



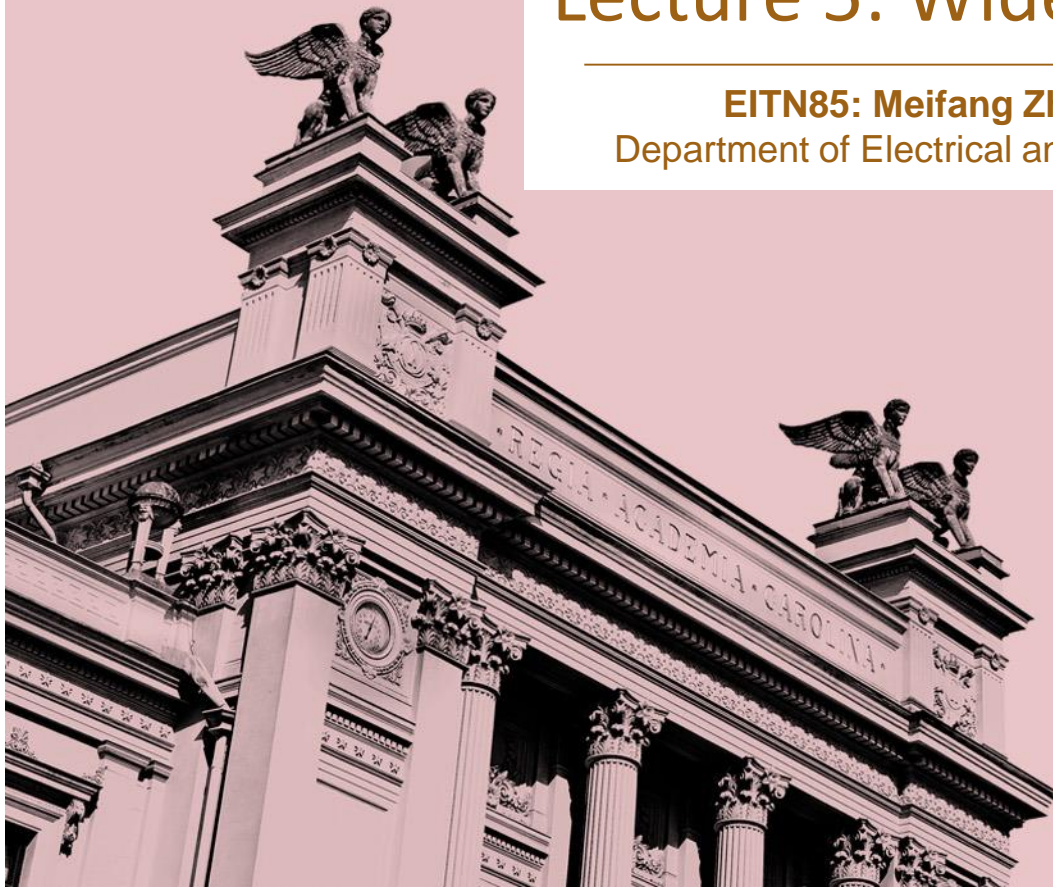
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# Wireless Communications Channels

## Lecture 5: Wideband Characterization

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# Recap: small/large scale fading



Deterministic Pathloss = 127dB



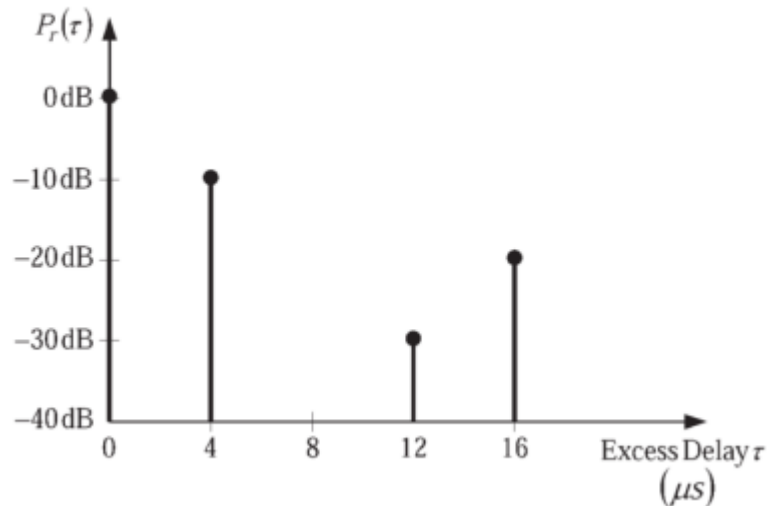
Receiver can handle  
loss maximum to  
135dB

- ☐ Assume only large scale fading, which is log-normal distributed with  $\sigma_F = 7\text{dB}$
- ☐ What is the outage probability of the user?
- ☐ How we can do to lower the outage probability for the user?

$$pdf(L_{dB}) = \frac{1}{\sqrt{2\pi}\sigma_{F|dB}} \exp\left(-\frac{(L_{dB} - L_{0|dB})^2}{2\sigma_{F|dB}^2}\right)$$

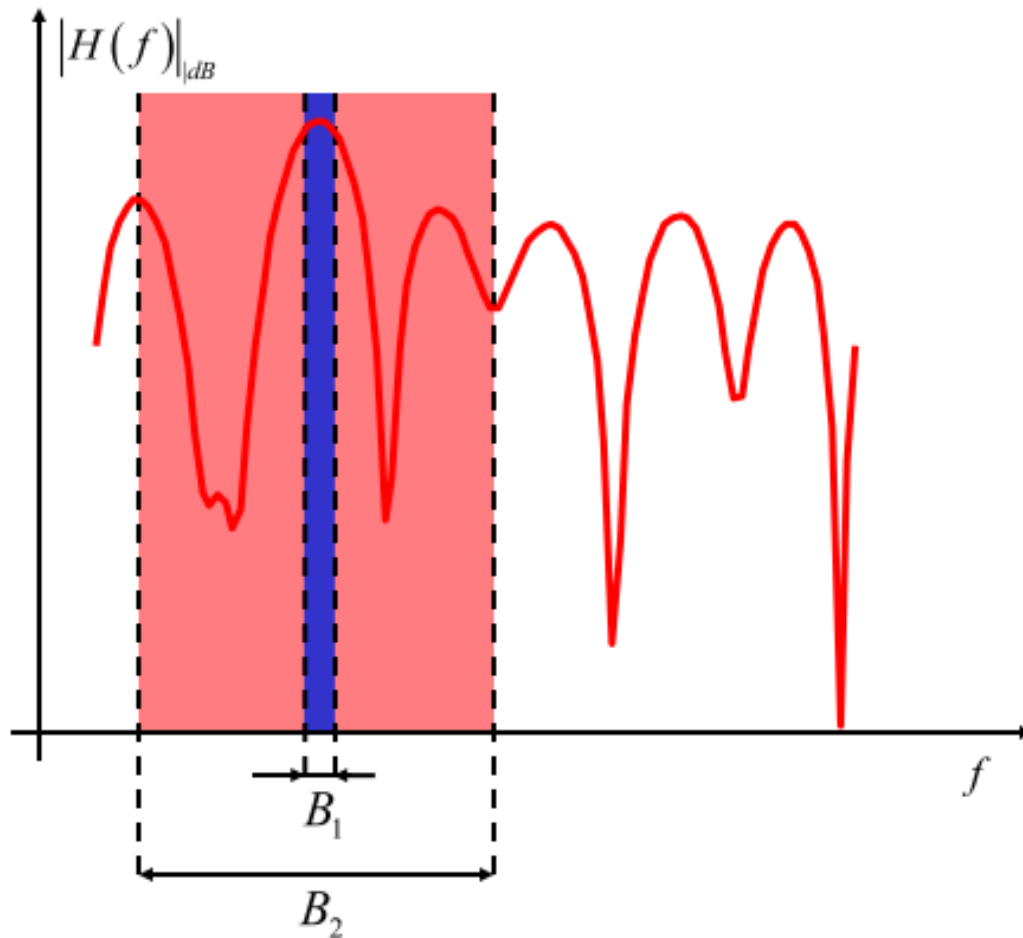
# Recap : power delay profile

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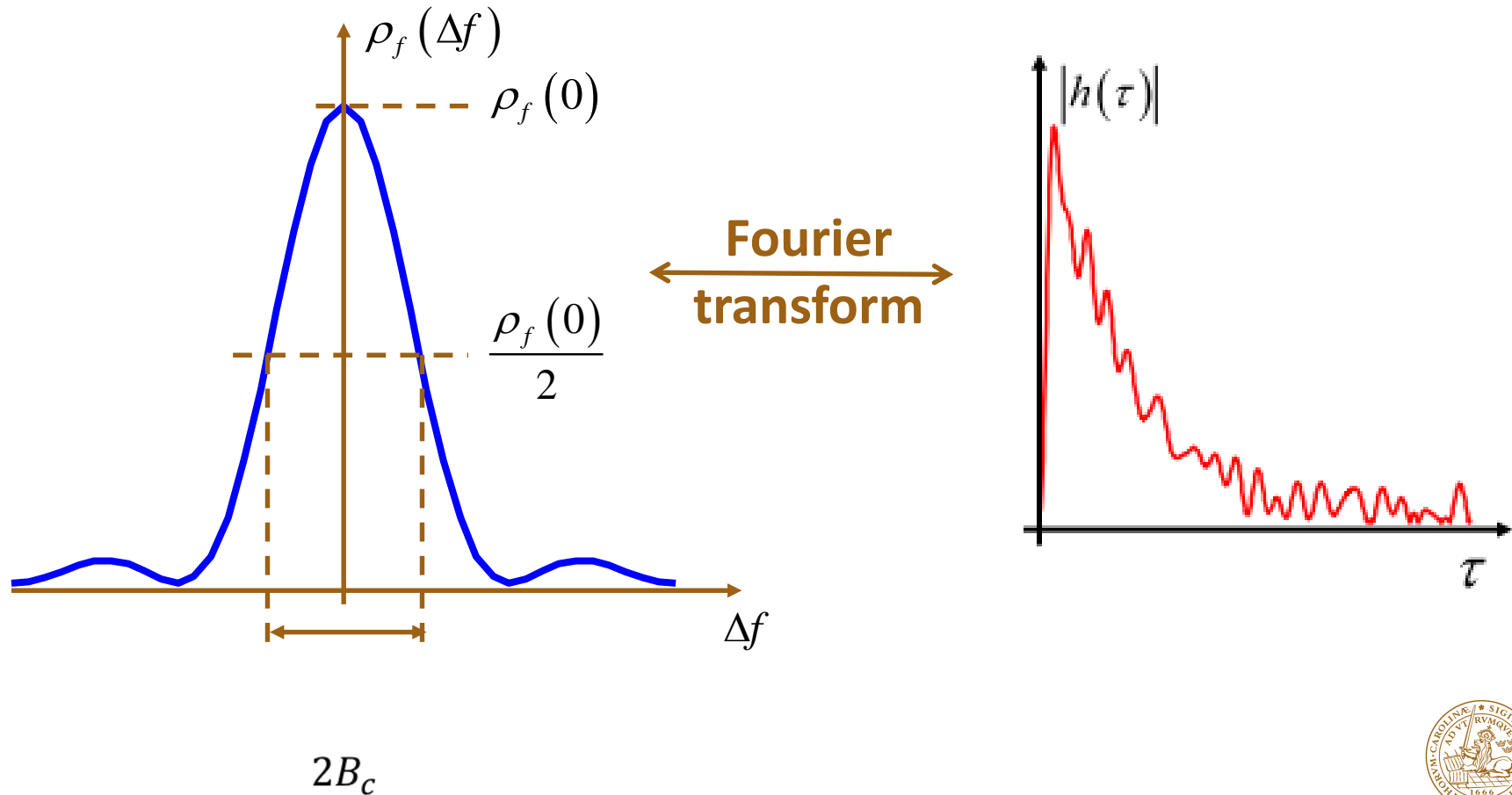


