

Formelsamling i kretsteori, ellära och elektronik

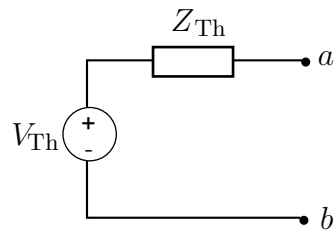
Elektro- och informationsteknik
Lunds tekniska högskola
Maj 2013

Kretsteori

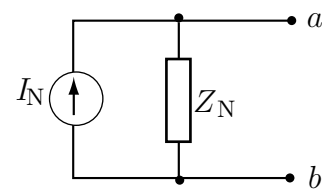
Komplexvärden

- Realdelskonvention: $v(t) = \operatorname{Re}\{V e^{j\omega t}\}$ och $i(t) = \operatorname{Re}\{I e^{j\omega t}\}$.
- Imaginärdelskonvention: $v(t) = \operatorname{Im}\{V e^{j\omega t}\}$ och $i(t) = \operatorname{Im}\{I e^{j\omega t}\}$.

Tvåpolsekvivalenter



Thévenin



Norton

Komplex effekt

$$S = \frac{1}{2} V I^* = P + jQ = |S|(\cos \varphi + j \sin \varphi)$$

$$S = \text{komplex effekt} \quad [\text{VA}]$$

$$|S| = \text{skenbar effekt} \quad [\text{VA}]$$

$$P = \operatorname{Re} S = \text{aktiv effekt (=tidsmedelvärdet av effektförbrukningen)} \quad [\text{W}]$$

$$Q = \operatorname{Im} S = \text{reaktiv effekt} \quad [\text{VA}_r] = [\text{VAR}]$$

$$\cos \varphi = \text{effektfaktor}$$

Effektanpassningsregeln

$$Z_L = Z_i^* \quad \text{och} \quad \max\{P_L\} = \frac{|V|^2}{8R_i}.$$

Ömsesidig induktans

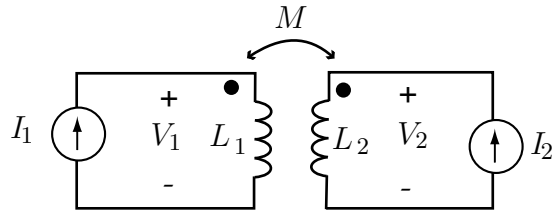
$$\begin{cases} V_1 = j\omega L_1 I_1 + j\omega M I_2 \\ V_2 = j\omega L_2 I_2 + j\omega M I_1 \end{cases}$$

$L_1, L_2 =$ självinduktanser

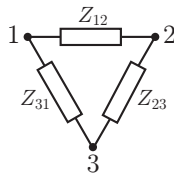
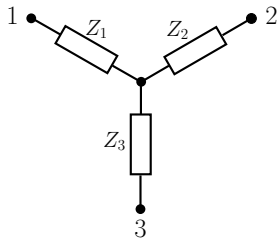
$M =$ ömsesidig induktans

