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What have we covered thus far?

- ❑ **Recap:** Considered the effect of multipath propagation on the received amplitude and phase, as well as its temporal variations.
- ❑ **Key assumption:** Small system bandwidth (narrowband systems only). As a consequence, multiple directions can not be **resolved** by the RX and seem that they arrive almost at the same time.
- ❑ **Most current and future systems however will leverage large bandwidths.**
- ❑ Desirable to describe channel variations over a larger bandwidth range – the topic for the current lecture.
 - ❑ **Wideband characterization** of channels and real world examples.

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Propagation Impact on Wideband Systems

Impact interpreted in **two** different ways:

- ❑ The transfer function of the channel **varies** over the **bandwidth** of interest (a.k.a. the **frequency selectivity** of the channel).
- ❑ Impulse response of the channel is **not** a Delta function; the arriving signal has a **longer run time** than the transmitted signal (a.k.a. delay dispersion).

Question: What is the relationship between the above?

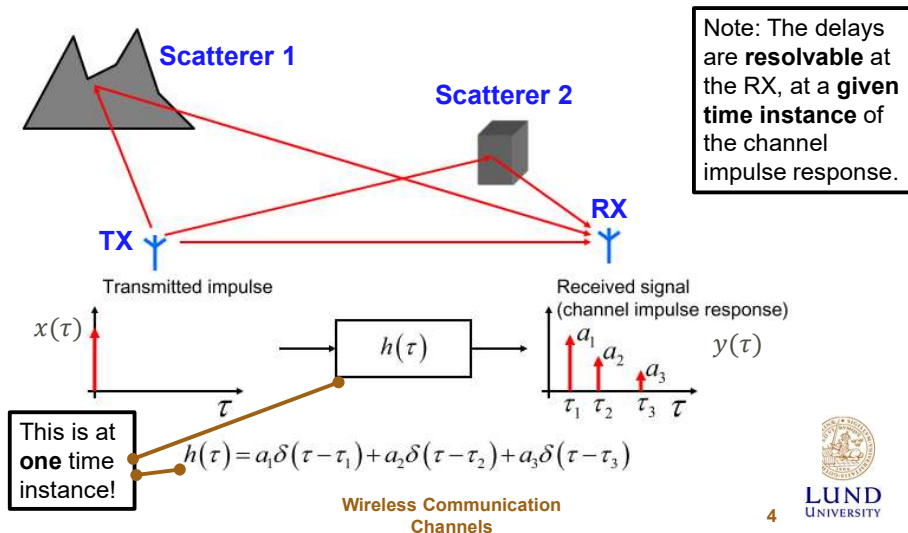
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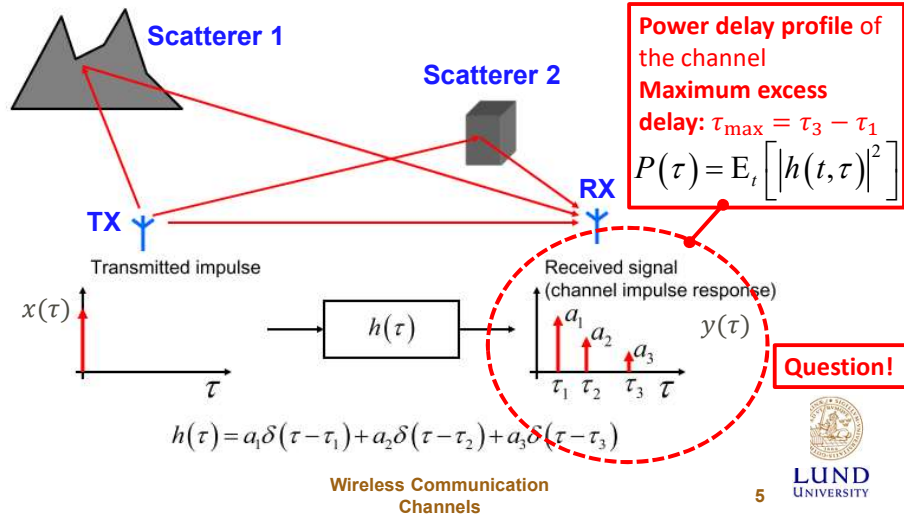
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Delay Dispersion: A Simple Case



