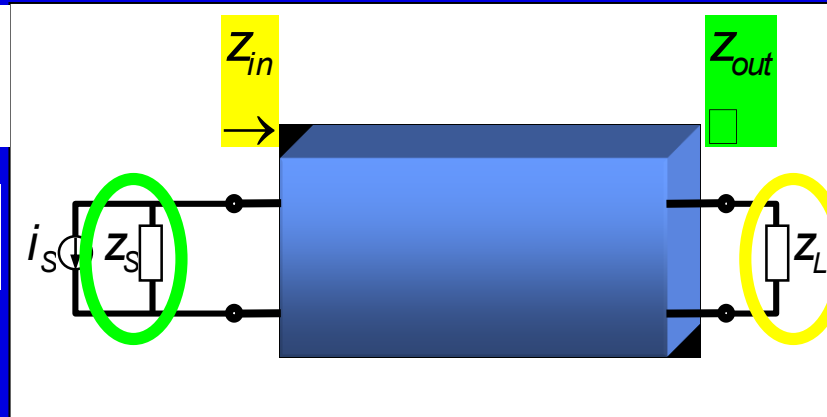
Note!
The definition utilizes
50Ω as
reference impedance

Stability Analysis by S-Parameters

- Definition of **unconditional** stability:

$$y_{in} = y_{11} - \frac{y_{21}y_{12}}{y_{22} + y_L}$$

$$\Gamma_{in} = S_{11} + S_{12}S_{21} \frac{\Gamma_L}{1 - S_{22}\Gamma_L}$$



$$y_{out} = y_{22} - \frac{y_{12}y_{21}}{y_{11} + y_S}$$

$$\Gamma_{out} = S_{22} + S_{12}S_{21} \frac{\Gamma_S}{1 - S_{11}\Gamma_S}$$

$\text{Re}[z_{in}] > 0$ for any value of z_L (assume $\text{Re}[z_L] > 0$)

$\text{Re}[z_{out}] > 0$ for any value of z_S (assume $\text{Re}[z_S] > 0$)

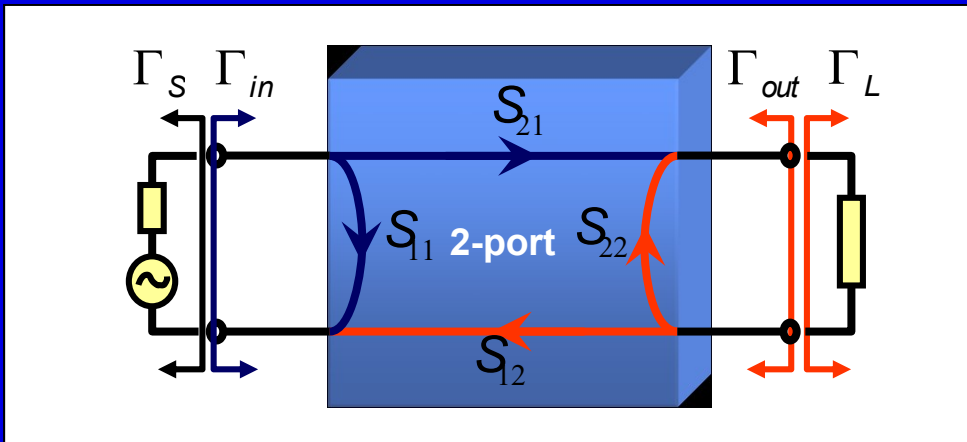
or

$|\Gamma_{in}| < 1$ for all $|\Gamma_L| < 1$

$|\Gamma_{out}| < 1$ for all $|\Gamma_S| < 1$

Bilateral and Unilateral Two-Port

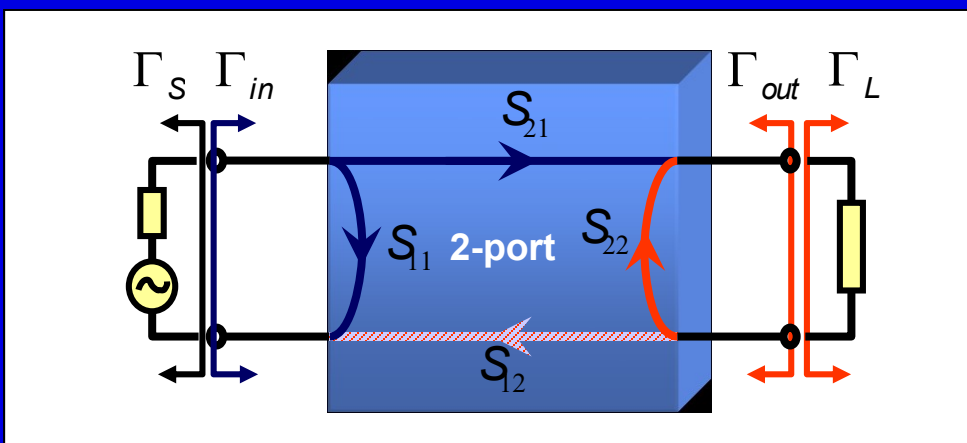
Bilateral two-port



$$\Gamma_{in} = S_{11} + S_{12} S_{21} \frac{\Gamma_L}{1 - S_{22} \Gamma_L}$$

$$\Gamma_{out} = S_{22} + S_{12} S_{21} \frac{\Gamma_s}{1 - S_{11} \Gamma_s}$$

Unilateral two-port: $S_{12} = 0$ (does these really exist?)



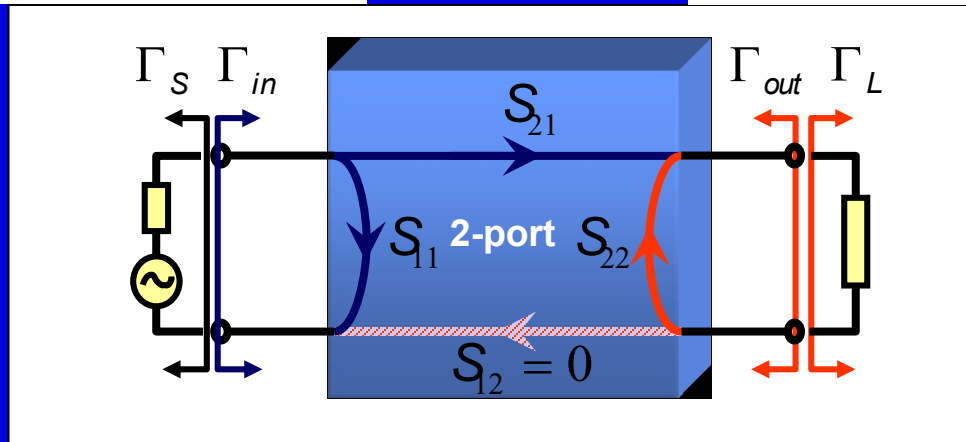
$$\Gamma_{in} = S_{11} + S_{12} S_{21} \frac{\Gamma_L}{1 - S_{22} \Gamma_L} = S_{11} |_{S_{12}=0}$$

$$\Gamma_{out} = S_{22} + S_{12} S_{21} \frac{\Gamma_s}{1 - S_{11} \Gamma_s} = S_{22} |_{S_{12}=0}$$