$M = k\sqrt{L_1 L_2}$ där $0 \leq k \leq 1$

$k =$ kopplingsfaktorn



Nätverkstransformation



Y till Δ

$$Z_{12} = Z_1 + Z_2 + \frac{Z_1 Z_2}{Z_3}$$

$$Z_{23} = Z_2 + Z_3 + \frac{Z_2 Z_3}{Z_1}$$

$$Z_{31} = Z_3 + Z_1 + \frac{Z_3 Z_1}{Z_2}$$

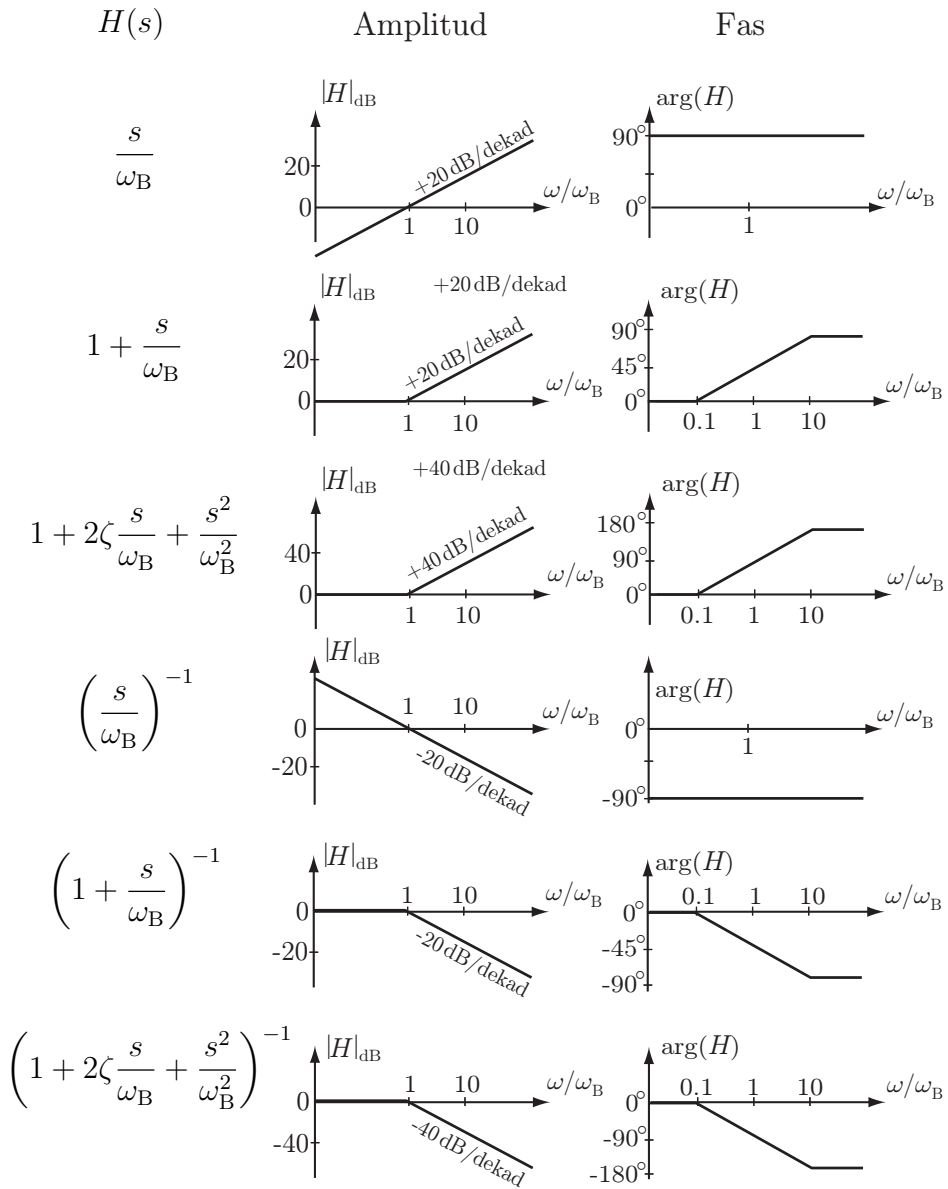
Δ till Y

$$Z_1 = \frac{Z_{31} Z_{12}}{Z_{12} + Z_{23} + Z_{31}}$$

$$Z_2 = \frac{Z_{12} Z_{23}}{Z_{12} + Z_{23} + Z_{31}}$$

$$Z_3 = \frac{Z_{23} Z_{31}}{Z_{12} + Z_{23} + Z_{31}}$$

Rätlinjeapproximationer av Bodediagram

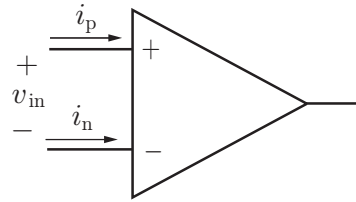


OBS! Det skall gälla att $|\zeta| \leq 1$.

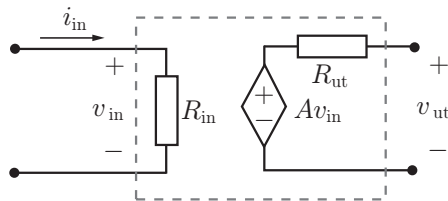
Elektronik

Ideal operationsförstärkare (OP)

För en ideal OP är $i_p = i_n = 0$. Vi använder vanligtvis negativ återkoppling där också $v_{in} = 0$.



