



LUND
UNIVERSITY

Wireless Communications Channels

Lecture 3: Fading

EITN85: Harsh Tataria (e-mail: harsh.tataria@eit.lth.se)
Department of Electrical and Information Technology, Lund University



1

Fading – Statistical description of the wireless channel

- Why statistical description
- Large scale fading
- Small scale fading:
 - without dominant component
 - with dominant component
- Statistical models

2

Why “statistical” description?

- ❑ Complex, unknown environment
- ❑ Can not describe everything in detail
 - ❑ Maxwell’s equations far too complex in real scenarios
- ❑ Large variations depending on the TX, RX and interacting object locations
- ❑ Need a statistical measure since we can not describe every point everywhere

“There is a x% probability that the amplitude/power will be above the level y”

3

The WSSUS model: Assumptions

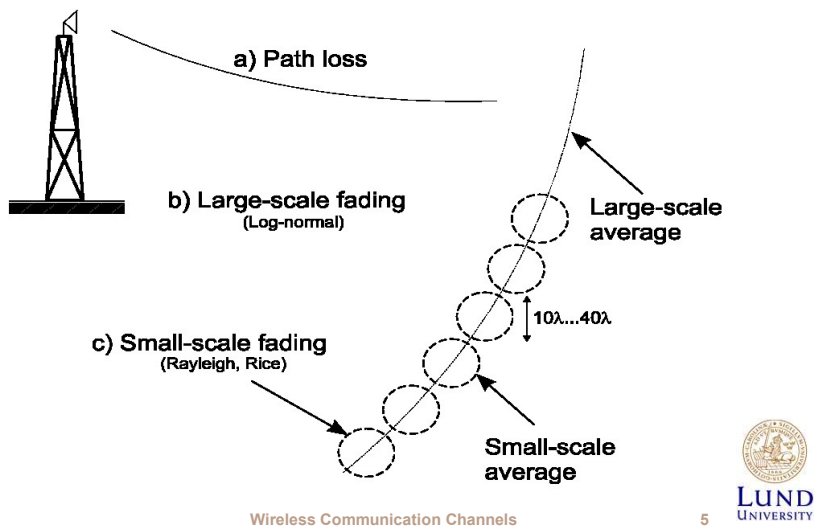
A very common channel model is the WSSUS-model: **Statistical properties remain the same over the considered time (or area)**

Recall: the channel is composed of a number of different contributions (incoming waves), the following is assumed:

- ❑ The channel is **Wide-Sense Stationary (WSS)**, meaning that the **correlation** of the channel is **invariant** over time.
- ❑ The channel is built up by **Uncorrelated Scatterers (US)**, meaning that the **frequency** correlation of the channels is **invariant** over frequency. (Contributions with different delays are uncorrelated.)

4

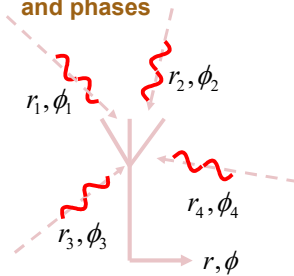
What is large scale and small scale?



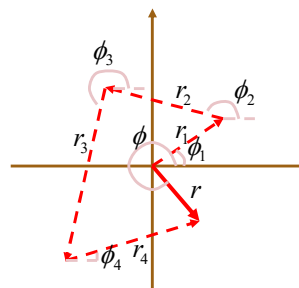
5

Small-scale fading Many incoming waves

Many incoming waves with independent amplitudes and phases



Add them up as phasors



$$r \exp(j\phi) = r_1 \exp(j\phi_1) + r_2 \exp(j\phi_2) + r_3 \exp(j\phi_3) + r_4 \exp(j\phi_4)$$

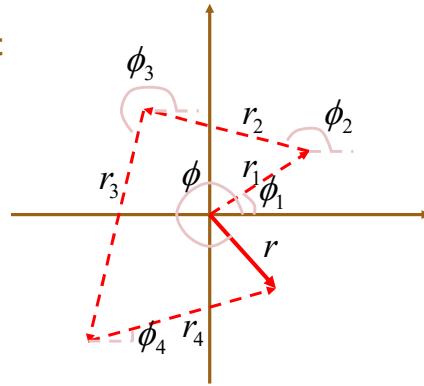
6

Small-scale fading Many incoming waves

Re and Im components are sums of many independent equally distributed components

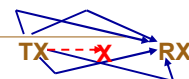
$$\text{Re}(r) \in N(0, \sigma^2)$$

Re(r) and Im(r) are independent

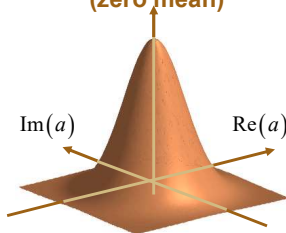


Small-scale fading Rayleigh fading

No dominant component
(non line-of-sight)

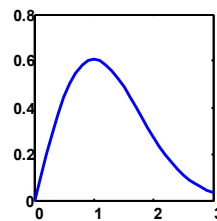


Tap distribution
2D Gaussian
(zero mean)