Stability Analysis, Unilateral Two-Port

$$\Gamma_{in} = S_{11} + S_{12}S_{21} \frac{\Gamma_L}{1 - S_{22}\Gamma_L} = S_{11} \Big|_{S_{22}=0}$$

$$\Gamma_{out} = S_{22} + S_{12}S_{21} \frac{\Gamma_S}{1 - S_{11}\Gamma_S} = S_{22} \Big|_{S_{11}=0}$$

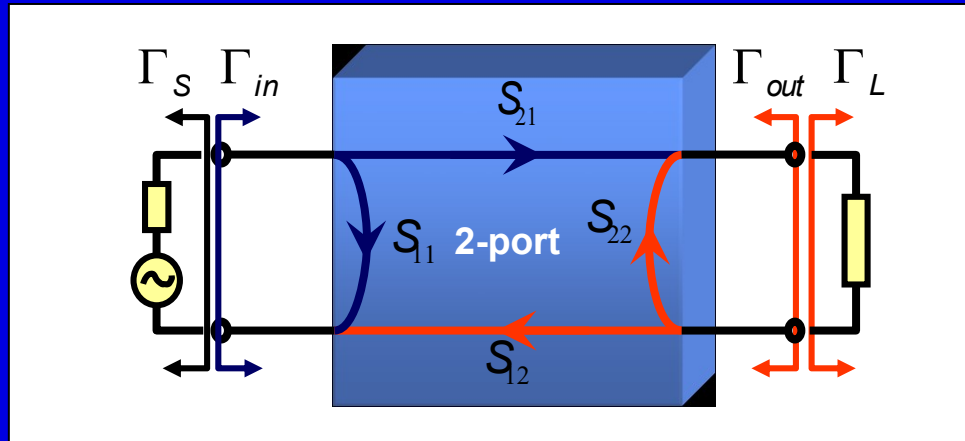


The unilateral two-port ($S_{12} = 0$) is **unconditionally** stable if

$$\left\{ \begin{array}{l} |\Gamma_{in}| < 1 \text{ for all } |\Gamma_L| < 1 \\ |\Gamma_{out}| < 1 \text{ for all } |\Gamma_S| < 1 \end{array} \right. \quad \text{i.e.} \quad \left\{ \begin{array}{l} |\Gamma_{in}| = |S_{11}| < 1 \\ |\Gamma_{out}| = |S_{22}| < 1 \end{array} \right. \quad \text{and}$$

Stability Analysis, Bilateral Two-Port

How can we show if a bilateral two-port is **unconditionally** stable?



$$\begin{cases} |\Gamma_{in}| = \left| S_{11} + S_{12} S_{21} \frac{\Gamma_L}{1 - S_{22} \Gamma_L} \right| < 1 \\ |\Gamma_{out}| = \left| S_{22} + S_{12} S_{21} \frac{\Gamma_s}{1 - S_{11} \Gamma_s} \right| < 1 \end{cases} \quad \text{for all } |\Gamma_s| < 1 \text{ and } |\Gamma_L| < 1$$

After an extensive analysis the stability criteria can be reformulated as

$$|\Delta| < 1 \text{ and } K > 1 \quad \text{where} \quad \Delta = S_{11} S_{22} - S_{12} S_{21} \quad \text{and} \quad K = \frac{1 - |S_{11}|^2 - |S_{22}|^2 + |\Delta|^2}{2 |S_{12} S_{21}|}$$

Stability Analysis, Bilateral Two-Port (cont.)

(BREAK)

But if $|\Delta| < 1$ and $K > 1$ not are fulfilled, what then?

- There may be some
 - Γ_L that provides $|\Gamma_{in}| < 1$ and
 - Γ_S that provides $|\Gamma_{out}| < 1$
- The two-port is then considered to be **conditionally stable**
- Where is the boundary for stability?
- Find
 - all Γ_L that gives $|\Gamma_{in}| = 1$ and
 - all Γ_S that gives $|\Gamma_{out}| = 1$

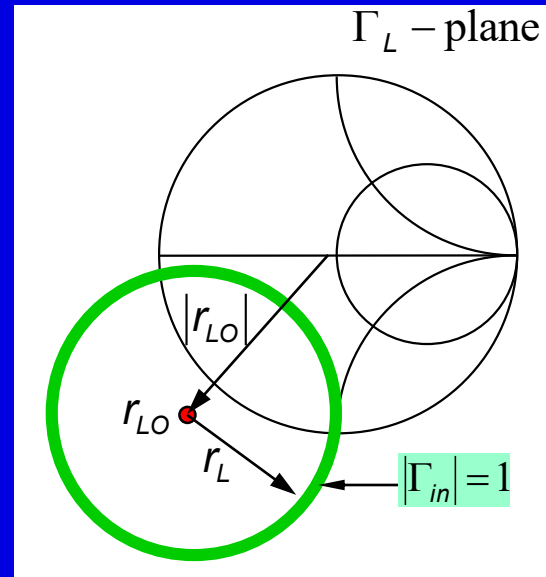
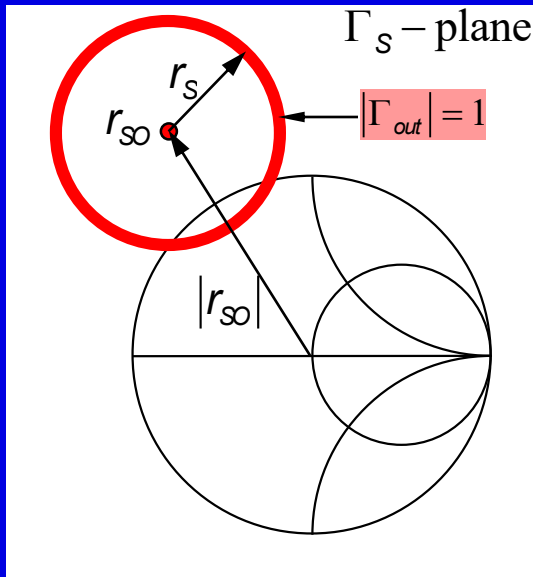
Stability Analysis, Bilateral Two-Port (cont.)