Kretsmodell av spänningsförstärkare



Dioder

Shockleyekvationen

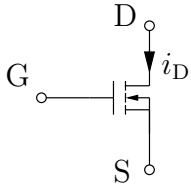
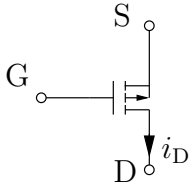
$$i_D = I_s \left(e^{\frac{v_D}{nV_T}} - 1 \right)$$

där $V_T = \frac{kT}{q}$, $q \approx 1.6 \cdot 10^{-19}$ C och $k \approx 1.38 \cdot 10^{-23}$ J/K.

Dynamisk resistans

$$r_d = \frac{1}{\left. \frac{di_D}{dv_D} \right|_Q}$$

MOSFET

| | NMOS | PMOS |
|-------------------------------|---|---|
| Kretssymbol |  |  |
| $\mu \approx$ | $675 \text{ cm}^2 \text{V}^{-1} \text{s}^{-1}$ | $240 \text{ cm}^2 \text{V}^{-1} \text{s}^{-1}$ |
| $\kappa \approx$ | $115 \mu \text{AV}^{-2}$ | $40 \mu \text{AV}^{-2}$ |
| $V_t \approx$ | $+0.5 \text{ V}$ | -0.6 V |
| Subtröskel (strypt område) | $v_{GS} \leq V_t,$ $v_{DS} \geq 0,$ $i_D = 0$ | $v_{GS} \geq V_t,$ $v_{DS} \leq 0,$ $i_D = 0$ |
| Linjärt område | $v_{GS} \geq V_t,$ $0 \leq v_{DS} \leq v_{GS} - V_t,$ $i_D = K(2(v_{GS} - V_t)v_{DS} - v_{DS}^2)$ | $v_{GS} \leq V_t,$ $0 \geq v_{DS} \geq v_{GS} - V_t,$ $i_D = K(2(v_{GS} - V_t)v_{DS} - v_{DS}^2)$ |
| Mättnads- område | $v_{GS} \geq V_t,$ $v_{DS} \geq v_{GS} - V_t,$ $i_D = K(v_{GS} - V_t)^2$ | $v_{GS} \leq V_t,$ $v_{DS} \leq v_{GS} - V_t,$ $i_D = K(v_{GS} - V_t)^2$ |
| v_{DS}, v_{GS} | Vanligtvis positiva | Vanligtvis negativa |

$$K = \frac{W}{L} \frac{\kappa}{2}$$

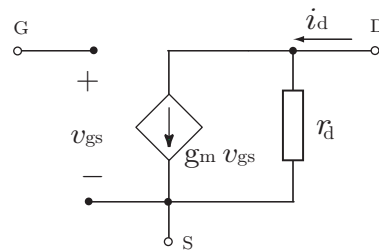
Småsignalmodell

Småsignalmodell för en FET, där

$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_{\text{arbetspunkt}}$$

och

$$\frac{1}{r_d} = \left. \frac{\partial i_D}{\partial v_{DS}} \right|_{\text{arbetspunkt}}$$



Ellära

Lorentzkraften

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Elektriskt fält och potential från punktladdning

$$\mathbf{E} = \frac{q}{4\pi\epsilon_0 r^2} \mathbf{e}_r \quad V = \frac{q}{4\pi\epsilon_0 r}$$

Spänning

$$U = V_1 - V_2 = \int_{P_1}^{P_2} \mathbf{E} \cdot d\mathbf{r}$$

Elektrisk dipol

$$\mathbf{p} = p\mathbf{e}_z \quad p = q\ell \quad \mathbf{E} = \frac{p}{4\pi\epsilon_0 r^3} (2 \cos \theta \mathbf{e}_r + \sin \theta \mathbf{e}_\theta)$$