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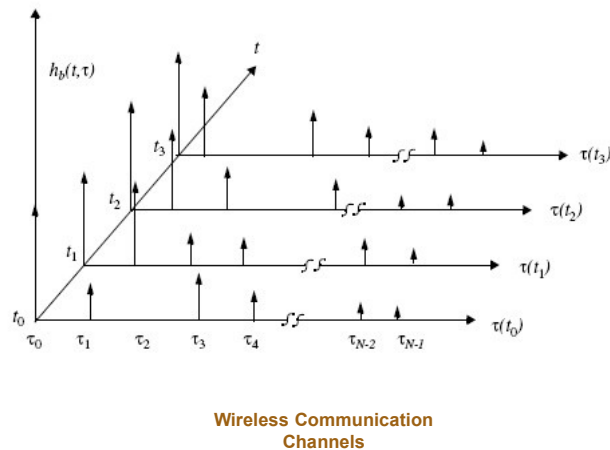
Delay Dispersion: A Simple Case



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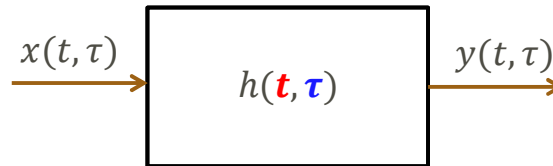
Power delay profile over time

The General Description



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Consequence of Wideband Channels



So, what about this?
What can we infer from a system view point?

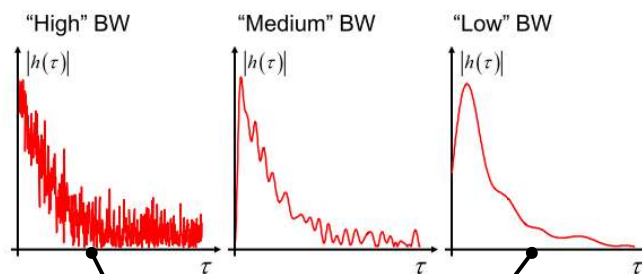
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Narrowband vs. Wideband Channels Bandwidth Dependency



Much better resolvability
of multipath components

Narrowband if $\frac{1}{B} \gg \tau_{\max}$

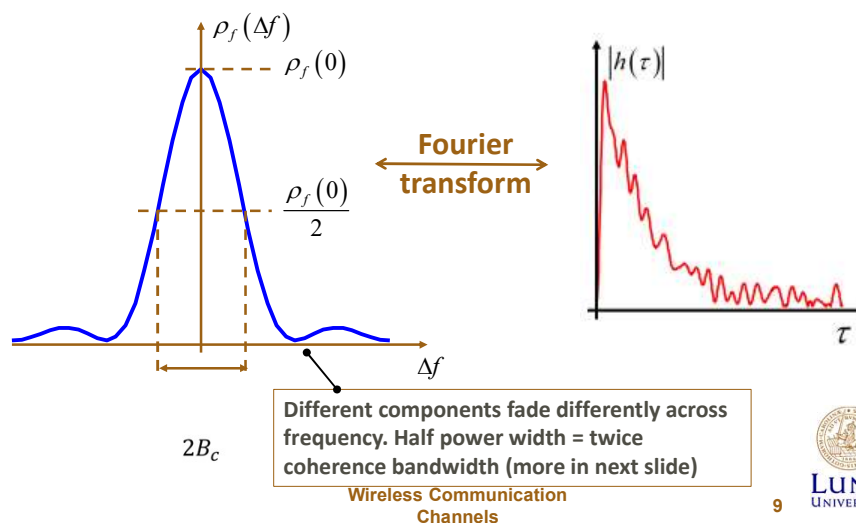
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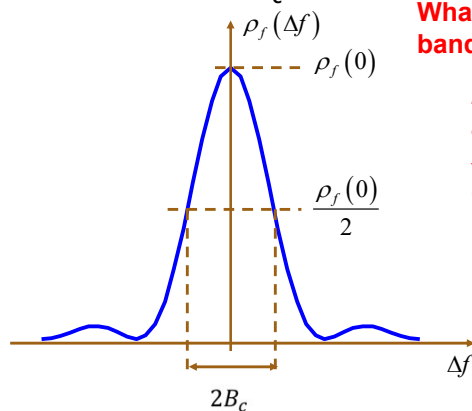
Power delay profile vs. frequency correlation function



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Condensed parameters Coherence bandwidth

Given the frequency correlation of a channel, we can define the coherence bandwidth B_c :



What does the coherence bandwidth tell us?

It shows us over how large a bandwidth we can assume so that the channel is fairly constant.

Radio systems using a bandwidth much smaller than B_c will not notice the frequency selectivity of the channel.

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Condensed parameters Power delay profile (cont.)

