

EITG05 – Digital Communications

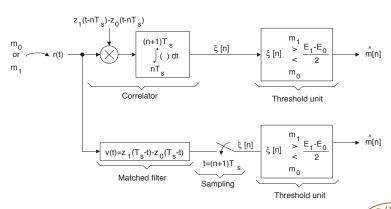
Lecture 6

Receivers continued: System design criteria, Performance for *M*-ary signaling

> Michael Lentmaier Monday, September 23, 2019

Last week: Analysis Binary Signaling

Only one correlator or one matched filter is now required:

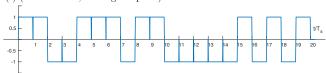


Matched filter output needs be sampled at correct time



Example: (see Matlab demo)

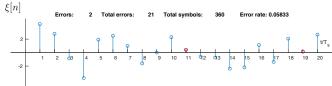
z(t) (random data, rectangular pulse)













An energy efficiency perspective

- ▶ Consider the case $P_0 = P_1 = 1/2$
- ► The average received energy per bit is then

$$\mathcal{E}_b = \frac{1}{2} \int_0^{T_b} z_0^2(t) \ dt + \frac{1}{2} \int_0^{T_b} z_1^2(t) \ dt = \frac{E_0 + E_1}{2}$$

 We can then introduce the normalized squared Euclidean distance

$$d_{0,1}^2 = \frac{D_{0,1}^2}{2\mathcal{E}_b} = \frac{1}{2\mathcal{E}_b} \int_0^{T_b} (z_1(t) - z_0(t))^2 dt$$

▶ With this the bit error probability becomes

$$P_b = Q\left(\sqrt{\frac{D_{0,1}^2}{2N_0}}\right) = Q\left(\sqrt{d_{0,1}^2 \frac{\mathcal{E}_b}{N_0}}\right)$$

► The parameter $d_{0.1}^2$ is a measure of energy efficiency



Special case 1: antipodal signals

▶ In case of antipodal signals we have $z_1(t) = -z_0(t)$ and

$$D_{0,1}^2 = \int_0^{T_b} (z_1(t) - z_0(t))^2 dt = 4 \int_0^{T_b} z_1^2(t) dt = 4E$$

From $E_0 = E_1 = E$ follows

$$\mathcal{E}_b = \frac{E + E}{2} = E$$

and

$$d_{0,1}^2 = \frac{D_{0,1}^2}{2\,\mathcal{E}_h} = \frac{4E}{2E} = 2$$

► The bit error probability for any pair of antipodal signals becomes

$$P_b = Q\left(\sqrt{2\frac{\mathcal{E}_b}{N_0}}\right)$$



Special case 2: orthogonal signals

In case of orthogonal signals we have

$$\int_0^{T_b} z_0(t) z_1(t) dt = 0$$

and hence (compare page 28)

$$D_{0,1}^2 = \int_0^{T_b} (z_1(t) - z_0(t))^2 dt = E_0 + E_1$$

► This gives

$$\mathcal{E}_b = \frac{E_0 + E_1}{2}$$

and

$$d_{0,1}^2 = \frac{D_{0,1}^2}{2\,\mathcal{E}_h} = \frac{E_0 + E_1}{E_0 + E_1} = 1$$

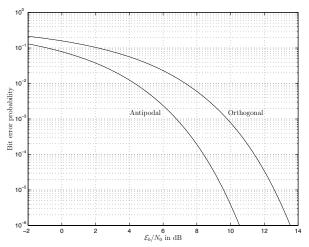
► The bit error probability for any pair of orthogonal signals is

$$P_b = Q\left(\sqrt{rac{\mathcal{E}_b}{N_0}}\right)$$



Comparison

Antipodal vs orthogonal signaling:



Larger values of $d_{0,1}^2$ give better energy efficiency



Antipodal vs orthogonal signaling

- ► There is a constant gap between the two curves
- ▶ We can measure the difference in energy efficiency by the ratio

$$\frac{\mathcal{E}_{b,atp}}{\mathcal{E}_{b,ort}} = \frac{d_{0,1,ort}^2}{d_{0,1,atp}^2} = \frac{1}{2}$$