Polarisation P och elektrisk flödestäthet D

$$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P}$$

$$\mathbf{P} = \chi_e \epsilon_0 \mathbf{E}$$

$$\epsilon_r = 1 + \chi_e$$

Strömtäthet och resistans för rak ledare

$$\mathbf{J} = \frac{i}{A} \mathbf{e}_x \quad R = \rho \frac{\ell}{A}$$

Plattkondensator

$$C = \epsilon_r \epsilon_0 \frac{A}{d}$$

RCL-beräkningar

Kretsparametrarna i fältuttryck:

| R | C | L |
|---|---|---|
| $R = \frac{v_a - v_b}{i}$ | $C = \frac{q}{v_a - v_b}$ | $L = \frac{\phi}{i}$ |
| $\int_S \mathbf{J} \cdot \mathbf{e}_n \, dS = i$ | $\oint_S \mathbf{D} \cdot \mathbf{e}_n \, dS = q$ | $\int_S \mathbf{B} \cdot \mathbf{e}_n \, dS = \phi$ |
| $\int_{P_a}^{P_b} \mathbf{E} \cdot d\mathbf{r} = v_a - v_b$ | $\int_{P_a}^{P_b} \mathbf{E} \cdot d\mathbf{r} = v_a - v_b$ | $\oint_C \mathbf{H} \cdot d\mathbf{r} = i$ |
| $\mathbf{J} = \sigma \mathbf{E}$ | $\mathbf{D} = \varepsilon_0 \varepsilon_r \mathbf{E}$ | $\mathbf{B} = \mu_0 \mu_r \mathbf{H}$ |

Fälten uppfyller följande villkor:

$$\begin{aligned} \nabla \times \mathbf{E} = 0 & \Leftrightarrow \mathbf{E} = -\nabla V & \Leftrightarrow \oint_C \mathbf{E} \cdot d\mathbf{r} = 0 \\ \nabla \cdot \mathbf{J} = 0 & \Leftrightarrow & \oint_S \mathbf{J} \cdot \mathbf{e}_n \, dS = 0 \\ \nabla \cdot \mathbf{B} = 0 & \Leftrightarrow & \oint_S \mathbf{B} \cdot \mathbf{e}_n \, dS = 0 \end{aligned}$$

Kretsparametrarna i effekt- och energiuttryck:

| | R | C | L |
|-------|--|--|--|
| Krets | $p = Ri^2 = v^2/R$ | $w_e = \frac{1}{2}Cv^2 = \frac{1}{2}q^2/C$ | $w_m = \frac{1}{2}Li^2 = \frac{1}{2}\phi^2/L$ |
| Fält | $p = \int \mathbf{E} \cdot \mathbf{J} \, dV$ | $w_e = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} \, dV$ | $w_m = \frac{1}{2} \int \mathbf{B} \cdot \mathbf{H} \, dV$ |

Transmissionsledningsgeometrier:

| Parameter | Koaxial | Tvåtråds | Platta |
|-----------------------------|--|---|---|
| $R' \, [\Omega/\text{m}]$ | $\frac{1}{2\pi\delta\sigma_c} \left[\frac{1}{a} + \frac{1}{b} \right]$ ($\delta \ll a, t$) | $\frac{1}{\pi a \delta \sigma_c}$ ($\delta \ll a$) | $\frac{2}{w \delta \sigma_c}$ ($\delta \ll t$) |
| $L' \, [\text{H}/\text{m}]$ | $\frac{\mu}{2\pi} \ln \frac{b}{a}$ | $\frac{\mu}{\pi} \cosh^{-1} \frac{d}{2a}$ | $\frac{\mu d}{w}$ |
| $G' \, [\text{S}/\text{m}]$ | $\frac{2\pi\sigma}{\ln \frac{b}{a}}$ | $\frac{\pi\sigma}{\cosh^{-1} \frac{d}{2a}}$ | $\frac{\sigma w}{d}$ |
| $C' \, [\text{F}/\text{m}]$ | $\frac{2\pi\varepsilon}{\ln \frac{b}{a}}$ | $\frac{\pi\varepsilon}{\cosh^{-1} \frac{d}{2a}}$ | $\frac{\varepsilon w}{d}$ ($w \gg d$) |

Transmissionsledning

Ledningsekvationerna, förlustfri dubbelledning

$$\begin{aligned} -\frac{\partial v}{\partial z} &= L \frac{\partial i}{\partial t} \\ -\frac{\partial i}{\partial z} &= C \frac{\partial v}{\partial t} \end{aligned}$$