We can infer many useful parameters from the power delay profile

Total power (time integrated):

$$P_m = \int_{-\infty}^{\infty} P(\tau) d\tau$$

Average mean delay (first moment of the PDP)

$$T_m = \frac{\int_{-\infty}^{\infty} \tau P(\tau) d\tau}{P_m}$$

Average RMS delay spread (second moment of the PDP)

$$S_\tau = \sqrt{\frac{\int_{-\infty}^{\infty} \tau^2 P(\tau) d\tau}{P_m} - T_m^2}$$

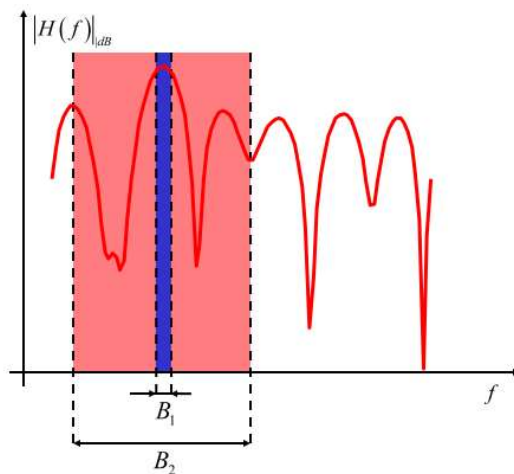
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Narrow vs. wideband frequency response



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Widely used "rules-of-thumb"

$$T_c \approx \frac{1}{D_s}$$

$$B_c \approx \frac{1}{S_\tau}$$

$$T_c = \frac{9}{16\pi D_s}$$

time over which the time correlation function is above 0.5

$$B_c = \frac{1}{5S_\tau}$$

band over which the frequency correlation function is above 0.5

$$T_c = \frac{0.423}{D_s}$$

less restrictive and widely used

$$B_c = \frac{1}{50S_\tau}$$

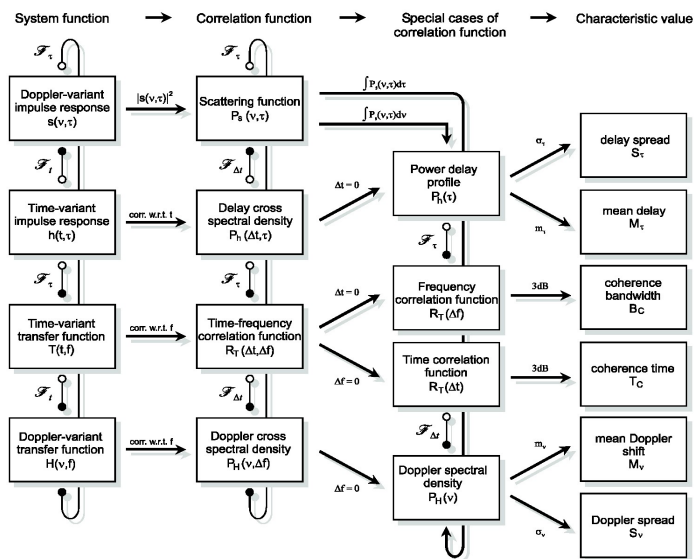
band over which the frequency correlation function is above 0.9

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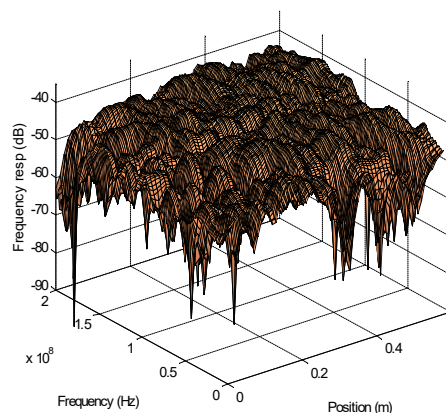
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Time variant channel transfer function



Measurement in the lab with a vector network analyzer

- Center frequency 3.2 GHz
- Measurement bandwidth 200 MHz, 201 frequency points
- 60 measurement positions, spaced 1 cm apart

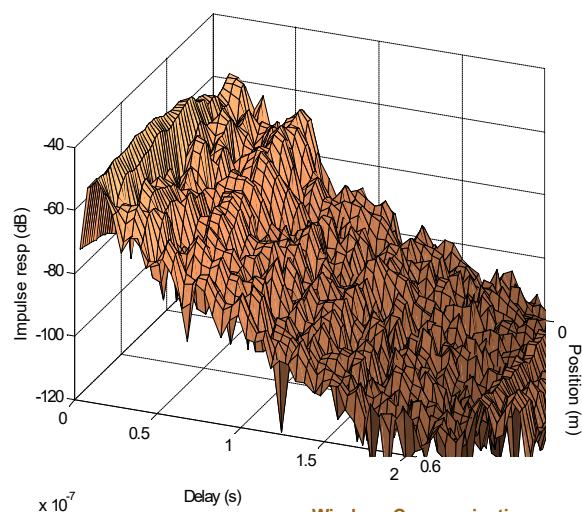
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Time variant channel impulse response



What are the delays?