- ☐ What is the maximum access delay?
- ☐ What is the mean delay and rms delay spread?
- ☐ If bandwidth of the system is 5MHz, determine if the channel will undergo frequency flat or frequency selective fading?

# Recap: frequency flat vs frequency selective



# Recap: Power delay profile vs. frequency correlation function



# Mathematical background

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$$H(t, f) = \int_{-\infty}^{\infty} h(t, \tau) e^{-j2\pi f \tau} d\tau$$

Frequency correlation



$$E\{H(t_1, f_1)H^*(t_2, f_2)\} = \iint_{-\infty}^{\infty} h(t_1, \tau_1) e^{-j2\pi f_1 \tau_1} h^*(t_2, \tau_2) e^{-j2\pi f_2 \tau_2} d\tau_1 d\tau_2$$

WSSUS



$$R_H(\Delta f) = \int_{-\infty}^{\infty} \underbrace{E\{|h(\tau)|^2\}}_{\text{PDP}} \underbrace{e^{-j2\pi \Delta f \tau}}_{\text{FFT}} d\tau$$



# Power delay profile in a dynamic environment

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$$P(\tau) = E_t \left[ |h(t, \tau)|^2 \right]$$

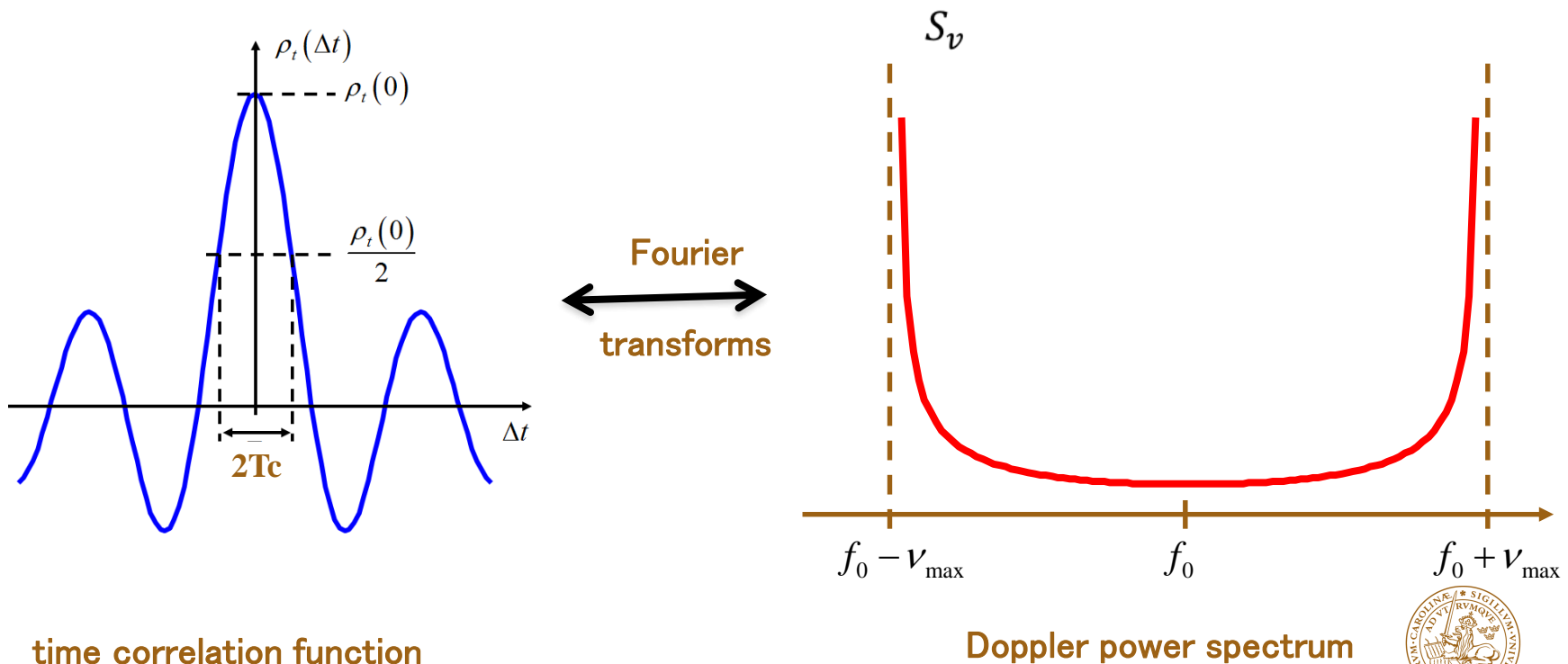
Does WSS still hold in a dynamic environment over time?

- ❑ WSS: the statistical properties of the channel not change with time
- ❑ Requires: mean power and Doppler spectrum do not change with time.
- ❑ Typically holds over an area of 10 wavelengths.



# Doppler spectrum vs. the time correlation function

Doppler spectrum and the time correlation of the signal are related to each other by Fourier transformation





# Condensed parameters

## Coherence time

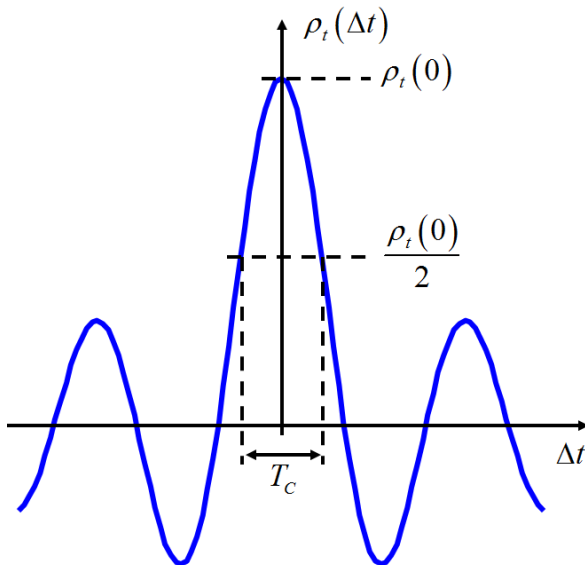
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Given the time correlation of a channel, we can define the coherence time  $T_c$ :

What does the coherence time tell us?

It shows us over how fast a Channel changes

Radio systems update channel status parameters that is smaller than the coherence time



# Condensed parameters

## Doppler spectra

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We can infer many useful parameters from the power delay profile

**Total power (Doppler frequency integrated):**

$$P_{B,m} = \int_{-\infty}^{\infty} P_B(v) dv$$

**Average Doppler shift (first moment of the Doppler spectra)**

$$v_m = \frac{\int_{-\infty}^{\infty} P_B(v) v dv}{P_{B,m}}$$

**Average RMS Doppler spread (second moment of the Doppler spectra)**

$$D_s = \sqrt{\frac{\int_{-\infty}^{\infty} P_B(v) v^2 dv}{P_{B,m}} - v_m^2}$$

# Widely used “rules-of-thumb”

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$$T_c \approx \frac{1}{D_s}$$