Solve $|\Gamma_{out}| = 1$ with respect to Γ_S and $|\Gamma_{in}| = 1$ with respect to Γ_L

$$\Gamma_{out} = S_{22} + S_{12}S_{21} \frac{\Gamma_S}{1 - S_{11}\Gamma_S}$$

$$\Gamma_{in} = S_{11} + S_{12}S_{21} \frac{\Gamma_L}{1 - S_{22}\Gamma_L}$$

The result is stability circles:



Γ_S -plane:

radius

$$r_s = \frac{|S_{12}S_{21}|}{|S_{11}|^2 - |\Delta|^2}$$

centre

$$\Gamma_{so} = \frac{S_{11}^* - \Delta^* S_{22}}{|S_{11}|^2 - |\Delta|^2}$$

Γ_L -plane:

radius

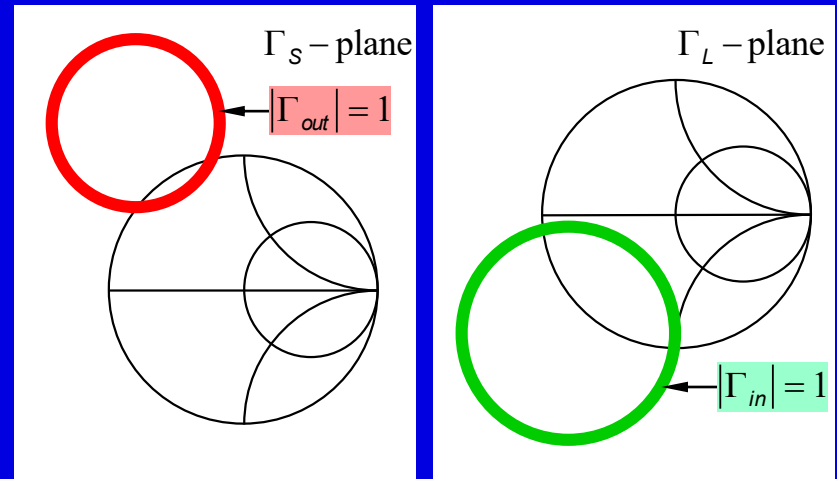
$$r_L = \frac{|S_{12}S_{21}|}{|S_{22}|^2 - |\Delta|^2}$$

centre

$$\Gamma_{LO} = \frac{S_{22}^* - \Delta^* S_{11}}{|S_{22}|^2 - |\Delta|^2}$$

Stability Circles

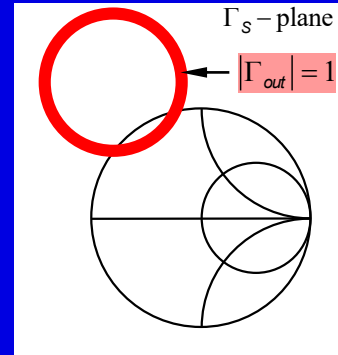
- The stability circles denotes
 - all Γ_S that equals $|\Gamma_{out}| = 1$ and
 - all Γ_L that equals $|\Gamma_{in}| = 1$
 the circles accordingly shows the boundary for instability...



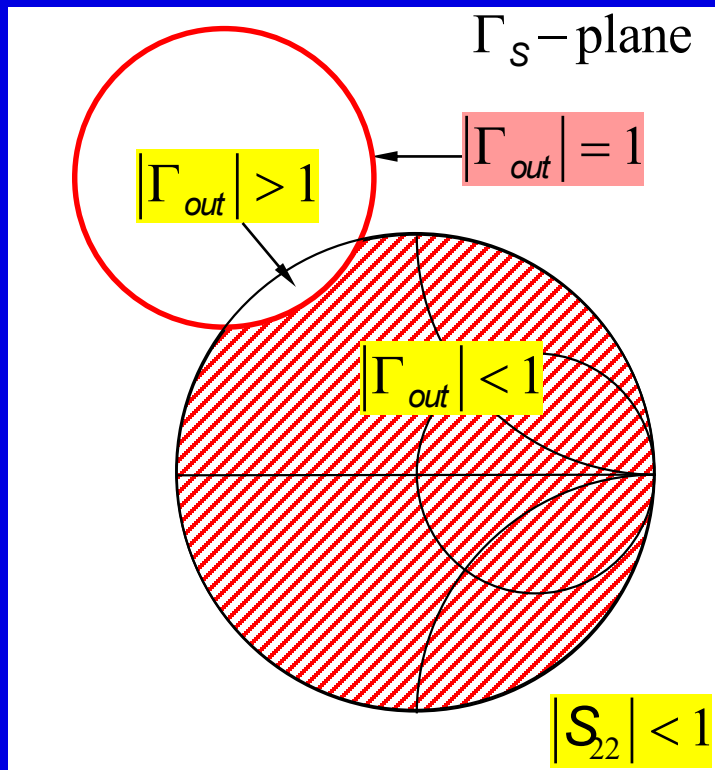
- But **which** Γ_S and Γ_L implies stability?
i.e. are the Γ that provides stability found inside or outside respectively stability circle?
 - Test at one location!
 - It is understood that **if one point is part of the stable set**, e.g. in the Γ_S -plane, then **this holds for all other points belonging to the same set.**
 - Tip: **test at the centre of the Smith chart!** Why is this smart?
- $$\Gamma_{out} = S_{22} + S_{12}S_{21} \frac{\Gamma_S}{1 - S_{11}\Gamma_S} = S_{22} \Big|_{\Gamma_S=0}$$
- Perform the same test in the Γ_L -plane.

Stability Circles (cont.)

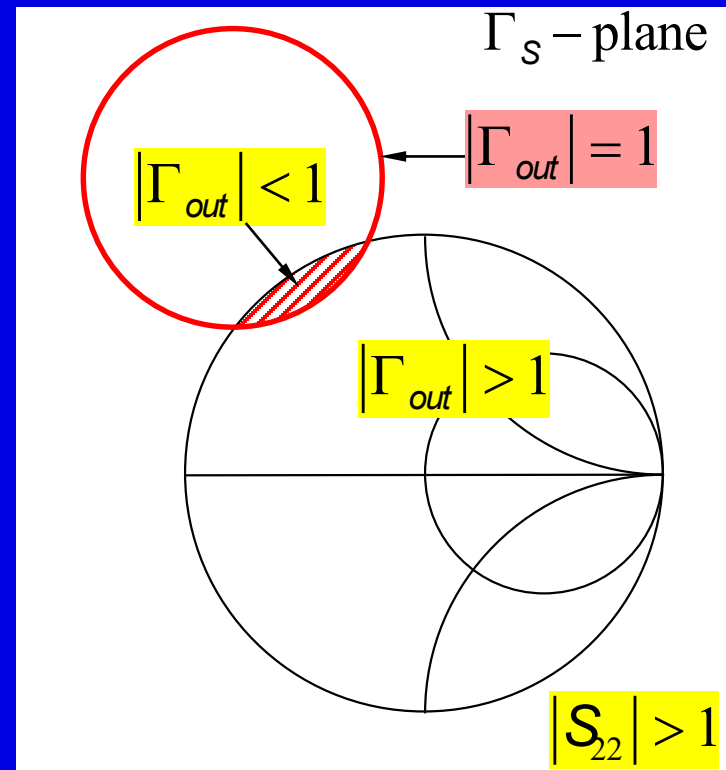
- In which area is the output stable?
- Test at the centre in the Γ_S -plane: $\Gamma_S = 0 \rightarrow \Gamma_{out} = S_{22}$
 - is $|S_{22}|$ greater or less than one?