No line-of-sight component

Amplitude distribution
Rayleigh

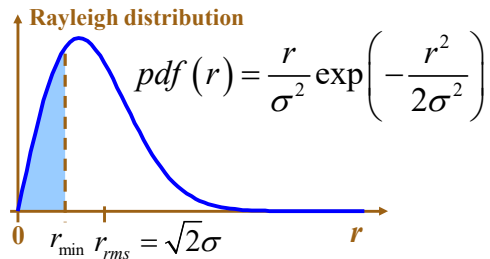


$$pdf(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right)$$



Small-scale fading

Rayleigh fading



Probability that the amplitude is below some threshold r_{\min} :

$$\Pr(r < r_{\min}) = \int_0^{r_{\min}} pdf(r) dr = 1 - \exp\left(-\frac{r_{\min}^2}{r_{rms}^2}\right)$$



Small-scale fading

Rayleigh fading – outage probability

- What is the probability that we will receive an amplitude 20 dB below the r_{rms} ?

$$\Pr(r < r_{\min}) = 1 - \exp\left(-\frac{r_{\min}^2}{r_{rms}^2}\right) = 1 - \exp(-0.01) \approx 0.01$$

- What is the probability that we will receive an amplitude below r_{rms} ?

$$\Pr(r < r_{\min}) = 1 - \exp\left(-\frac{r_{\min}^2}{r_{rms}^2}\right) = 1 - \exp(-1) \approx 0.63$$



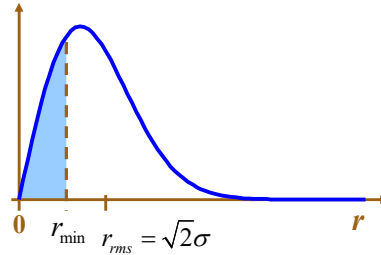
Small-scale fading

Rayleigh fading – fading margin

To ensure that in most cases we **receive** enough power, we transmit **extra** power by including the so-called “fading margin”

$$M = \frac{r_{rms}^2}{r_{min}^2}$$

$$M_{dB} = 10 \log_{10} \left(\frac{r_{rms}^2}{r_{min}^2} \right)$$



11

Small-scale fading

Rayleigh fading – fading margin

How many dB fading margin, against Rayleigh fading, do we need to obtain an outage probability of 1%?

$$\Pr(r < r_{min}) = 1 - \exp\left(-\frac{r_{min}^2}{r_{rms}^2}\right) = 1\% = 0.01$$

Some manipulation gives

$$1 - 0.01 = \exp\left(-\frac{r_{min}^2}{r_{rms}^2}\right) \Rightarrow \ln(0.99) = -\frac{r_{min}^2}{r_{rms}^2}$$

$$\Rightarrow \frac{r_{min}^2}{r_{rms}^2} = -\ln(0.99) = 0.01 \Rightarrow M = \frac{r_{rms}^2}{r_{min}^2} = 1 / 0.01 = 100$$

$$\Rightarrow M_{dB} = 20$$

12

Small-scale fading

Rayleigh fading – signal and interference

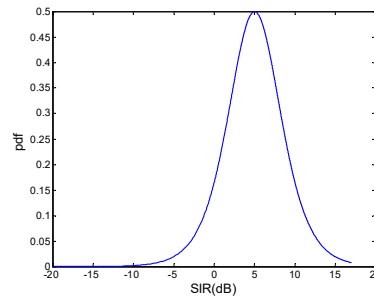
Both the desired signal and the interference undergo fading

For a single user interferer and Rayleigh fading:

$$pdf_{SIR}(r) = \frac{2\bar{\sigma}^2 r}{(\bar{\sigma}^2 + r^2)^2}$$

$$cdf_{SIR}(r) = 1 - \frac{\bar{\sigma}^2}{\bar{\sigma}^2 + r^2}$$

where $\bar{\sigma}^2 = \frac{\sigma_2^2}{\sigma_1^2}$ is the mean signal to interference ratio



pdf for 10 dB mean signal to interference ratio

13

Small-scale fading

Rayleigh fading – signal and interference

What is the probability that the instantaneous SIR will be below 0 dB if the mean SIR is 10 dB when both the desired signal and the interferer experience Rayleigh fading?

$$\Pr(r < r_{\min}) = 1 - \frac{\bar{\sigma}^2 r_{\min}}{\bar{\sigma}^2 + r_{\min}^2} = 1 - \frac{10}{(10+1)} \approx 0.09$$

14

Small-scale fading: One dominating component

In case of Line-of-Sight (LOS) one component dominates.

- Assume it is aligned with the real axis

$$\text{Re}(r) \in N(A, \sigma^2) \quad \text{Im}(r) \in N(0, \sigma^2)$$

- The received amplitude has now a Ricean distribution instead of a Rayleigh
 - The fluctuations are smaller
 - The phase is dominated by the LOS component
 - In real cases the mean propagation loss is often smaller due to the LOS
- The ratio between the power of the LOS component and the diffuse components is called Ricean K-factor

$$k = \frac{\text{Power in LOS component}}{\text{Power in random components}} = \frac{A^2}{2\sigma^2}$$



Small-scale fading Ricean fading