$$B_c \approx \frac{1}{S_\tau}$$

$$T_c = \frac{9}{16\pi D_s}$$

time over which the time  
correlation function is above 0.5

$$B_c = \frac{1}{5S_\tau}$$

band over which the frequency  
correlation function is above 0.5

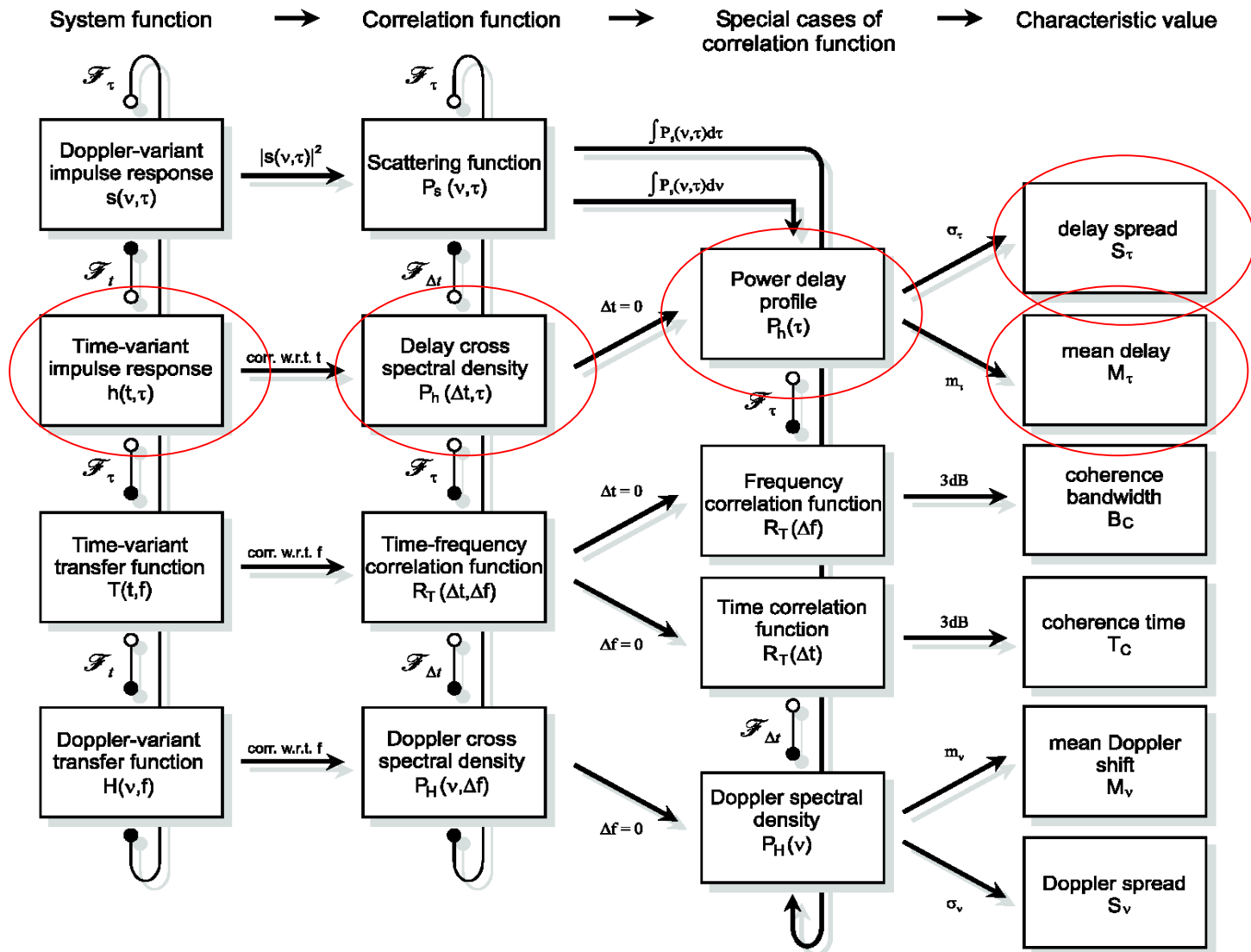
$$T_c = \frac{0.423}{D_s}$$

less restrictive and widely used

$$B_c = \frac{1}{50S_\tau}$$

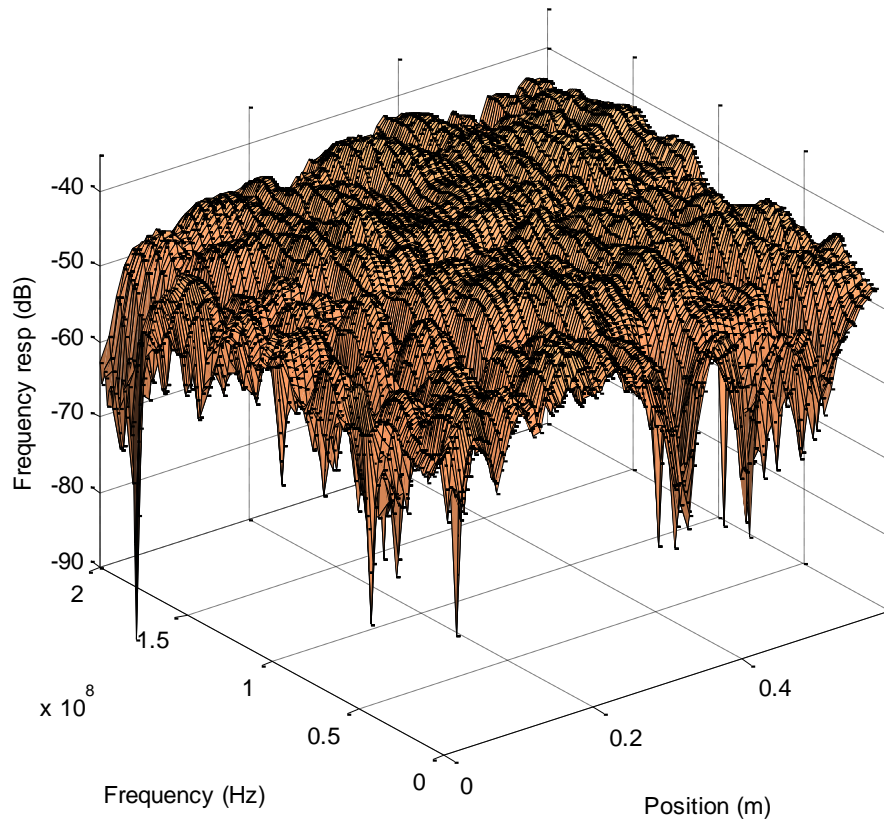
band over which the frequency  
correlation function is above 0.9





# Time variant channel transfer function

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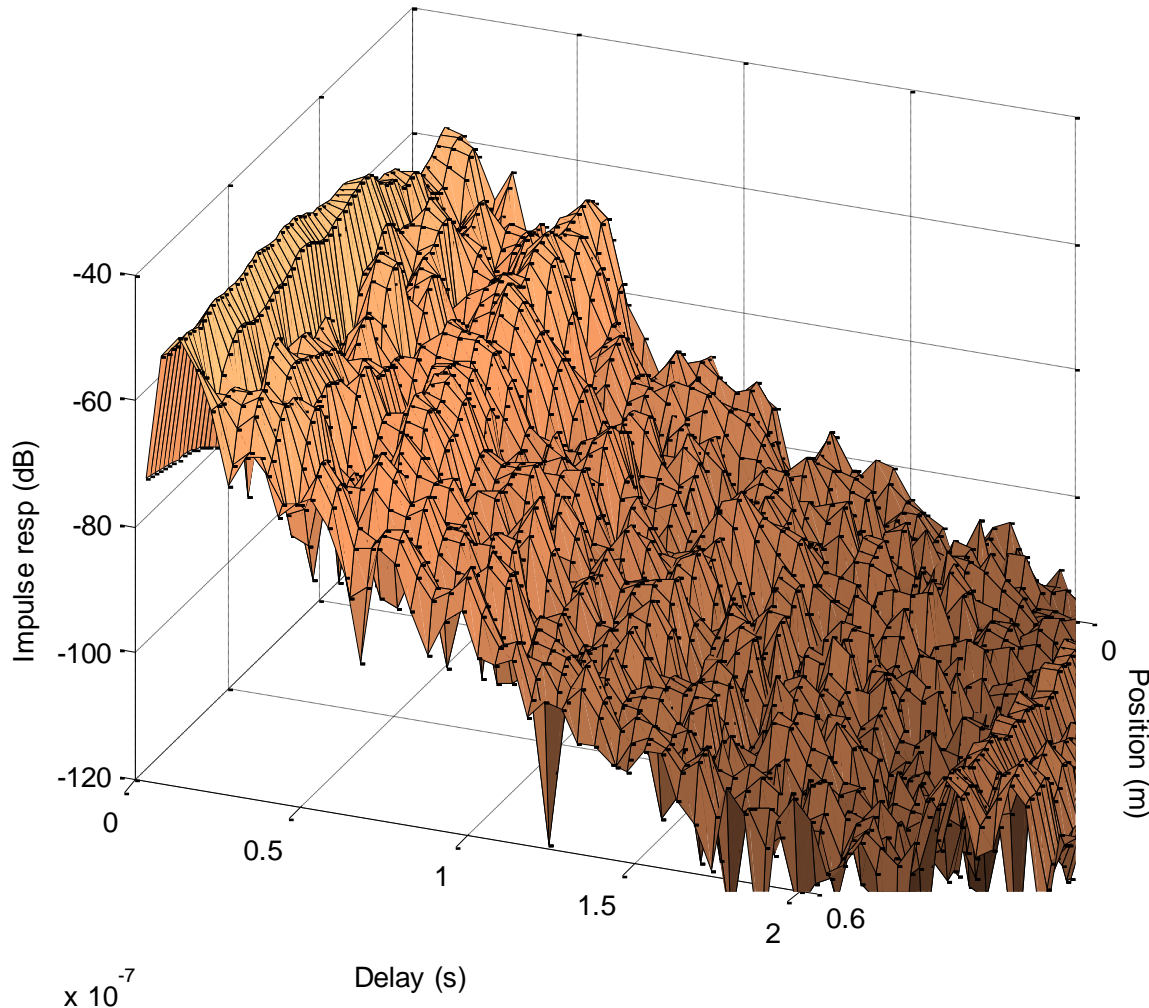


Measurement in the lab with a vector network analyzer

- Center frequency 3.2 GHz
- Measurement bandwidth 200 MHz, 201 frequency points
- 60 measurement positions, spaced 1 cm apart