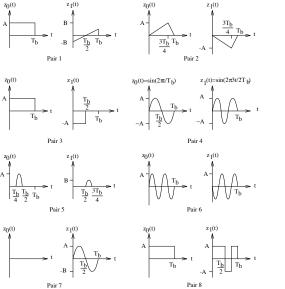
In terms of dB this corresponds to

$$10\log_{10}\left(\frac{\mathcal{E}_{b,atp}}{\mathcal{E}_{b,ort}}\right) = 10\log_{10}\left(\frac{d_{0,1,ort}^2}{d_{0,1,atp}^2}\right) = -3 \text{ [dB]}$$

 \Rightarrow antipodal signaling requires 3 dB less energy for equal P_b



Example 4.11: rank pairs with respect to $d_{0,1}^2$





Can we do better?

It is possible to show that for two equally likely signal alternatives we always have

$$d_{0,1}^2 \le 2$$

▶ Antipodal signaling is hence optimal for binary signaling (M = 2)

Remark:

- ▶ Channel coding can be used to further increase $d_{0.1}^2$
- Sequences of binary pulses with large separation are designed
- ► This does not contradict the result from above: coded binary signals correspond to uncoded signals with M > 2

Channel coding can be used for improving energy efficiency Cost: complexity, latency, (bandwidth)



Relationship between parameters

▶ The bit error probability can be expressed in different ways

$$P_b = Q\left(\sqrt{rac{D_{0,1}^2}{2N_0}}\;
ight) = Q\left(\sqrt{d_{0,1}^2rac{\mathcal{E}_b}{N_0}}\;
ight) = Q\left(\sqrt{d_{0,1}^2rac{P_z}{R_bN_0}}\;
ight)$$

► Assuming $z_0(t) = \alpha s_0(t)$ and $z_1(t) = \alpha s_1(t)$ we also get

$$P_b = Q\left(\sqrt{d_{0,1}^2\,rac{lpha^2ar{P}_{sent}}{R_b\,N_0}}\,
ight) = Q\left(\sqrt{rac{d_{0,1}^2}{
ho}\cdotrac{lpha^2ar{P}_{sent}}{N_0\,W}}\,
ight)$$

▶ Recall that $\rho = R_b/W$ is the bandwidth efficiency and N_0W is the noise power within the bandwidth W

The expression that is most appropriate to use depends on the specific problem to be solved

A "typical" type of problem

▶ The bit error probability must not exceed a certain level,

$$P_b \leq P_{b,req} = Q(\sqrt{\mathcal{X}})$$

- **Example:** if $P_{b,req} = 10^{-9}$ then $\mathcal{X} \approx 36$
- ► Consequences:

$$d_{0,1}^2 \frac{\mathcal{E}_b}{N_0} \geq \mathcal{X}$$

$$R_b \leq \frac{d_{0,1}^2}{\mathcal{X}} \cdot \frac{P_z}{N_0}$$

$$R_b \leq \frac{d_{0,1}^2}{\mathcal{X}} \cdot \frac{\alpha^2 \bar{P}_{sent}}{N_0}$$

Note: the received signal power Pz decreases with communication distance



Example 4.12: transmission hidden in noise

In a specific application equally likely binary antipodal signals are used, and the pulse shape is $g_{rc}(t)$ with amplitude A and duration $T \leq T_b$. AWGN with power spectral density $N_0/2$, and the ML receiver is assumed. It is required that the bit error probability must not exceed 10^{-9} . It is also required that the power spectral density satisfies $R(f) \leq N_0/2$ for all frequencies f (the information signal is intentionally "hidden" in the noise). Determine system and signal parameters above such that these two requirements are satisfied.

