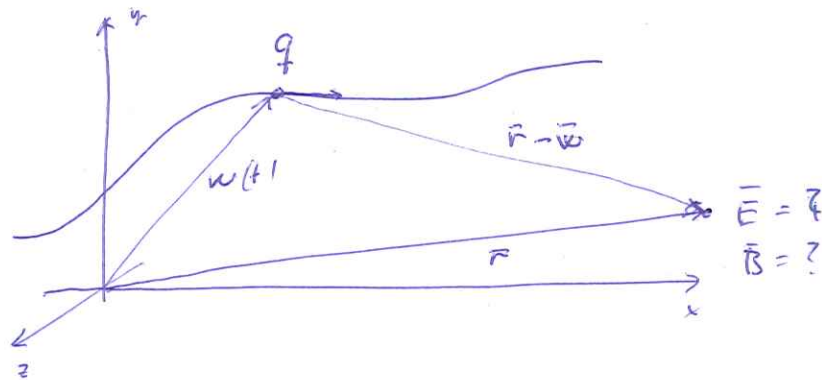


Liénard-Wiechert potentials

Find $\vec{E}(\vec{r})$ and $\vec{B}(\vec{r})$ from q that moves along the curve $\vec{w}(t)$. t = time



Position $\vec{w}(t)$

Velocity $\vec{v}(t) = \frac{d\vec{w}(t)}{dt}$

acceleration $\vec{a}(t) = \frac{d^2\vec{w}(t)}{dt^2}$

Charge density $= \rho(\vec{r}, t)$

$\rho(\vec{r}, t) = q \delta^3(\vec{r} - \vec{w}(t))$

where $\delta^3(\vec{r} - \vec{r}_0) = \delta(x - x_0) \delta(y - y_0) \delta(z - z_0)$

$$\int_V \delta^3(\vec{r} - \vec{r}_0) dV = \begin{cases} 1 & \text{if } \vec{r}_0 \in V \\ 0 & \text{otherwise} \end{cases}$$

$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0}$

Current density $= \vec{j}(\vec{r}, t) = \rho(\vec{r}, t) \vec{v}(\vec{r}, t)$

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(\vec{r}', t_r)}{|\vec{r} - \vec{r}'|} dV'$$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{j}(\vec{r}', t_r)}{|\vec{r} - \vec{r}'|} dV'$$

$t_r = t - \frac{|\vec{r} - \vec{r}'|}{c}$ = retarded time

$$\Rightarrow V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \int_V \frac{\delta^3(\vec{r}' - \vec{w}(t_r))}{|\vec{r} - \vec{r}'|} dV'$$

$$\vec{A}(\vec{r}, t) = \frac{q\mu_0}{4\pi} \int_V \frac{\vec{v}(t_r) \delta^3(\vec{r}' - \vec{w}(t_r))}{|\vec{r} - \vec{r}'|} dV'$$

Note $w(t_r) = w\left(t - \frac{|\vec{r} - \vec{w}(t_r)|}{c}\right)$
 gives problem

Change of variables in integrals gives

$$V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 (|\vec{r} - \vec{w}(t_r)| - \vec{\beta} \cdot (\vec{r} - \vec{w}(t_r)))}$$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0 q \vec{v}(t_r)}{4\pi (|\vec{r} - \vec{w}(t_r)| - \vec{\beta} \cdot (\vec{r} - \vec{w}(t_r)))} = \frac{1}{c^2} V(\vec{r}, t) \cdot \vec{v}(t_r)$$

$$\vec{\beta} = \frac{\vec{v}(t_r)}{c}$$

\vec{E}, \vec{B}

$$\vec{E}(\vec{r}, t) = -\nabla V(\vec{r}, t) - \frac{\partial \vec{A}(\vec{r}, t)}{\partial t}$$

$$\vec{B}(\vec{r}, t) = \nabla \times \vec{A}(\vec{r}, t)$$

\Rightarrow see Griffiths

$$\vec{R} = \vec{r} - \vec{w}(t_r), \quad R = |\vec{R}|, \quad \vec{u} = c \hat{R} - \vec{v}(t_r)$$