# Time variant channel impulse response



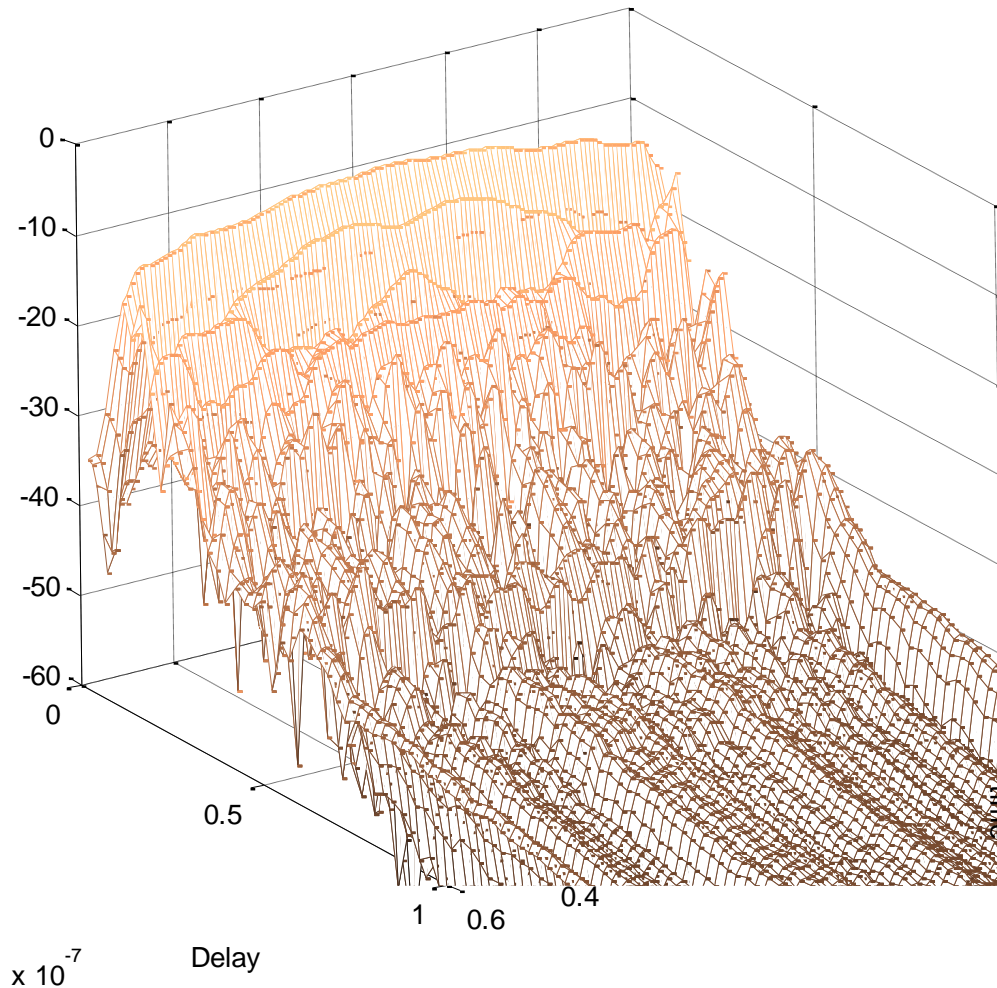
What are the delays?

How is the signal affected for different delays?

How does it change with time?



# Delay cross spectral density



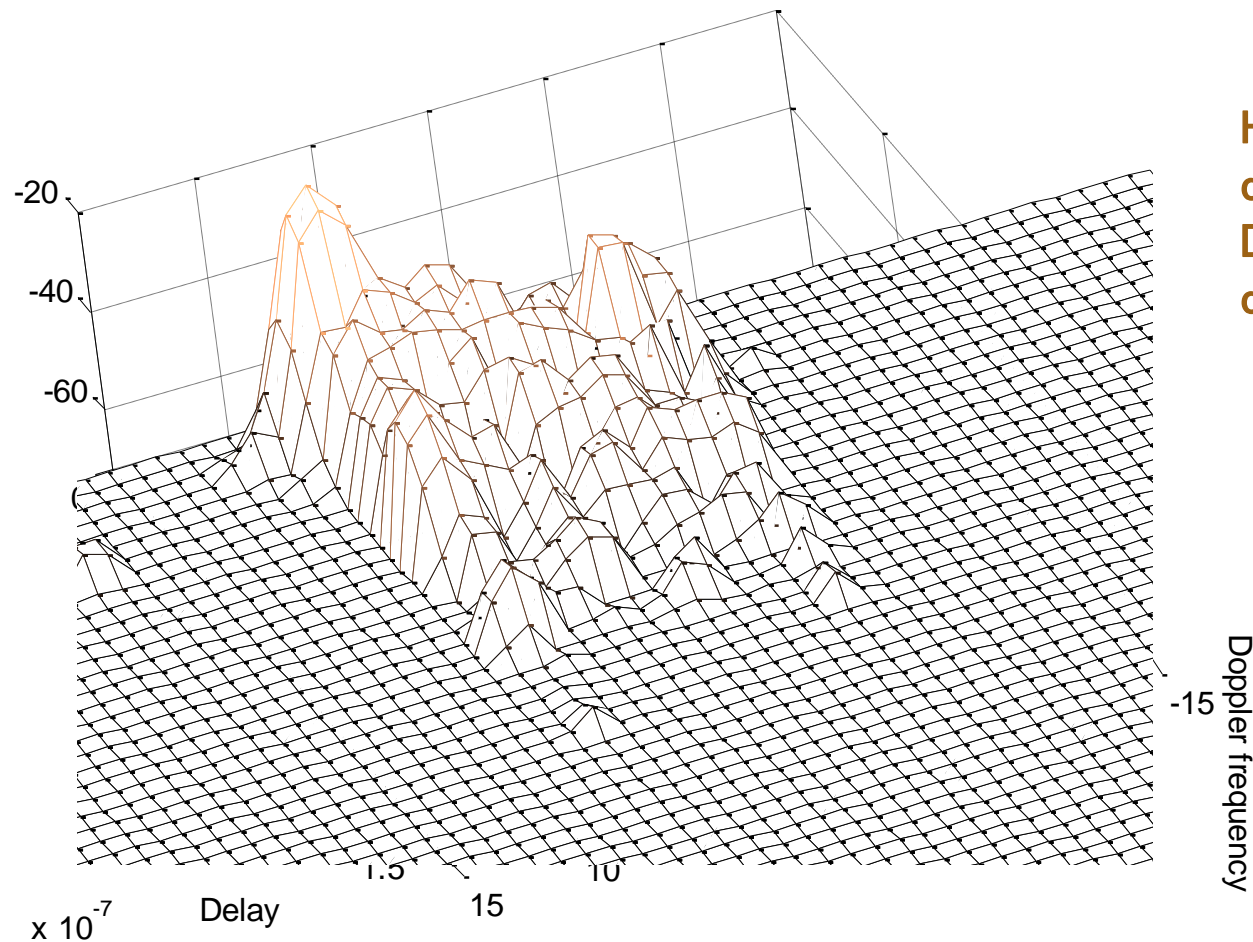
How is the power for different delays correlated in time?





# Spreading function (Doppler-variant transfer function) of the channel

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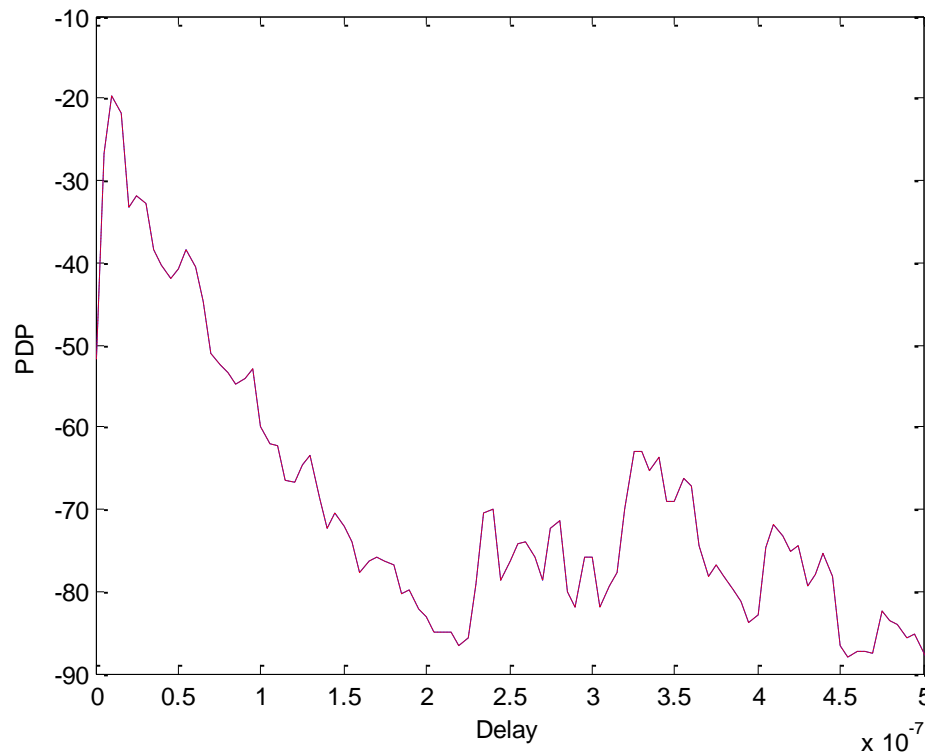
How is the power distributed in the Doppler and delay domains?