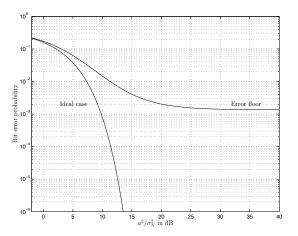
$$P_b = Q\left(\sqrt{2\mathcal{E}_b/N_0}\right) \le 10^{-9} \Rightarrow \mathcal{E}_b/N_0 \ge 18$$

- $ightharpoonup R(f) = R_b |G_{rc}(f)|^2$ has maximum at f = 0
- ► $R(0) = R_b A^2 T^2 / 4 \le N_0 / 2$ (check pulse shape)
- $\mathcal{E}_b/N_0 = 3/8A^2T/N_0 \ge 18$
- ▶ Hidden in noise: $A^2T/N_0 \le 2/(R_bT)$
- ▶ P_b requirement: $A^2T/N_0 \ge 48$
- Solution: choose $T \le T_b/24$ and $A^2 = 48N_0/T$



Non-ideal receiver conditions

Example 4.15: unexpected additional noise w_x , i.e., $w = w_N + w_x$

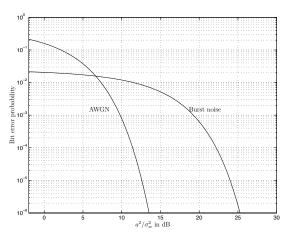


Can be analyzed with our methods



Non-ideal receiver conditions

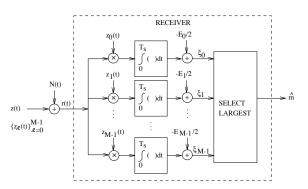
Example 4.16: hostile bursty interference, active with $p_{on} = 0.05$



Observe: at low power an interference in bursts is more severe than continuous interference



M-ary Signaling



- ▶ The receiver computes M decision variables $\xi_0, \xi_1, ..., \xi_{M-1}$
- ▶ The selected message \hat{m} is based on the largest value

$$\hat{m} = m_{\ell} , \quad \ell = \arg \max_{i} \xi_{i}$$

Question: when do we make a wrong decision?



Probability of a wrong decision

- For M = 2 we have considered two error probabilities P_F and P_M
- For a given message $m = m_j$, in general there are M 1 ways (events) to make a wrong decision,

$$\{\xi_i > \xi_j \mid m = m_j\}, \quad i \neq j$$

The probability of a wrong decision can be upper bounded by

$$Pr\{\hat{m} \neq m_j | m = m_j\} = Pr\left\{ \bigcup_{\substack{i=0\\i \neq j}}^{M-1} \xi_i > \xi_j \mid m = m_j \right\}$$

$$\leq \sum_{\substack{i=0\\i \neq j}}^{M-1} Pr\{\xi_i > \xi_j \mid m = m_j\} \quad \text{(union bound)}$$

▶ Note: given some events *A* and *B*, the union bound states that

$$Pr\{A \cup B\} \le Pr\{A\} + Pr\{B\} ,$$

where equality holds if A and B are independent



Symbol error probability

► The symbol error probability can be upper bounded by

$$P_{s} \leq \sum_{j=0}^{M-1} P_{j} \sum_{\substack{i=0 \ i \neq j}}^{M-1} Pr\{\xi_{i} > \xi_{j} \mid m = m_{j}\}$$

From the binary case M=2 we know that (pick i=0 and j=1)

$$Prig\{ \xi_i > \xi_j \mid m=m_j ig\} = Q\left(\sqrt{rac{D_{i,j}^2}{2N_0}}
ight)$$

where $D_{i,j}$ is the Euclidean distance between $z_i(t)$ and $z_j(t)$

▶ We obtain the following main result for *M*-ary signaling:

$$\max_{\substack{i \\ i \neq j}} \ Q\left(\sqrt{\frac{D_{i,j}^2}{2N_0}}\ \right) \ \leq \ P_s \ \leq \sum_{j=0}^{M-1} P_j \sum_{\substack{i=0 \\ i \neq j}}^{M-1} Q\left(\sqrt{\frac{D_{i,j}^2}{2N_0}}\ \right)$$