$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{R}{(R \cdot \vec{u})^3} [(c^2 - v^2) \vec{u} + \vec{R} \times (\vec{u} \times \vec{a})]$$

Notice! $\vec{R} = \vec{R}(t_r), v = v(t_r), \vec{a} = \vec{a}(t_r)$ in this expression

$$\vec{B}(\vec{r}, t) = \frac{1}{c} \hat{n} \times (\vec{E} \vec{r}, t)$$

Notice: $\vec{E} \perp \vec{B}$

Example Assume $\vec{w}(t_r) = \vec{r}_0$ (constant)

$$\Rightarrow \vec{v} = \frac{d\vec{w}}{dt} = \vec{0} \quad \text{and} \quad \vec{a} = \frac{d^2\vec{w}}{dt^2} = \vec{0}$$

$$\Rightarrow \vec{u} = c \hat{n}$$

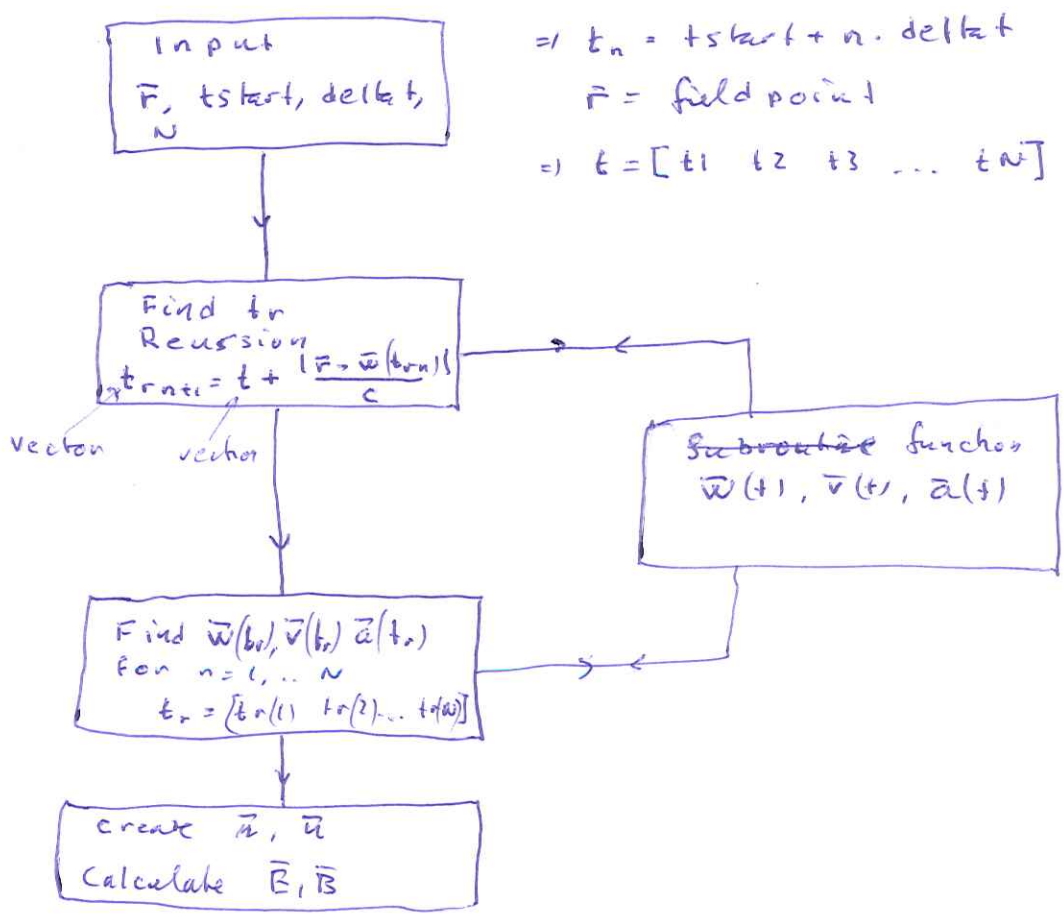
$$\Rightarrow \vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1}{(cr)^3} \quad c^3 \hat{n} = \frac{q}{4\pi\epsilon_0} \frac{\hat{n}}{r^2}$$