# Integrating the spreading function over the Doppler – the delay domain

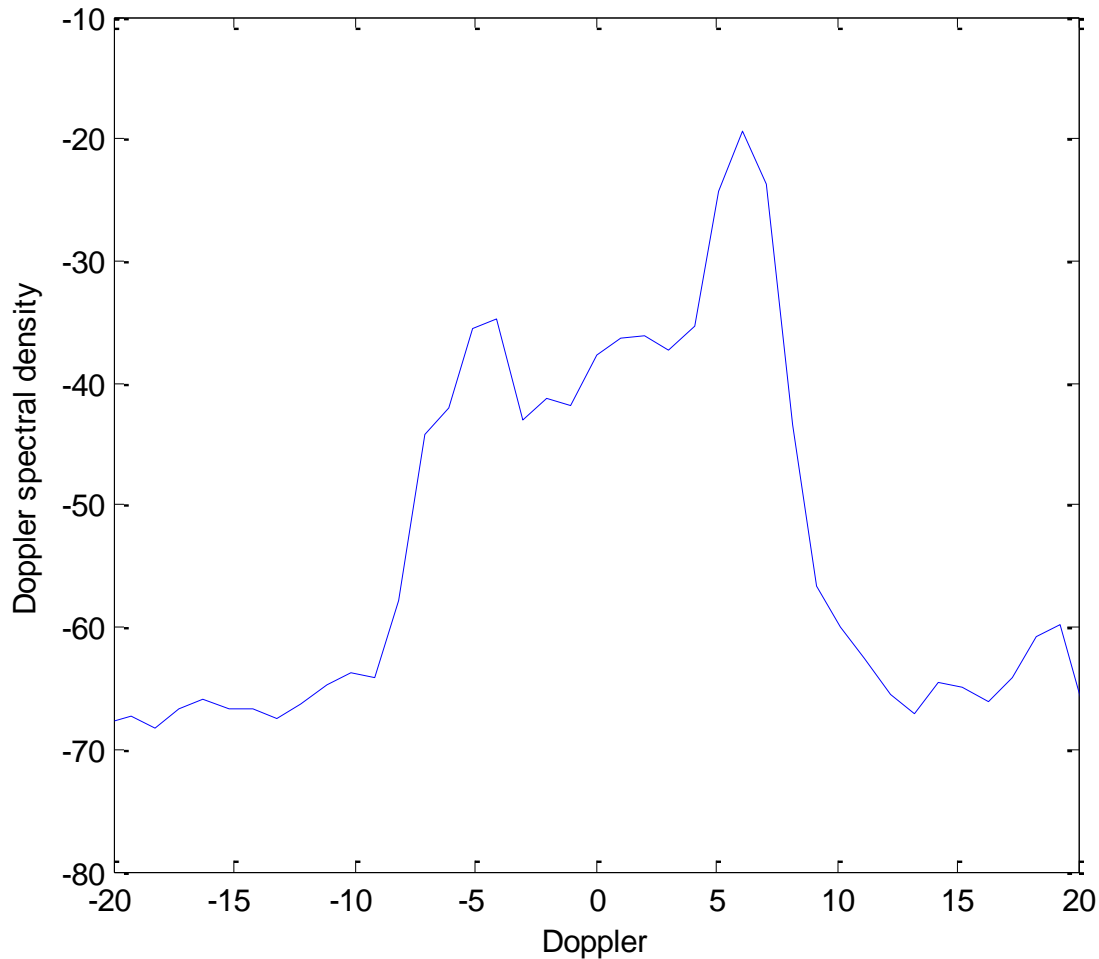
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**How is the power distributed in the delay domain?**

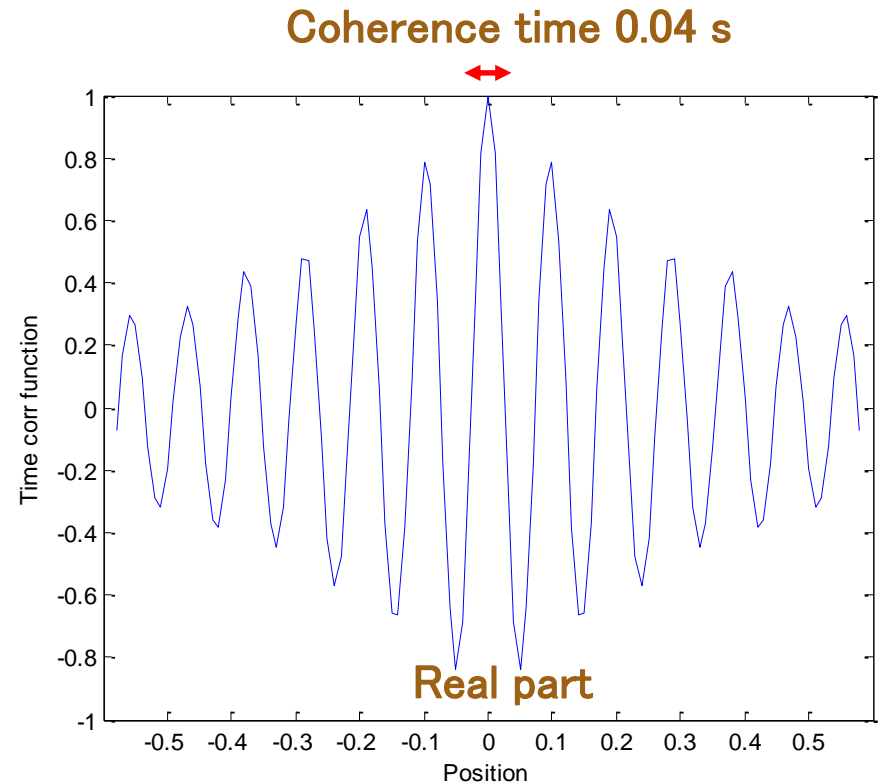
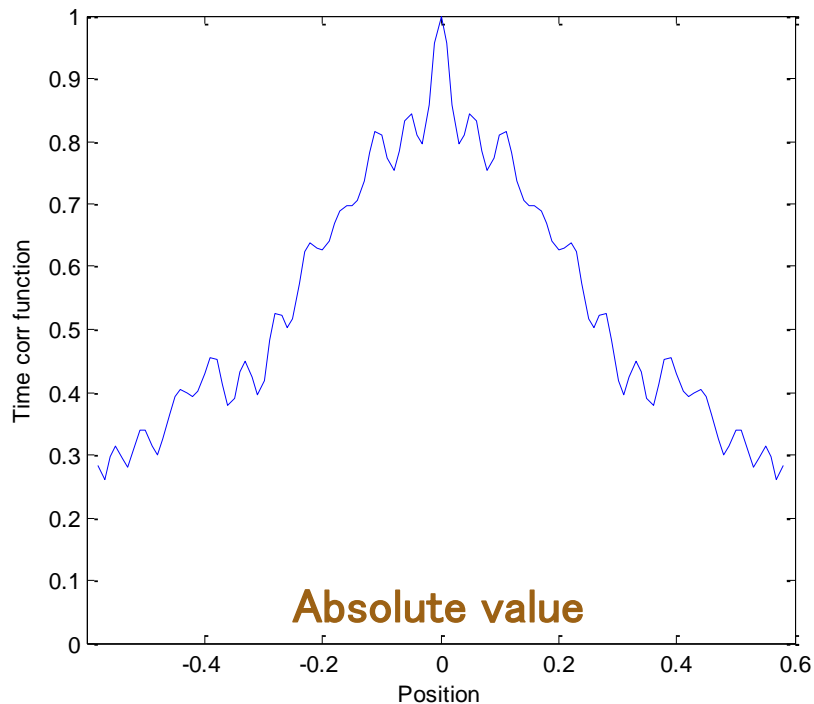


# Integrating the scattering function over the delay – the Doppler spectral density

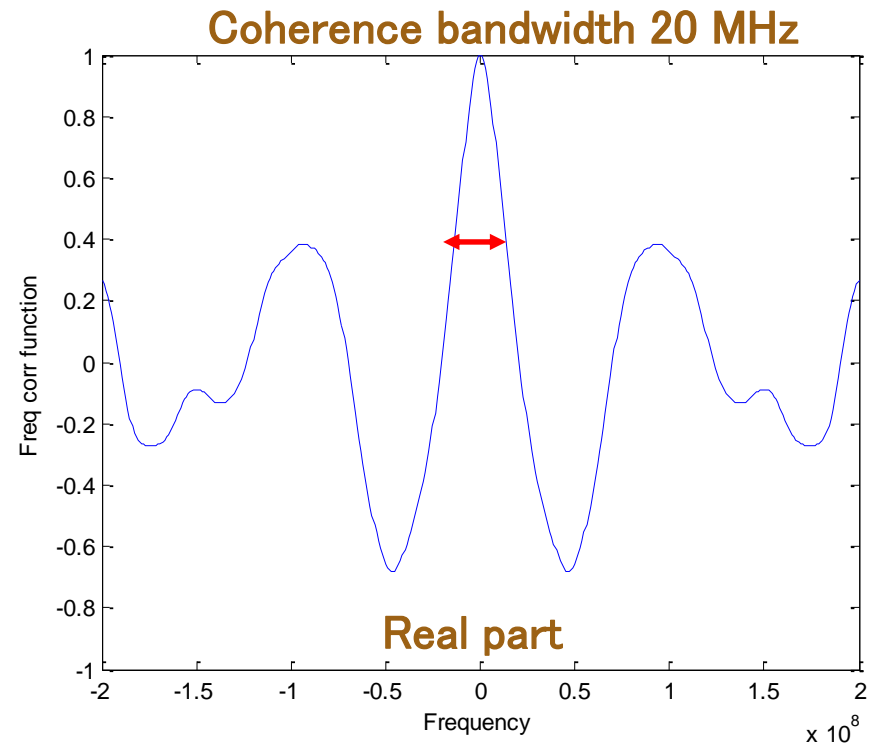
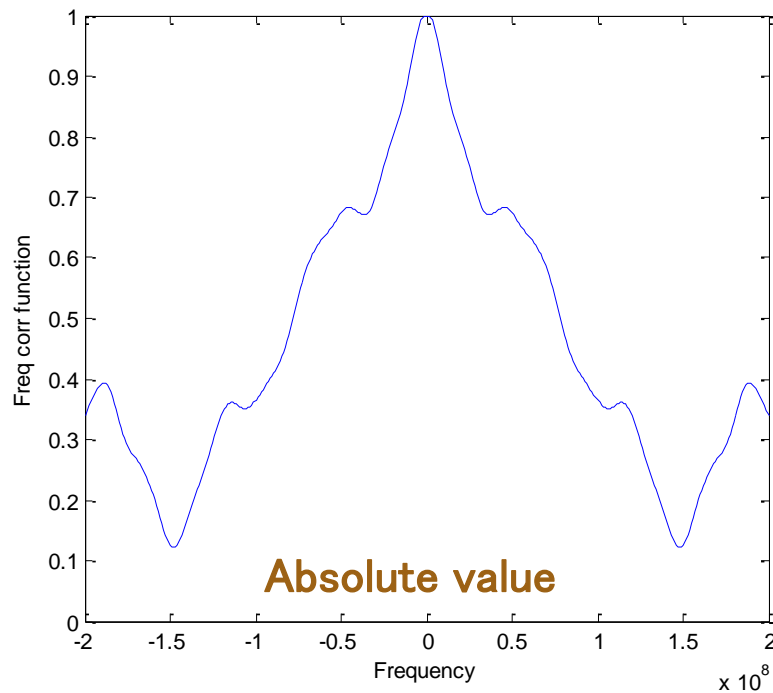