Allmän lösning, förlustfri dubbelledning

$$\begin{aligned} v &= v^+(z - v_p t) + v^-(z + v_p t) \\ i &= \frac{1}{Z_0} v^+(z - v_p t) - \frac{1}{Z_0} v^-(z + v_p t) \end{aligned}$$

$$v_p = \frac{1}{\sqrt{LC}} \quad Z_0 = \sqrt{\frac{L}{C}} \quad LC = \mu_r \mu_0 \varepsilon_r \varepsilon_0$$

Ledningsekvationerna, sinusformigt tidsberoende

$$\begin{aligned} -\frac{dV}{dz} &= RI + j\omega LI \\ -\frac{dI}{dz} &= GV + j\omega CV \end{aligned}$$

Allmän lösning, sinusformigt tidsberoende

$$\begin{aligned} V(z) &= V_1 e^{-\gamma z} + V_2 e^{\gamma z} \\ I(z) &= \frac{1}{Z_0} (V_1 e^{-\gamma z} - V_2 e^{\gamma z}) \end{aligned}$$

Utbredningskonstant

$$\gamma = \sqrt{(R + j\omega L)(G + j\omega C)} = \alpha + j\beta$$

Karakteristisk impedans

$$Z_0 = \sqrt{\frac{R + j\omega L}{G + j\omega C}}$$

Impedansen för en dubbelledning med längden l avslutad med Z_L

$$Z_{\text{in}} = Z_0 \frac{Z_L \cosh(\gamma l) + Z_0 \sinh(\gamma l)}{Z_0 \cosh(\gamma l) + Z_L \sinh(\gamma l)} = Z_0 \frac{1 + \Gamma e^{-2\gamma l}}{1 - \Gamma e^{-2\gamma l}}$$

Impedansen för en förlustfri ledning med längden l avslutad med Z_L

$$Z_{\text{in}} = Z_0 \frac{Z_L \cos(\beta l) + jZ_0 \sin(\beta l)}{Z_0 \cos(\beta l) + jZ_L \sin(\beta l)} = Z_0 \frac{1 + \Gamma e^{-j2\beta l}}{1 - \Gamma e^{-j2\beta l}}$$

Reflektionsfaktorn för spänning vid belastningen

$$\Gamma = \frac{Z_L - Z_0}{Z_L + Z_0}$$

Matematiska formler och samband

Trigonometriska formler

$$\sin \alpha = \cos(\alpha - \pi/2)$$

$$\cos \alpha = \sin(\alpha + \pi/2)$$

$$\cos^2 \alpha + \sin^2 \alpha = 1$$

$$\cos^2 \alpha - \sin^2 \alpha = \cos 2\alpha$$

$$2 \sin \alpha \cos \alpha = \sin 2\alpha$$

$$\sin(\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$2 \sin \alpha \sin \beta = \cos(\alpha - \beta) - \cos(\alpha + \beta)$$

$$2 \sin \alpha \cos \beta = \sin(\alpha + \beta) + \sin(\alpha - \beta)$$

$$2 \cos \alpha \cos \beta = \cos(\alpha + \beta) + \cos(\alpha - \beta)$$

$$A \cos \alpha + B \sin \alpha = \sqrt{A^2 + B^2} \cos(\alpha - \beta) \text{ där } \cos \beta = \frac{A}{\sqrt{A^2 + B^2}}, \sin \beta = \frac{B}{\sqrt{A^2 + B^2}}$$

$$\cos \alpha = \frac{e^{j\alpha} + e^{-j\alpha}}{2}$$

$$\sin \alpha = \frac{e^{j\alpha} - e^{-j\alpha}}{2j}$$

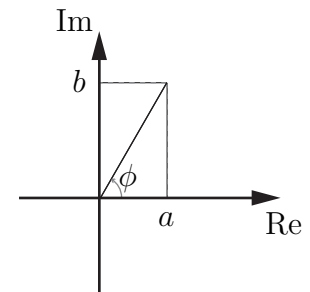
$$e^{j\alpha} = \cos \alpha + j \sin \alpha$$

Komplexa tal

$$z = a + jb = |z|e^{j\phi}$$

där

$$|z| = \sqrt{a^2 + b^2} \text{ och om } a > 0 \text{ är } \phi = \arctan \frac{b}{a}$$



Ekvationssystem (2×2)