$$\vec{B} = \vec{0}$$

\Rightarrow Coulomb field

Matlab script

Use function or script



Dot and cross in Matlab

4

Ex
Let

$$\mathbf{A} = [A_x \ A_y \ A_z];$$

$$\mathbf{B} = [B_x \ B_y \ B_z];$$

row vectors $\bar{A} = (A_x, A_y, A_z)$

$$\bar{B} = (B_x, B_y, B_z)$$

$$\Rightarrow C = \text{dot}(\mathbf{A}, \mathbf{B});$$

$C = \bar{A} \cdot \bar{B}$ scalar product

$$D = \text{cross}(\mathbf{A}, \mathbf{B});$$

$\bar{D} = \bar{A} \times \bar{B}$ vector product.

Notice $\text{dot}(\mathbf{A}, \mathbf{B}) = \mathbf{A} \cdot \mathbf{B}$

Recursion

$tr = t - r/c$;
 $tol = 1e-4$; (for instance)

while $\text{diff} > tol$

$$trn = t - (r-w(tr))/c;$$

$$\text{diff} = \max(\text{abs}(tr - trn)) / \dots$$

$$tr = trn$$

end

\vec{E} and \vec{B} from q with constant \vec{v} ~~($\vec{v} \ll c$)~~ $\Rightarrow \vec{w}(t) = \vec{w}(0) + \vec{v} \cdot t$ 5



$\vec{a} = 0 \Rightarrow$

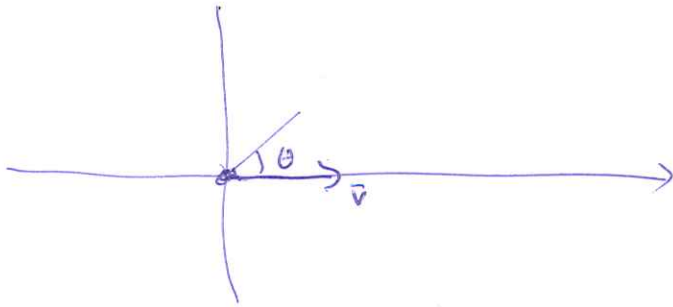
$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{(c^2 - v^2) \vec{r}}{(\vec{r} \cdot \vec{u})^3} \vec{u}$$

Remember! $\vec{r} = \vec{r} - \vec{w}(t_r)$
 $\vec{u} = c \hat{r}(t_r) - \vec{v}$

We get, see Griffiths

$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1 - (v/c)^2}{(1 - v^2 \sin^2\theta / c^2)^{3/2}} \frac{\hat{R}}{R^2}$$

where $\vec{R} = \vec{r} - \vec{v} \cdot t$ (Notice! t , not t_r)



Forward $\Rightarrow \theta = 0, \Rightarrow \vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{\hat{R}}{R^2} \cdot (1 - (v/c)^2)$
 \Rightarrow reduced by factor $1 - (v/c)^2$

Perpendicular $\Rightarrow \theta = \frac{\pi}{2} \Rightarrow \vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{\hat{R}}{R^2} \frac{1}{\sqrt{1 - (v/c)^2}}$
 \Rightarrow enhanced by $\frac{1}{\sqrt{1 - (v/c)^2}}$

Notiz

$$\vec{B}(\vec{r}, t) = \frac{1}{c} \hat{n} \times \vec{E}(\vec{r}, t)$$

$$\hat{n} = \frac{\vec{r} - \vec{v} \cdot t_r}{r} = \frac{(\vec{r} - \vec{v} t) + (t - t_r) \vec{v}}{r} = \frac{\vec{R}}{r} + \frac{\vec{v}}{c}$$

$(t - t_r = \frac{r}{c})$

$$\Rightarrow \vec{B}(\vec{r}, t) = \frac{1}{c^2} \vec{v} \times \vec{E}(\vec{r}, t)$$