**How is the power distributed in the Doppler domain?**

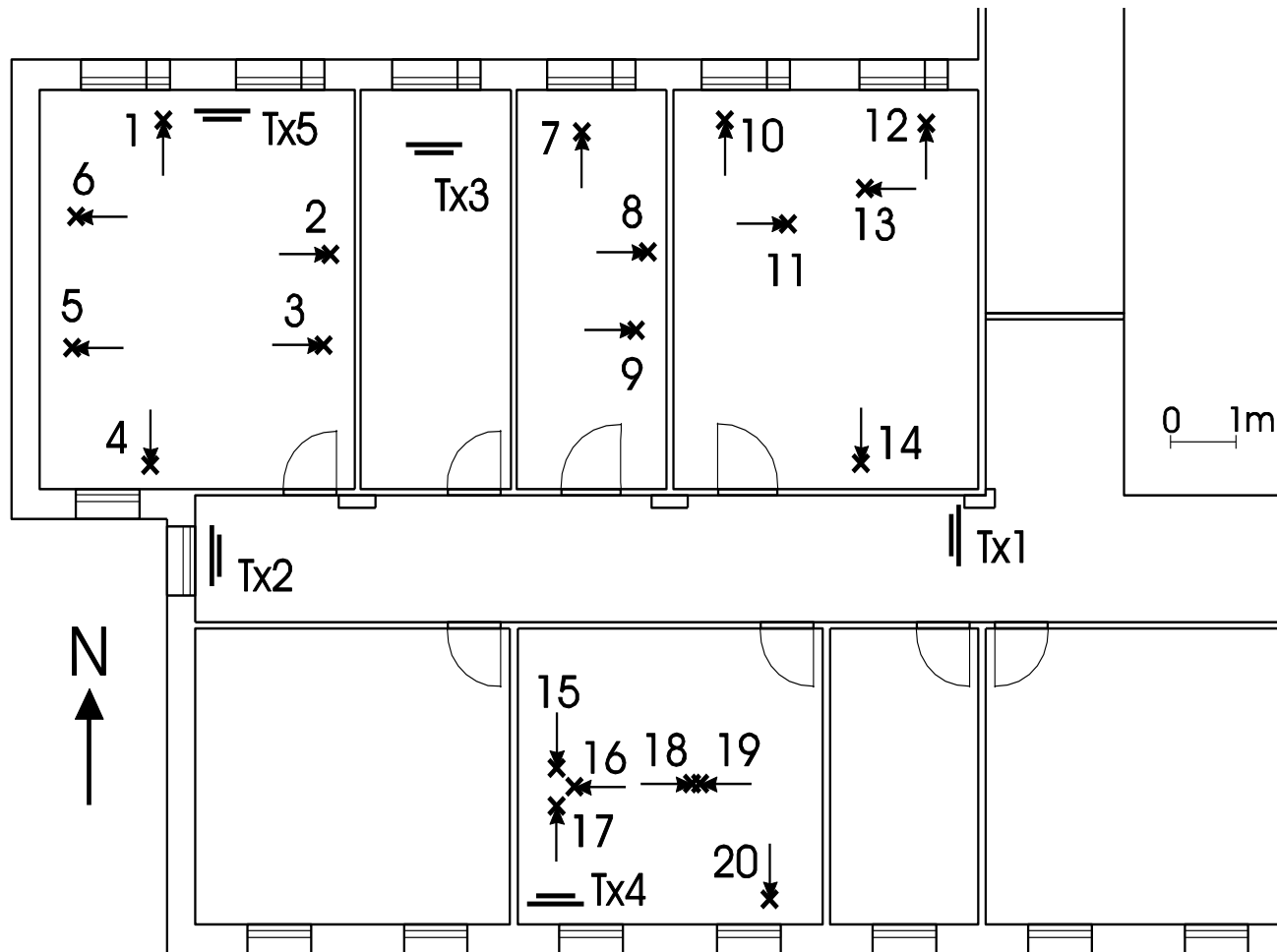
# Measured time correlation function



# Measured Frequency correlation function



# Measurements performed at typical work positions



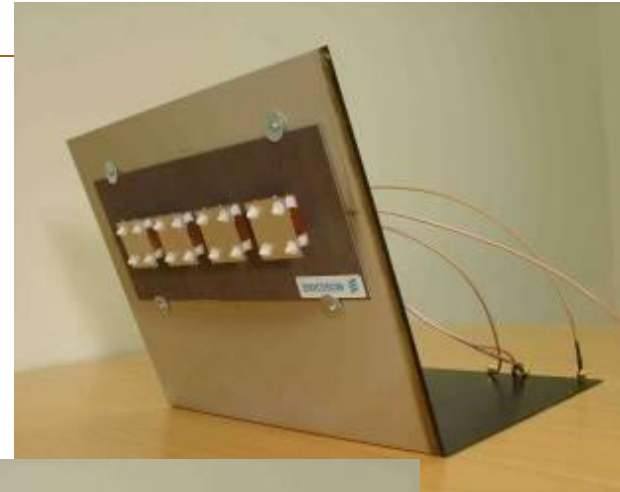
# 2.6 GHz antennas



**2 port  
hand held**



**4 port  
hand held**



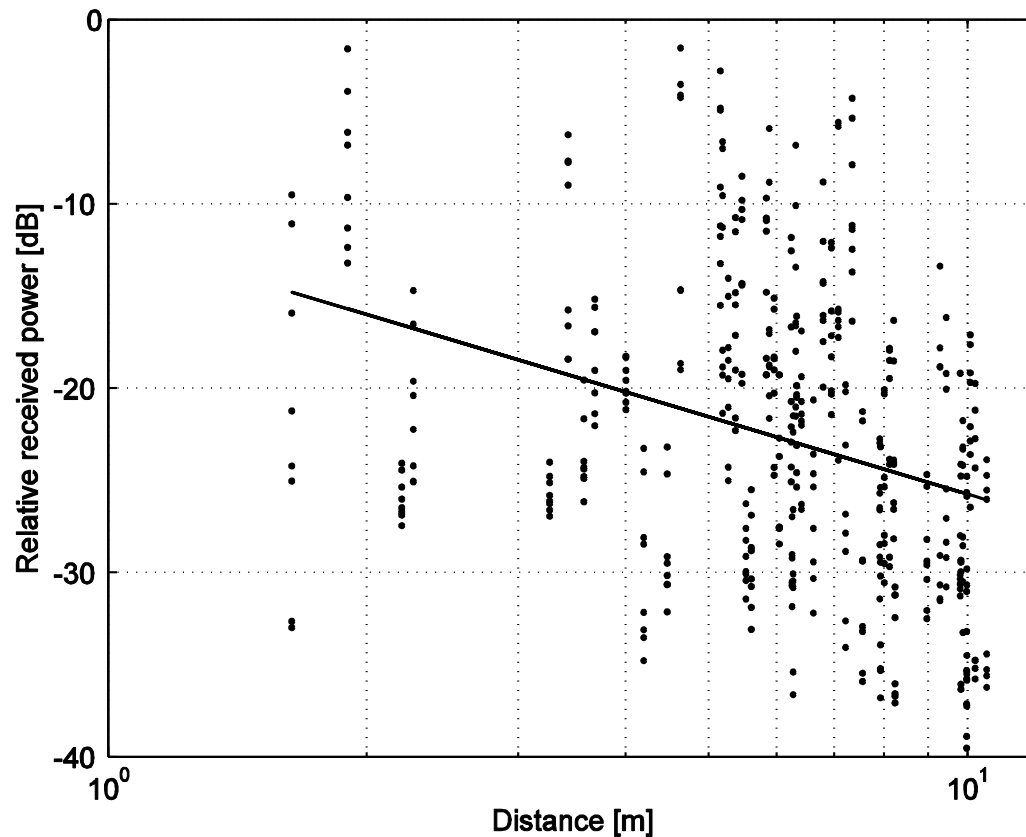
**PC**



**Fixed  
device**

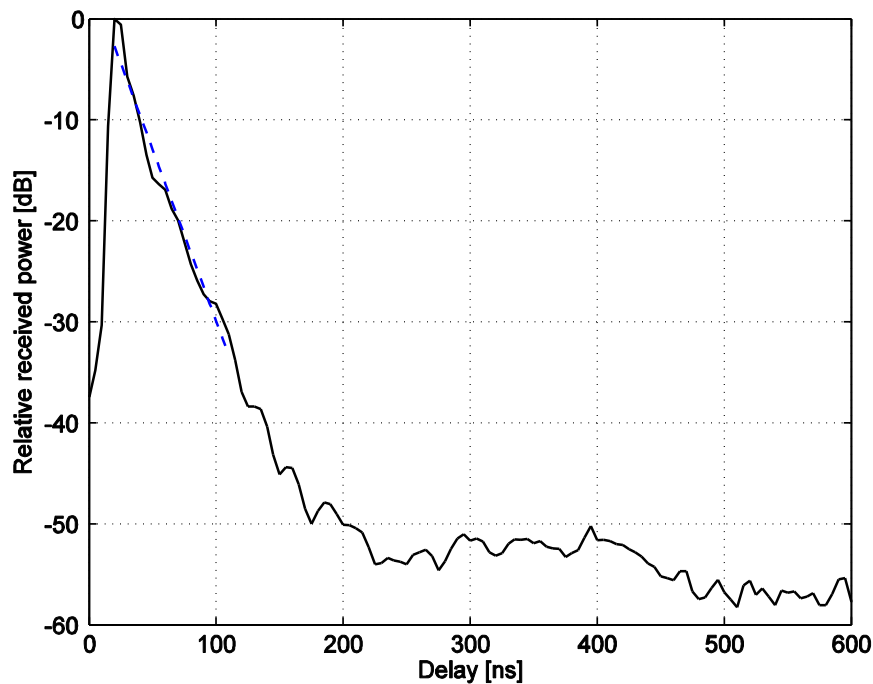
# Total received power vs. link distance