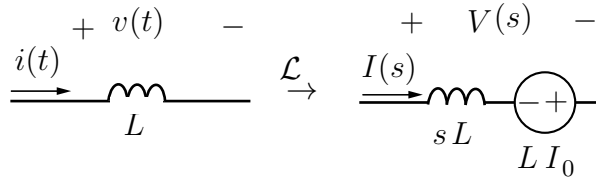
$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix}$$

med lösning

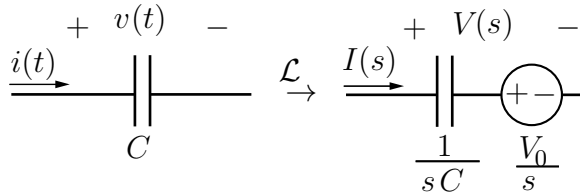
$$\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix}$$

Laplacetransformen

Spole med $i(0^-) = I_0$:
 $V(s) = L(sI(s) - I_0)$



Kondensator med $v(0^-) = V_0$:
 $I(s) = C(sV(s) - V_0)$



| | $f(t)$ | $F(s)$ |
|----|------------------------------------|---|
| 1. | $\alpha f(t)$ | $\alpha F(s)$ |
| 2. | $f_1(t) + f_2(t) + f_3(t) + \dots$ | $F_1(s) + F_2(s) + F_3(s) + \dots$ |
| 3. | $\frac{df(t)}{dt}$ | $sF(s) - f(0^-)$ |
| 4. | $\int_0^t f(\tau) d\tau$ | $\frac{F(s)}{s}$ |
| 5. | $f(t - a) u(t - a), \quad a > 0$ | $e^{-as} F(s)$ |
| 6. | $e^{-at} f(t)$ | $F(s + a)$ |
| 7. | $f(at), \quad a > 0$ | $\frac{1}{a} F\left(\frac{s}{a}\right)$ |

Begynnelsevärdessatsen $\lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} sF(s)$

Slutvärdessatsen $\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$

| | $f(t)$ | $F(s)$ |
|-----|---|--|
| 1. | $\delta(t)$ | 1 |
| 2. | $\frac{d^n}{dt^n} \delta(t)$ | s^n |
| 3. | $u(t)$, enhetssteget | $\frac{1}{s}$ |
| 4. | $\frac{t^n}{n!} u(t)$ | $\frac{1}{s^{n+1}}$ |
| 5. | $e^{-at} u(t)$ | $\frac{1}{s+a}$ |
| 6. | $\frac{t^n}{n!} e^{-at} u(t)$ | $\frac{1}{(s+a)^{n+1}}$ |
| 7. | $\frac{e^{-at} - e^{-bt}}{b-a} u(t)$ | $\frac{1}{(s+a)(s+b)}$ |
| 8. | $\frac{ae^{-at} - be^{-bt}}{a-b} u(t)$ | $\frac{s}{(s+a)(s+b)}$ |
| 9. | $\sin(\omega_0 t) u(t)$ | $\frac{\omega_0}{s^2 + \omega_0^2}$ |
| 10. | $\cos(\omega_0 t) u(t)$ | $\frac{s}{s^2 + \omega_0^2}$ |
| 11. | $(\sin(\omega_0 t) - \omega_0 t \cos(\omega_0 t)) u(t)$ | $\frac{2\omega_0^3}{(s^2 + \omega_0^2)^2}$ |
| 12. | $\omega_0 t \sin(\omega_0 t) u(t)$ | $\frac{2\omega_0^2 s}{(s^2 + \omega_0^2)^2}$ |
| 13. | $e^{-at} \sin(\omega_0 t) u(t)$ | $\frac{\omega_0}{(s+a)^2 + \omega_0^2}$ |
| 14. | $e^{-at} \cos(\omega_0 t) u(t)$ | $\frac{s+a}{(s+a)^2 + \omega_0^2}$ |

Koordinatsystem

Kartesiska koordinater (x, y, z)

Ortsvektor $\mathbf{r} = x \mathbf{e}_x + y \mathbf{e}_y + z \mathbf{e}_z$

Linjeelement $d\mathbf{l} = dx \mathbf{e}_x + dy \mathbf{e}_y + dz \mathbf{e}_z$

Volymelement $dv = dx dy dz$

Differentialoperatorer

$$\nabla V = \mathbf{e}_x \frac{\partial V}{\partial x} + \mathbf{e}_y \frac{\partial V}{\partial y} + \mathbf{e}_z \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \mathbf{A} = \mathbf{e}_x \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \mathbf{e}_y \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \mathbf{e}_z \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right)$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$$