$|S_{22}| < 1 \rightarrow$ stable outside the circle

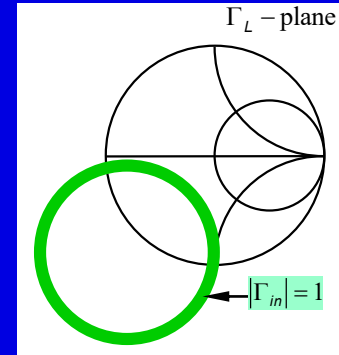


$|S_{22}| > 1 \rightarrow$ stable inside the circle

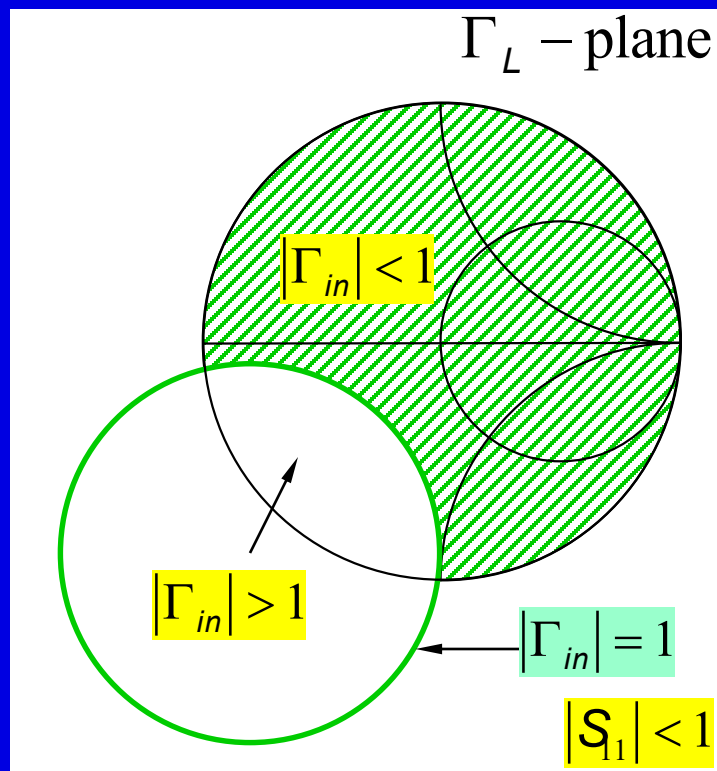


Stability Circles (cont.)

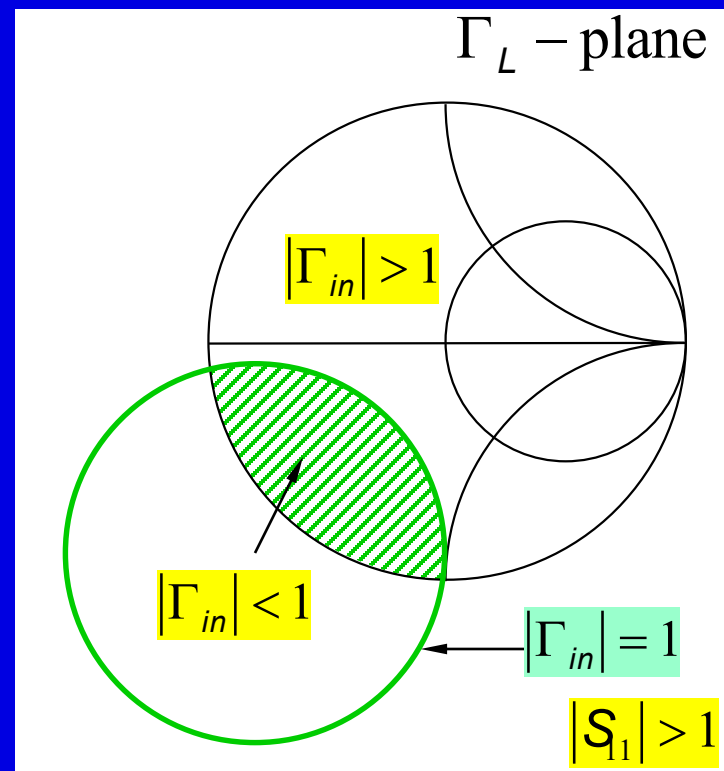
- In which area is the input stable?
- Test at the centre in the Γ_L -plane: $\Gamma_L = 0 \rightarrow \Gamma_{in} = S_{11}$
 - is $|S_{11}|$ greater or less than one?