How is the signal affected for different delays?

How does it change with time?

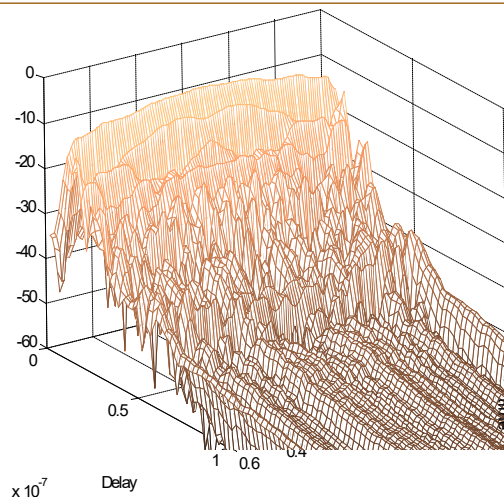
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Delay cross spectral density



How is the power for different delays correlated in time?

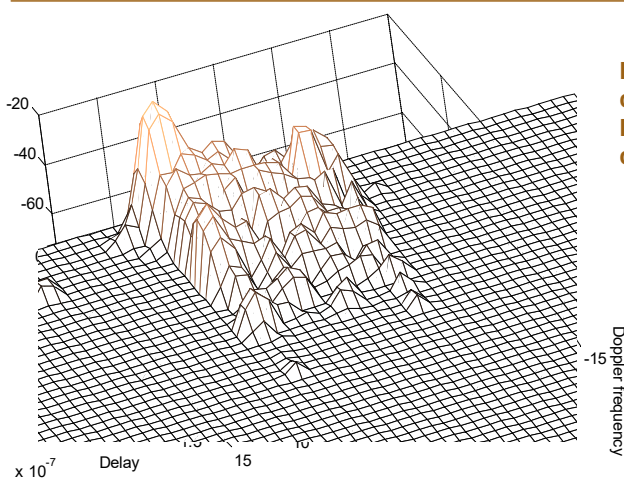
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Spreading function of the channel



How is the power distributed in the Doppler and delay domains?

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Measurements in an industrial UWB channel

4.9 GHz bandwidth
49 TX-RX positions 49
7*7 Virtual MIMO system
Antenna array elements
separation 5cm
TX-RX Separations 3,6,10,12m

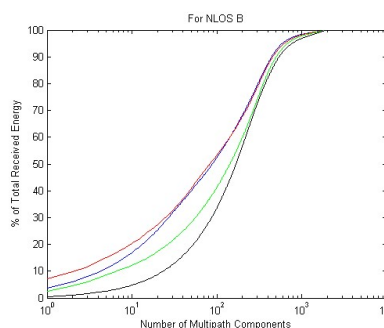
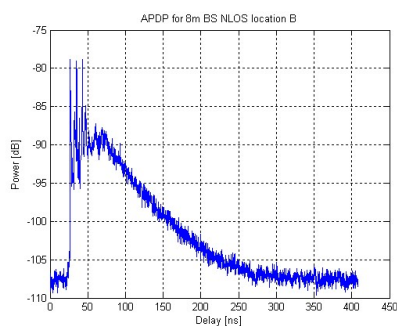


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UWB channels – PDP



Huge bandwidth – possible to identify single multipath components
Need a large number of fingers in a special type of receiver (so called RAKE receiver)

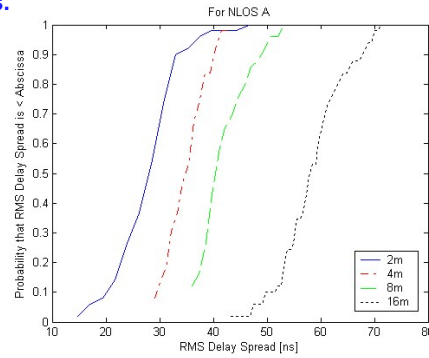
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UWB channels

Delay spread is mainly dependent on distance to the scatterers, since it influences the resolvability of the system to identify potential multipath components.



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