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# Power delay profile

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- exponential decay

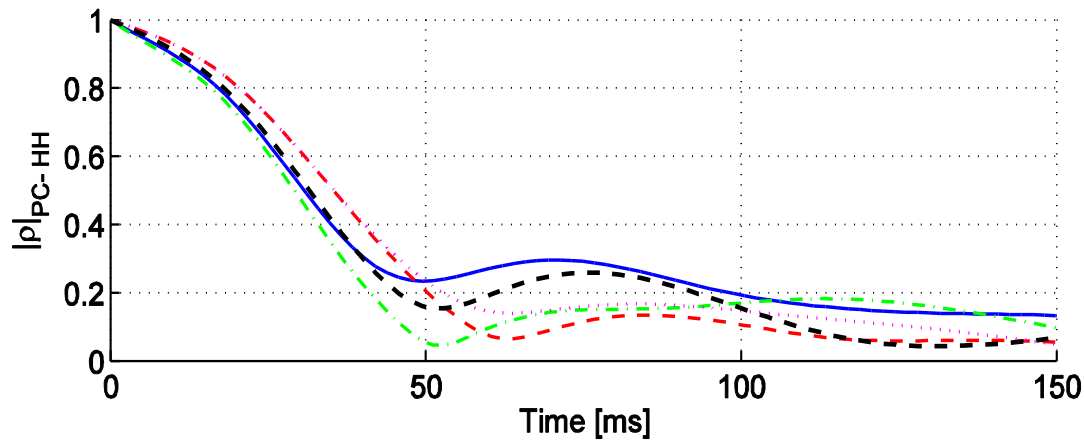
$$P(\tau) = |\beta|^2 e^{-\tau/\gamma}$$