Cylinderkoordinater (r_c, φ, z)

Ortsvektor $\mathbf{r} = r_c \mathbf{e}_{r_c} + z \mathbf{e}_z$

Enhetsvektorer $\mathbf{e}_{r_c} = \cos \varphi \mathbf{e}_x + \sin \varphi \mathbf{e}_y$

$$\mathbf{e}_\varphi = -\sin \varphi \mathbf{e}_x + \cos \varphi \mathbf{e}_y$$

Linjeelement $d\mathbf{l} = dr_c \mathbf{e}_{r_c} + r_c d\varphi \mathbf{e}_\varphi + dz \mathbf{e}_z$

Volymelement $dv = r_c dr_c d\varphi dz$

Differentialoperatorer

$$\nabla V = \mathbf{e}_{r_c} \frac{\partial V}{\partial r_c} + \mathbf{e}_\varphi \frac{1}{r_c} \frac{\partial V}{\partial \varphi} + \mathbf{e}_z \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{r_c} \frac{\partial}{\partial r_c} (r_c A_{r_c}) + \frac{1}{r_c} \frac{\partial A_\varphi}{\partial \varphi} + \frac{\partial A_z}{\partial z}$$

$$\begin{aligned} \nabla \times \mathbf{A} = & \mathbf{e}_{r_c} \left(\frac{1}{r_c} \frac{\partial A_z}{\partial \varphi} - \frac{\partial A_\varphi}{\partial z} \right) + \mathbf{e}_\varphi \left(\frac{\partial A_{r_c}}{\partial z} - \frac{\partial A_z}{\partial r_c} \right) \\ & + \mathbf{e}_z \frac{1}{r_c} \left[\frac{\partial}{\partial r_c} (r_c A_\varphi) - \frac{\partial A_{r_c}}{\partial \varphi} \right] \end{aligned}$$

$$\nabla^2 V = \frac{1}{r_c} \frac{\partial}{\partial r_c} \left(r_c \frac{\partial V}{\partial r_c} \right) + \frac{1}{r_c^2} \frac{\partial^2 V}{\partial \varphi^2} + \frac{\partial^2 V}{\partial z^2}$$

Sfäriska koordinater (r, θ, φ)

Ortsvektor $\mathbf{r} = r \mathbf{e}_r$

Enhetsvektorer $\mathbf{e}_r = \sin \theta \cos \varphi \mathbf{e}_x + \sin \theta \sin \varphi \mathbf{e}_y + \cos \theta \mathbf{e}_z$

$\mathbf{e}_\theta = \cos \theta \cos \varphi \mathbf{e}_x + \cos \theta \sin \varphi \mathbf{e}_y - \sin \theta \mathbf{e}_z$

$\mathbf{e}_\varphi = -\sin \varphi \mathbf{e}_x + \cos \varphi \mathbf{e}_y$

Linjeelement $d\mathbf{l} = dr \mathbf{e}_r + r d\theta \mathbf{e}_\theta + r \sin \theta d\varphi \mathbf{e}_\varphi$

Volymelement $dv = r^2 \sin \theta dr d\theta d\varphi$

Differentialoperatorer

$$\nabla V = \mathbf{e}_r \frac{\partial V}{\partial r} + \mathbf{e}_\theta \frac{1}{r} \frac{\partial V}{\partial \theta} + \mathbf{e}_\varphi \frac{1}{r \sin \theta} \frac{\partial V}{\partial \varphi}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial A_\varphi}{\partial \varphi}$$

$$\begin{aligned} \nabla \times \mathbf{A} &= \mathbf{e}_r \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (A_\varphi \sin \theta) - \frac{\partial A_\theta}{\partial \varphi} \right] \\ &\quad + \mathbf{e}_\theta \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial A_r}{\partial \varphi} - \frac{\partial}{\partial r} (r A_\varphi) \right] + \mathbf{e}_\varphi \frac{1}{r} \left[\frac{\partial}{\partial r} (r A_\theta) - \frac{\partial A_r}{\partial \theta} \right] \end{aligned}$$

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \varphi^2}$$