$|S_{11}| < 1 \rightarrow$ stable outside the circle

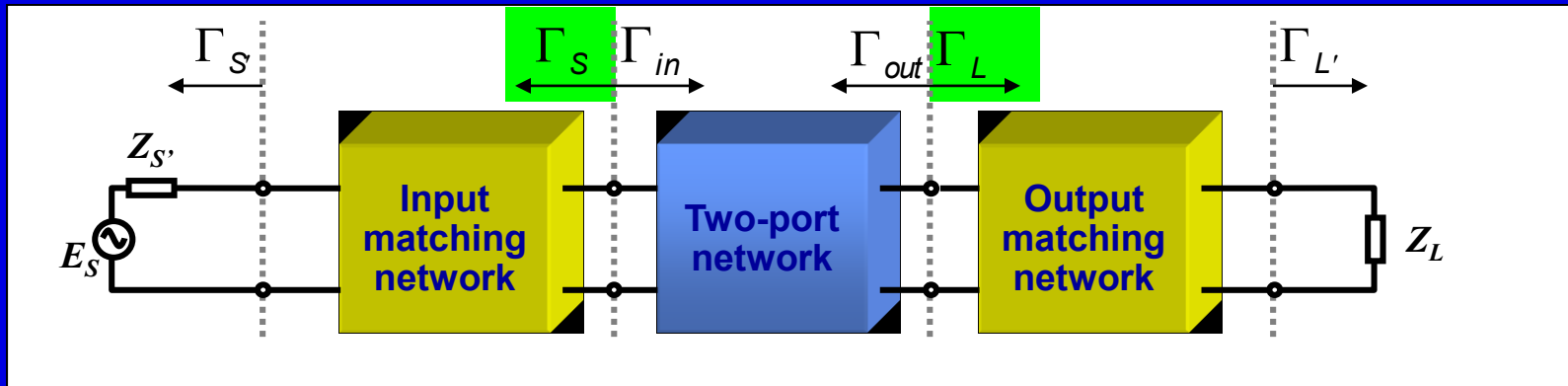


$|S_{11}| > 1 \rightarrow$ stable inside the circle



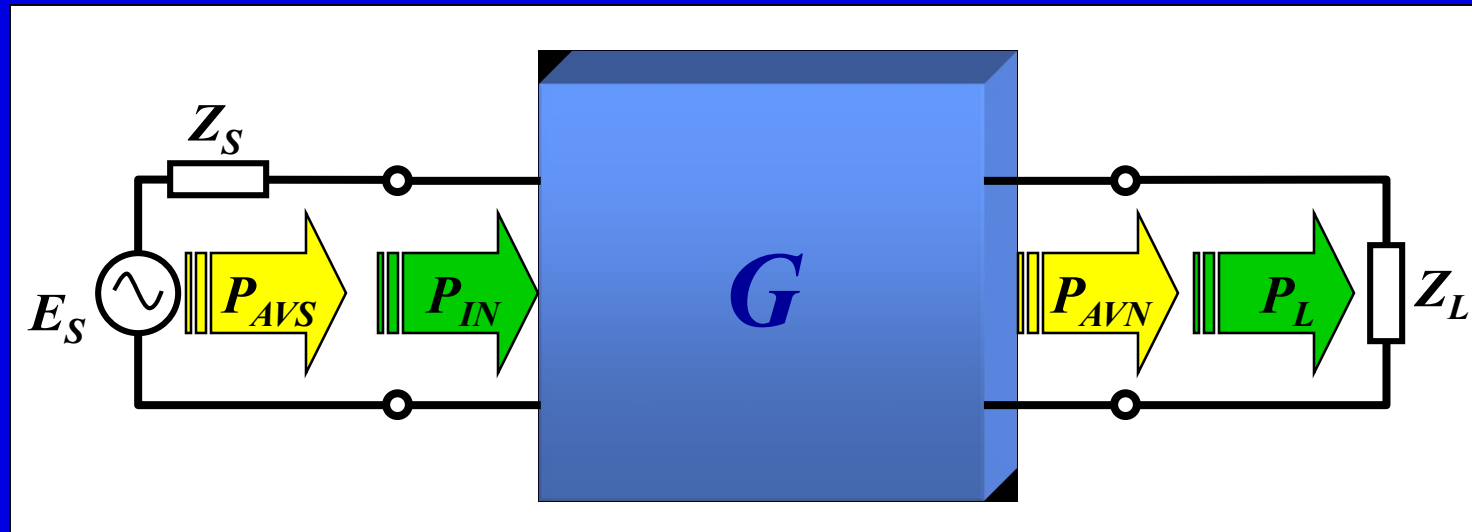
Amplifier Design

General design case



- Given this:
 - two-port (S-parameters) and
 - source Γ_S and load Γ_L
- The stability analysis gives allowed values of Γ_S and Γ_L
- After a proper choice of Γ_S and Γ_L the matching networks may be designed

Power Gain Definitions

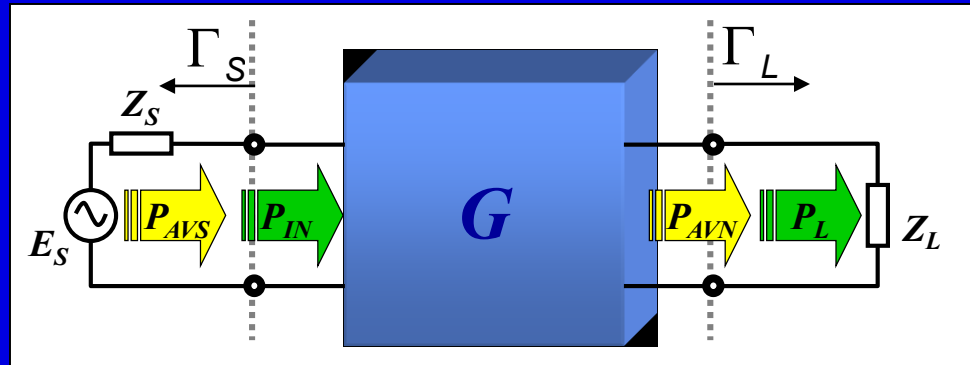


available gain $G_A = \frac{P_{AVN}}{P_{AVS}}$

operating gain $G_P = \frac{P_L}{P_{IN}}$

transducer gain $G_T = \frac{P_L}{P_{AVS}}$

The Gain Expressed by S-Parameters



available gain

$$G_A = \frac{P_{AVN}}{P_{AVS}} = \frac{1 - |\Gamma_S|^2}{|1 - S_{11}\Gamma_S|^2} |S_{21}|^2 \frac{1}{1 - |\Gamma_{out}|^2}$$

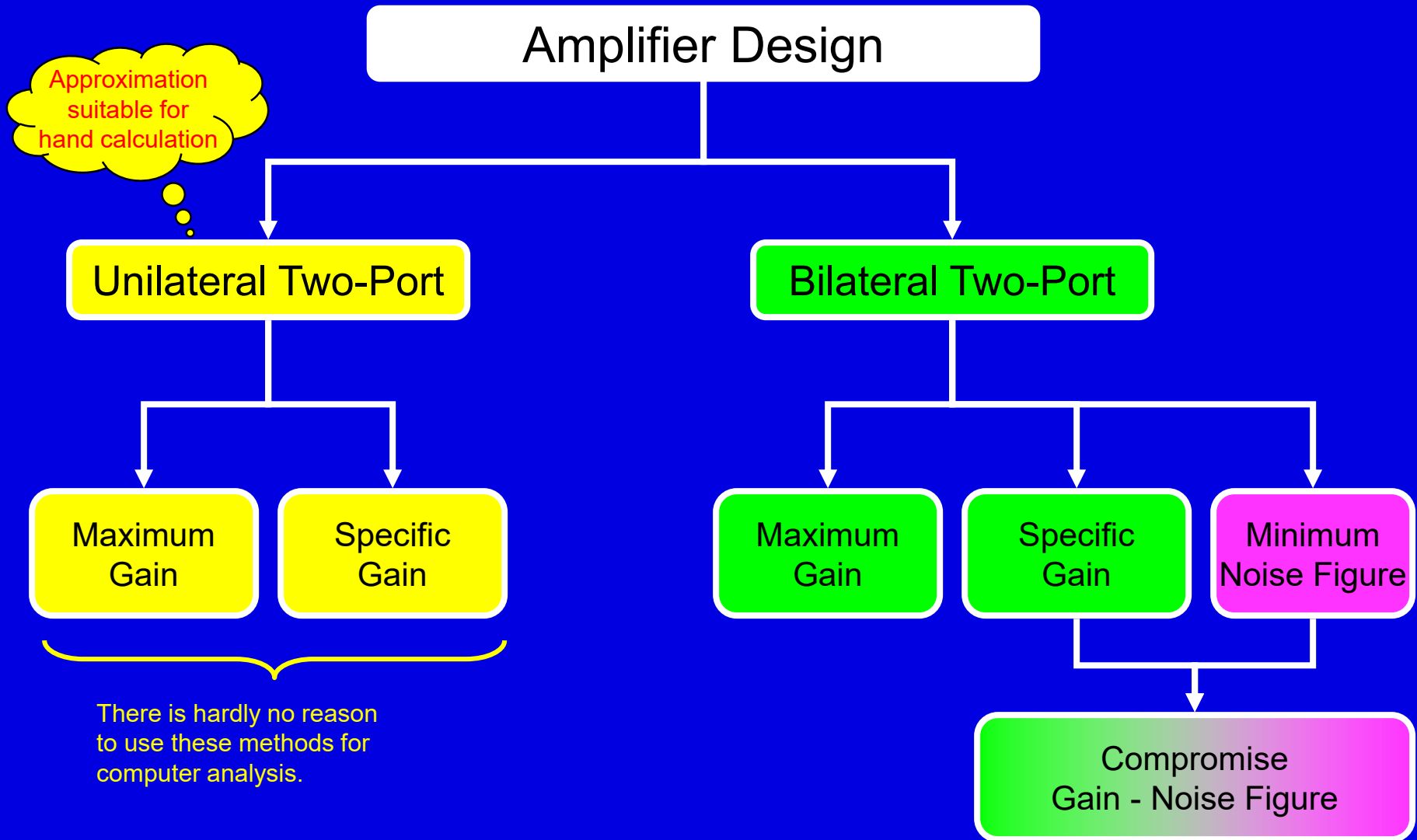
operating gain

$$G_P = \frac{P_L}{P_{IN}} = \frac{1}{1 - |\Gamma_{in}|^2} |S_{21}|^2 \frac{1 - |\Gamma_L|^2}{|1 - S_{22}\Gamma_L|^2}$$