- mean 10 - 13 ns
- standard deviation 1.2 - 2.1 ns



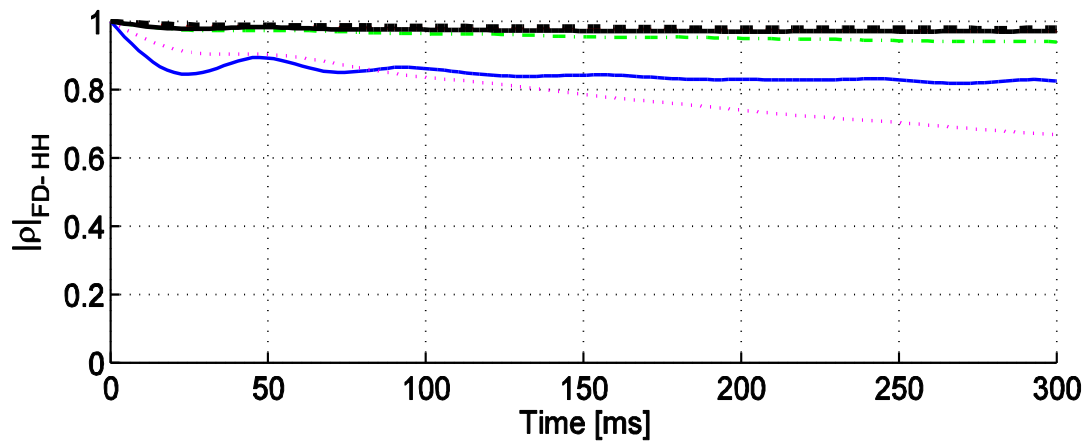


# Variation of coherence time vs. measured environment



**PC-HH**

**moving receiver**

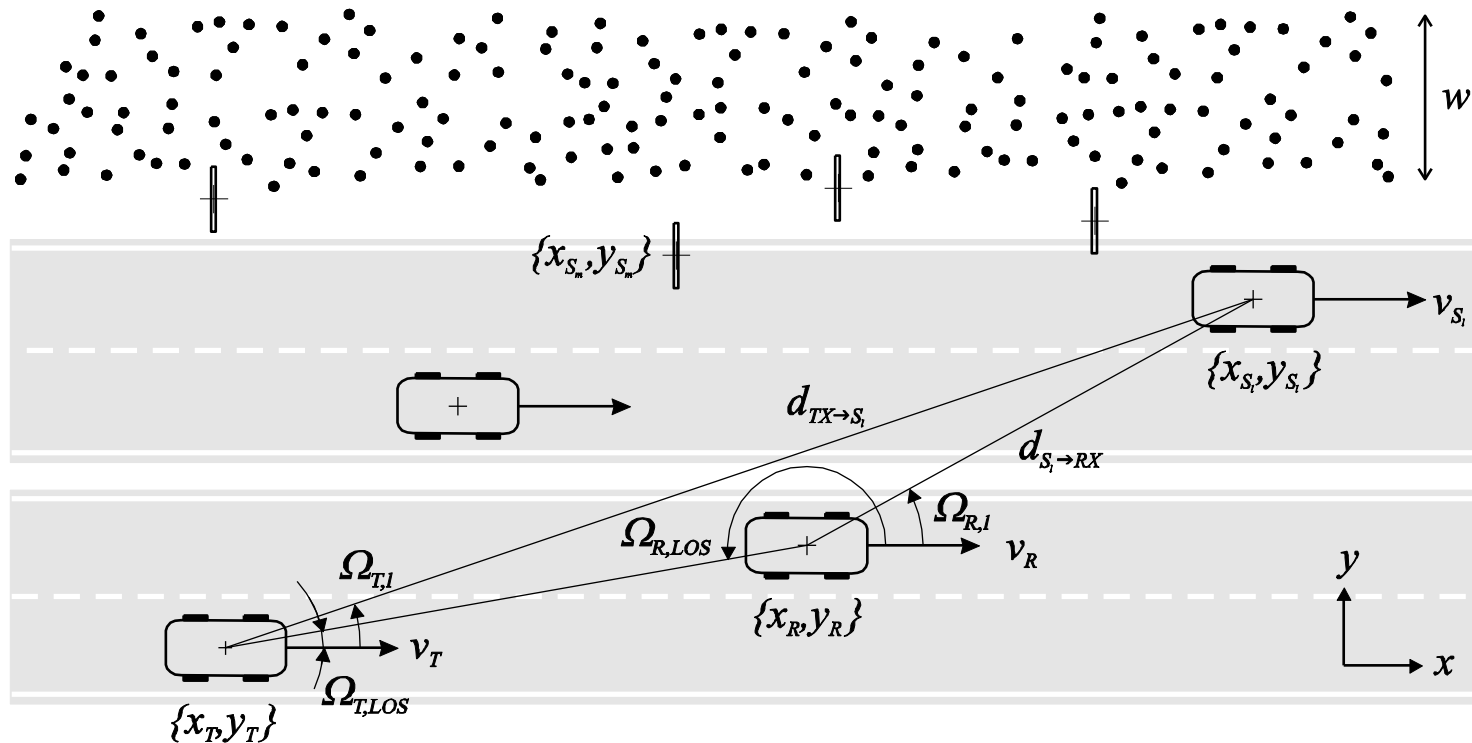


**FD-HH**

**person moving  
in corridor**

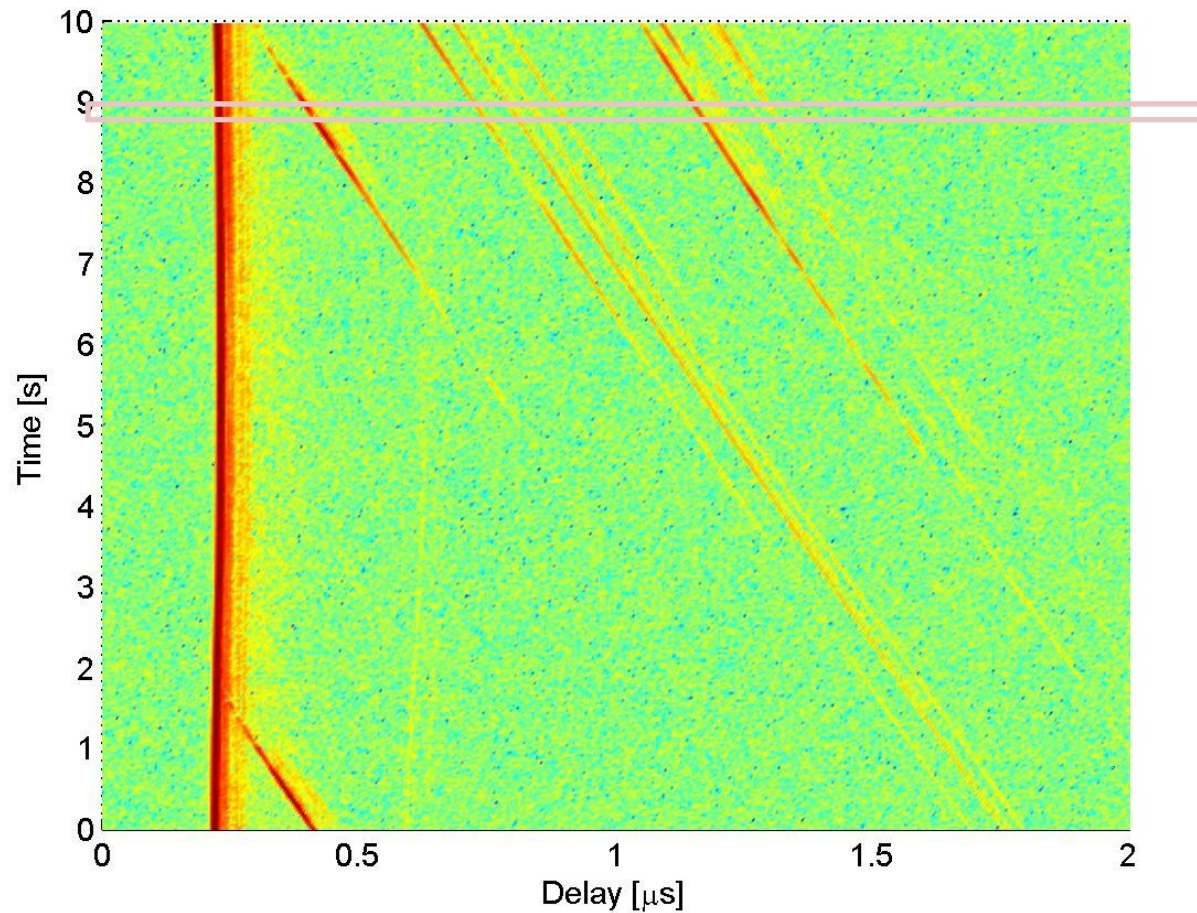
# Car to car communication

Cars driving in same direction with a distance of 50 m, 70 km/h, rural area



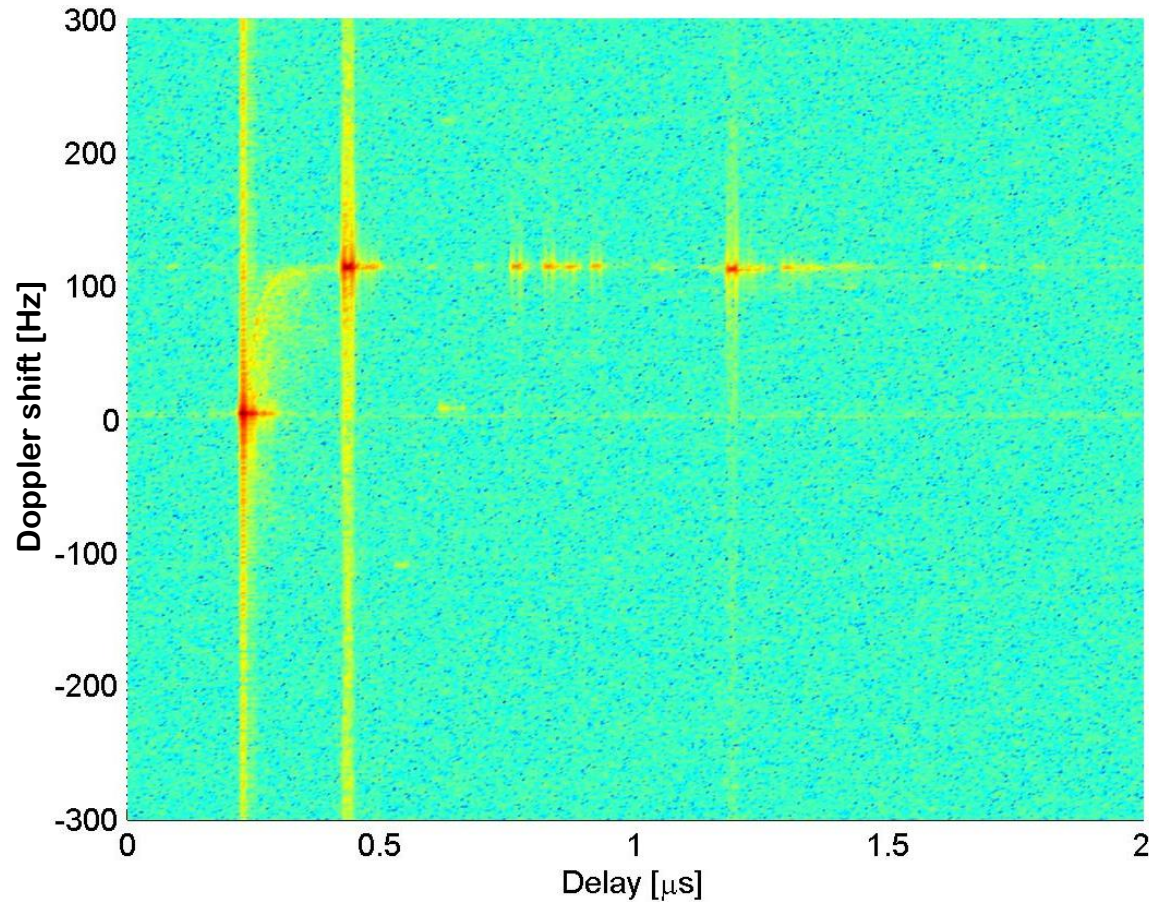
# Time variant impulse response

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# Scattering function, $t=8.5-8.65$ s

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# UWB channel

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- UWB bandwidth is relatively large compared to the carrier frequency
- Different frequency components see different propagation properties
- Statistical channel models are changed



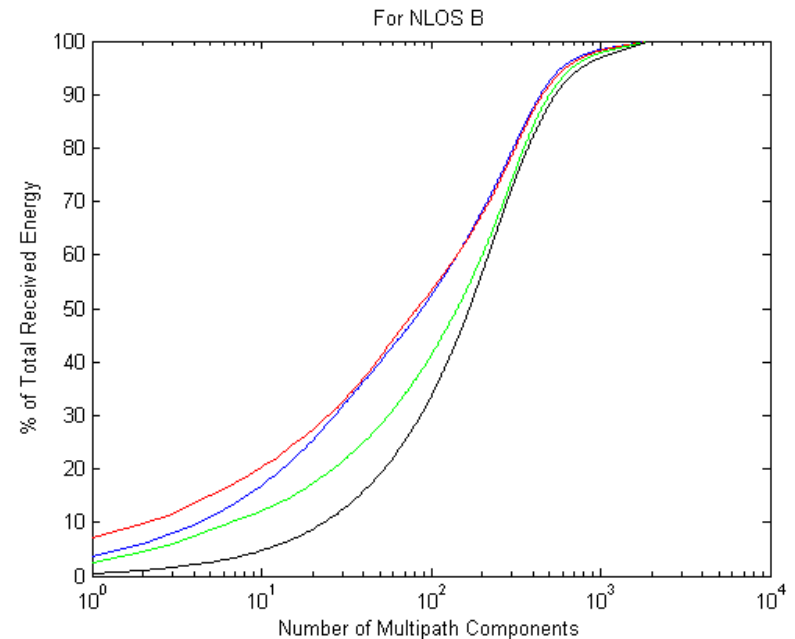
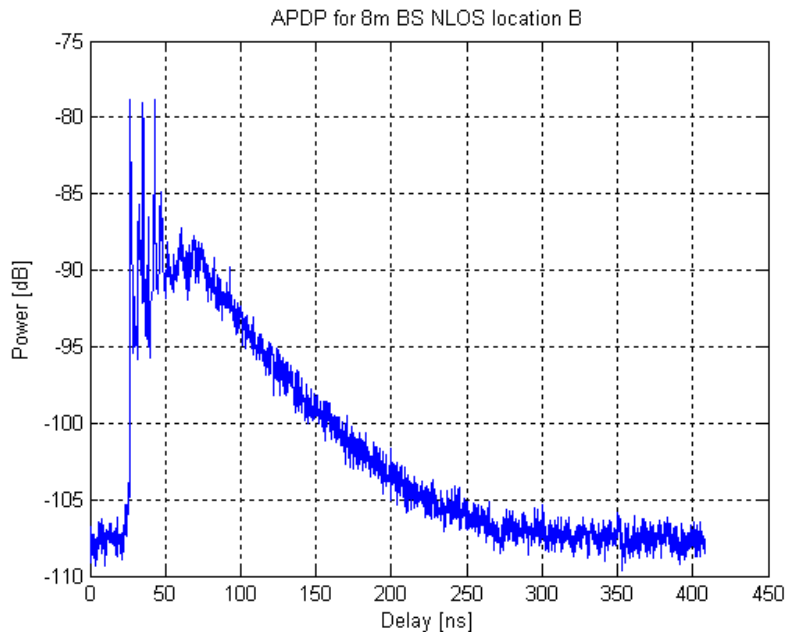
# Measurements in an industrial UWB channel

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4.9 GHz bandwidth  
49 TX-RX positions  
7\*7 Virtual MIMO system  
Antenna array elements  
separation 5cm  
TX-RX Separations 3,6,10,12m



# UWB channels – PDP



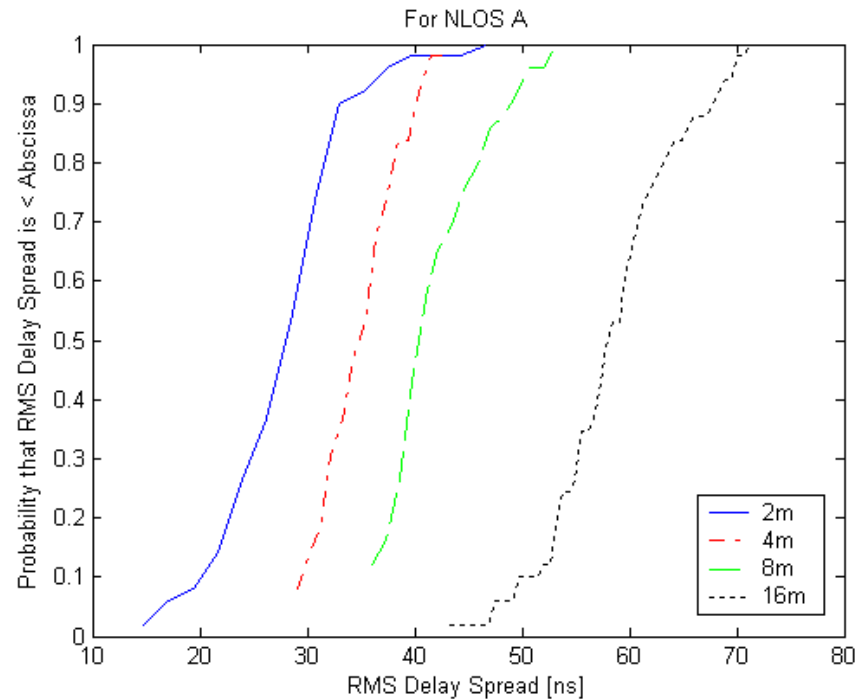
Huge bandwidth – possible to identify single multipath components

Need a large number of fingers in a special type of receiver (so called RAKE receiver)



# UWB channels

Delay spread is mainly dependent on distance to the scatterers, since it influences the resolvability of the system to identify potential multipath components.







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