transducer gain

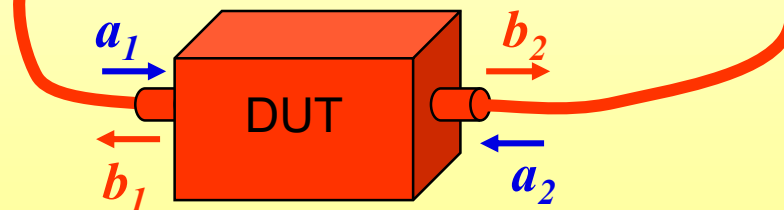
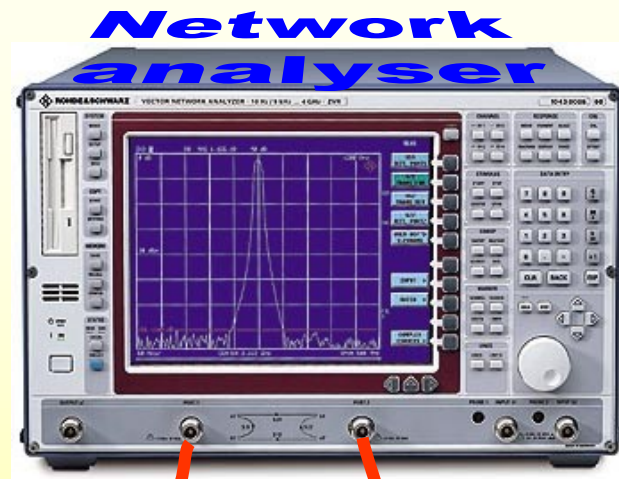
$$\begin{aligned} G_T &= \frac{P_L}{P_{AVS}} = \frac{1 - |\Gamma_S|^2}{|1 - \Gamma_{in}\Gamma_S|^2} |S_{21}|^2 \frac{1 - |\Gamma_L|^2}{|1 - S_{22}\Gamma_L|^2} = \\ &= \frac{1 - |\Gamma_S|^2}{|1 - S_{11}\Gamma_S|^2} |S_{21}|^2 \frac{1 - |\Gamma_L|^2}{|1 - \Gamma_{out}\Gamma_L|^2} \end{aligned}$$

Design Cases - Gain and Noise Figure



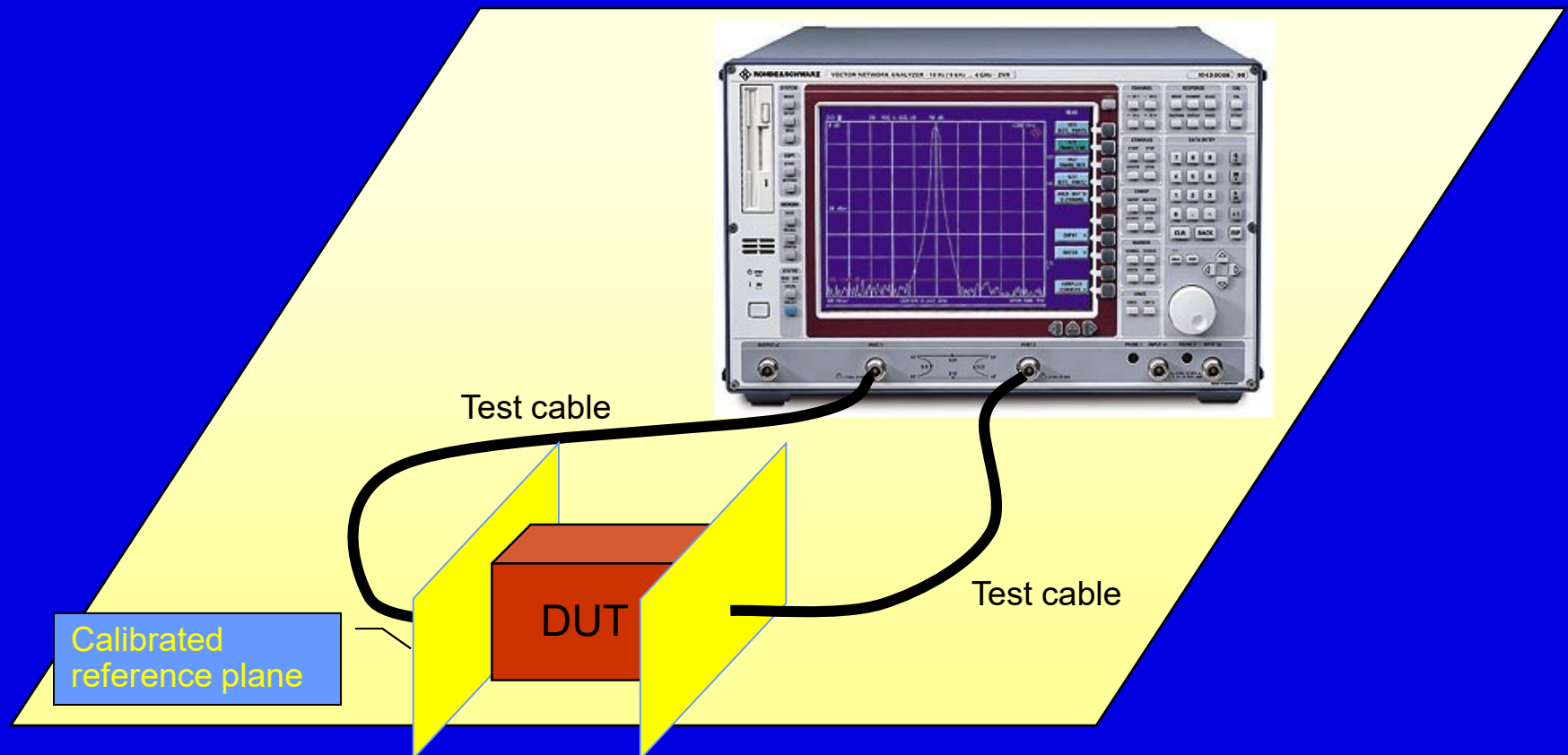
Vector Network Analysis

- Characterising the **D**evice **U**nder **T**est properties
- Network Analyser
 - frequency sweep
 - amplitude sweep
 - complete information
 - amplitude
 - phase



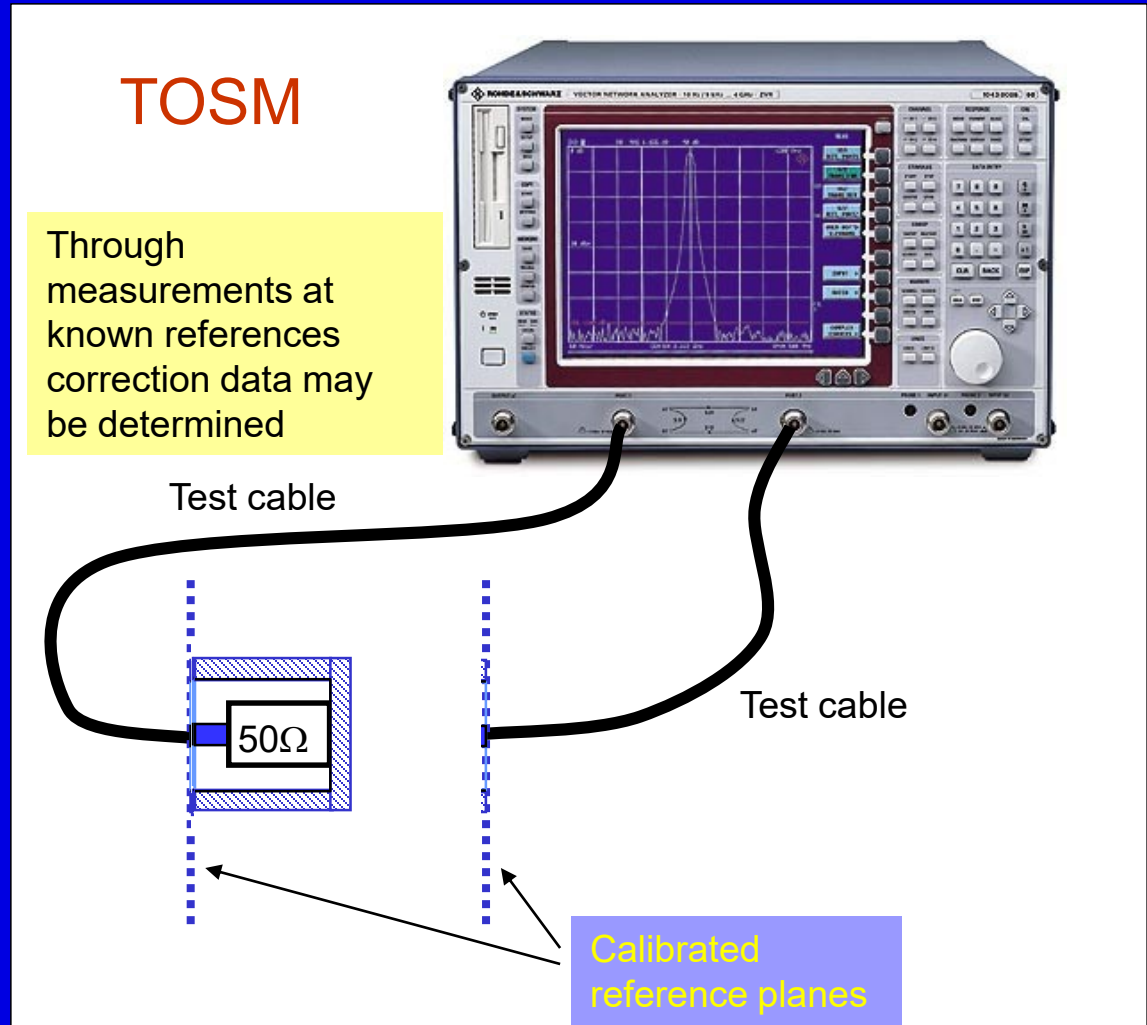
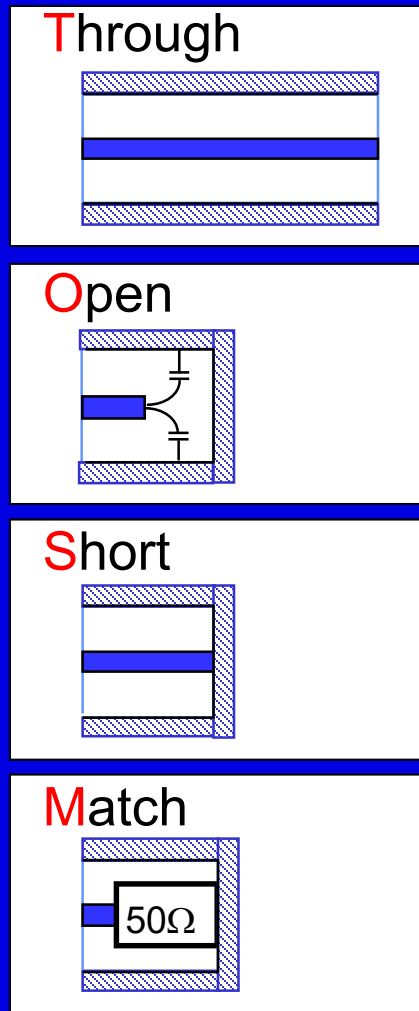
Calibration

- Attenuation and phase shift in the test cables must be compensated
- Calibrated reference planes are therefore created where the device under test is connected



Calibration

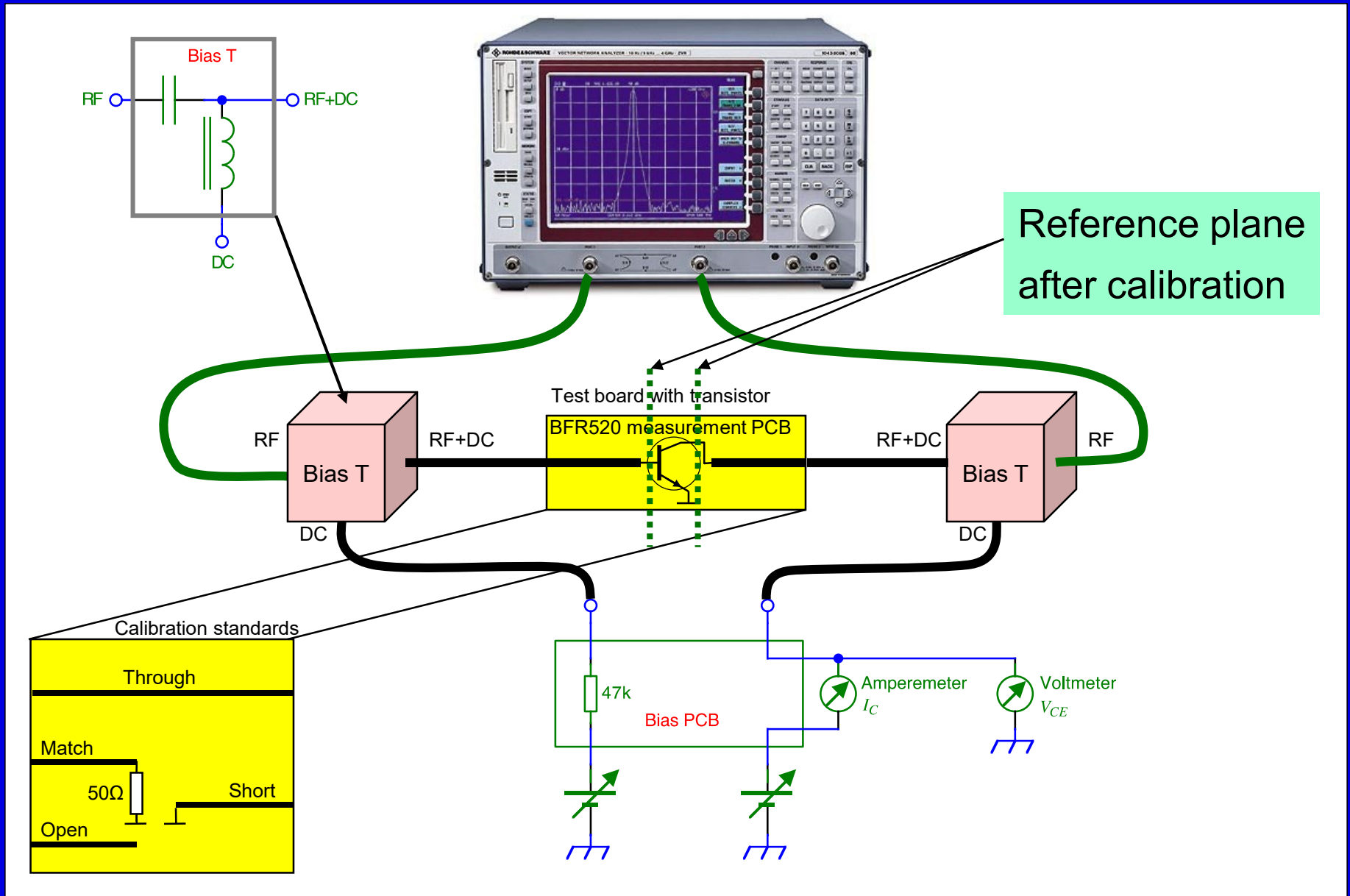
- Calibrated reference planes will be created where the DUT is to be connected



Be careful about torn connectors!

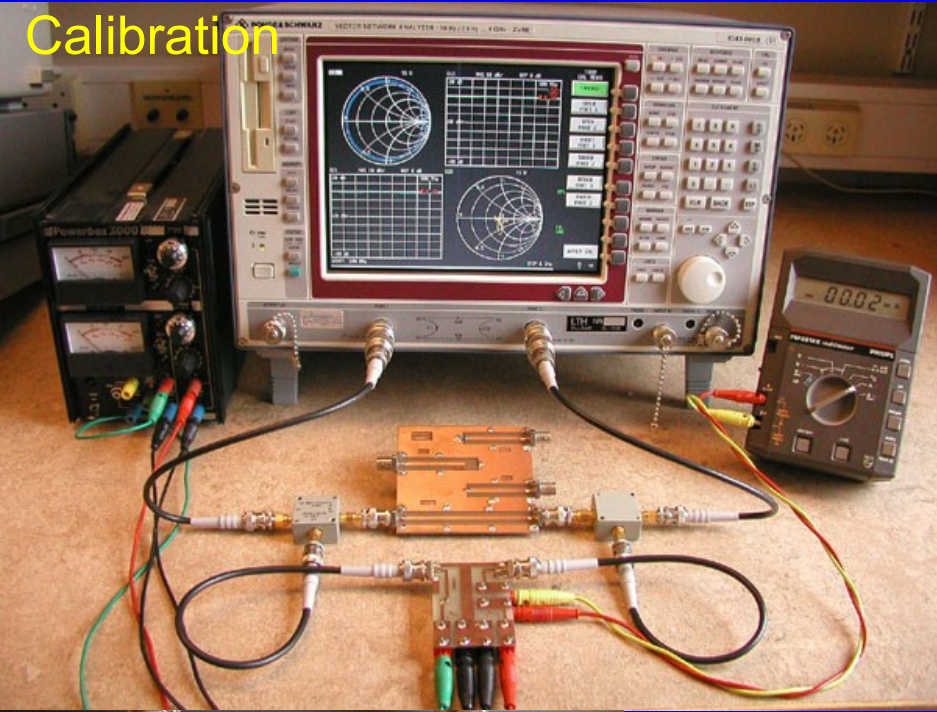
- The wear and tear when connectors are connected and disconnected may result in measurement errors.
 - always check that the connectors are **clean**
 - **only turn the socket or the nut**
 - the contact pin may **never** spin round
 - **always use a torque wrench or fingers**
 - the connector may never be fastened by other tools
if you tighten up to hard the thread is harmed
- Test cables and connectors for professional use are only used for a limited period until they will be exchanged or reconditioned.

S-Parameter Measurements on a Transistor

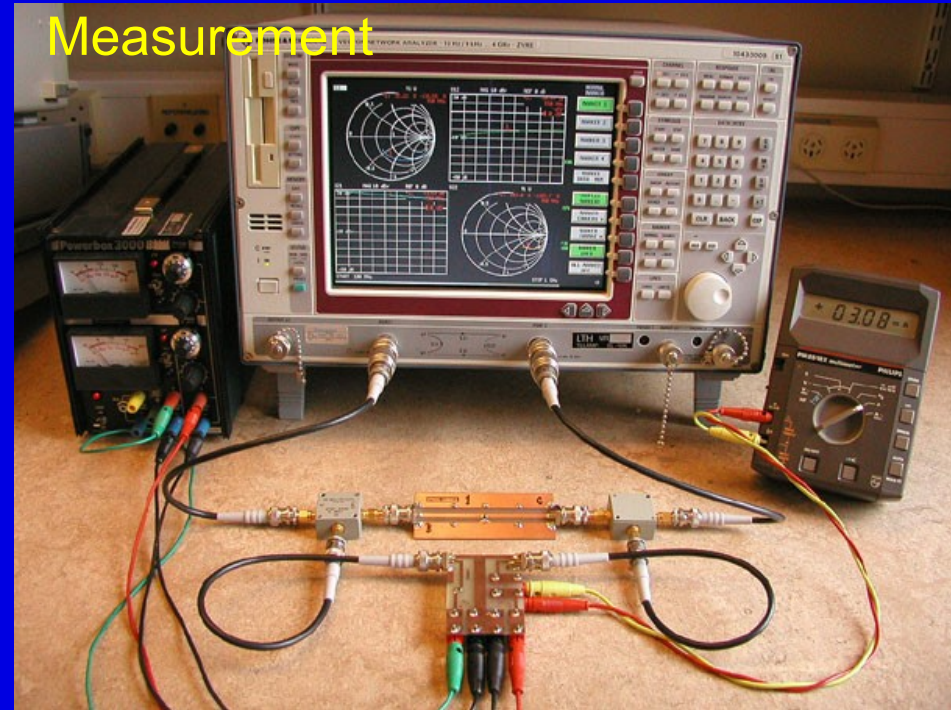


Lab 2

Calibration



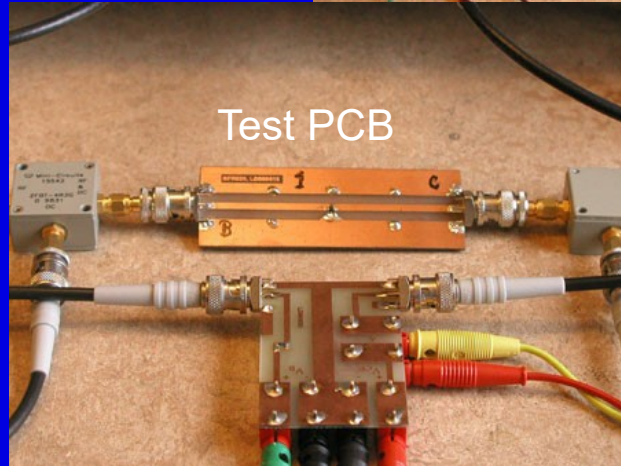
Measurement



Calibration standards



Test PCB



Transistor