Example: orthogonal signaling

- ightharpoonup Consider M orthogonal signals with equal energy E
- ► Examples: FSK, PPM
- ▶ For each pair $z_i(t)$ and $z_i(t)$ we get

$$D_{i,j}^2 = E + E = 2E$$

From the union bound we obtain

$$\begin{split} P_s & \leq \sum_{j=0}^{M-1} P_j \sum_{\substack{i=0\\i \neq j}}^{M-1} Q\left(\sqrt{\frac{D_{i,j}^2}{2N_0}}\right) \\ & = (M-1) Q\left(\sqrt{\frac{2E}{2N_0}}\right) = (M-1) Q\left(\sqrt{\frac{E}{N_0}}\right) \end{split}$$

This generalizes the binary case considered previously



Distances $D_{i,j}$ are important

- $ightharpoonup P_s$ is determined by the distances $D_{i,j}$ between the signal pairs
- Let us sort these distances

$$D_{min} < D_1 < D_2 < \cdots < D_{max}$$

 \triangleright Then the upper bound on P_s can be written as

$$P_s \leq c \ Q\left(\sqrt{\frac{D_{min}^2}{2N_0}}\right) + c_1 \ Q\left(\sqrt{\frac{D_1^2}{2N_0}}\right) + \dots + c_x \ Q\left(\sqrt{\frac{D_{max}^2}{2N_0}}\right)$$

The coefficients are

$$c_{\ell} = \sum_{j=1}^{M-1} P_j \cdot n_{j,\ell} , \quad \ell = 0, 1, 2, \dots, x$$

▶ $n_{j,\ell}$: number of signals at distance D_{ℓ} from signal $z_j(t)$

How many distinct terms do exist for 4-PAM?



A useful approximation of P_s

- ▶ The union bound is easy to compute if we know all distances D_{ℓ}
- At large signal-to-noise ratio (small N_0), i.e., when P_s is small, the first term provides a good approximation

$$P_s pprox c \ Q\left(\sqrt{rac{D_{min}^2}{2 N_0}}\
ight)$$

We see that the minimum distance D_{min}^2 and the average number of closest signals c dominate the performance in this case

Explanation:

the function Q(x) decreases very fast as x increases (faster than exponentially). The other terms become negligible at some point.

 \Rightarrow at small P_s (small N_0) we can compare different signal constellations by means of D_{min}^2 , similarly to the binary case



Michael Lentmaier, Fall 2019

Energy efficiency and normalized distances

- ▶ Consider the case $P_{\ell} = 1/M$, $\ell = 0, 1, ..., M-1$
- ► The average received energy per bit is given by

$$\mathcal{E}_b = \frac{1}{k} \sum_{i=0}^{M-1} \frac{1}{M} \int_0^{T_s} z_i^2(t) dt = \frac{1}{k} \frac{E_0 + E_1 + \dots + E_{M-1}}{M}$$

Using the normalized squared Euclidean distances

$$d_\ell^2 = \frac{D_\ell^2}{2\,\mathcal{E}_b} \;,$$

the union bound can be written as

$$P_s \leq c Q\left(\sqrt{d_{min}^2 \frac{\mathcal{E}_b}{N_0}}\right) + c_1 Q\left(\sqrt{d_1^2 \frac{\mathcal{E}_b}{N_0}}\right) + \dots + c_x Q\left(\sqrt{d_{max}^2 \frac{\mathcal{E}_b}{N_0}}\right)$$

▶ The parameters d_ℓ^2 determine the energy efficiency



Approximate P_s for some constellations

▶ Considering the dominating term in the union bound we obtain

$$P_s \approx c \ Q\left(\sqrt{d_{min}^2 \frac{\mathcal{E}_b}{N_0}}\right)$$

▶ This approximation is valid if $\frac{\mathcal{E}_b}{N_0}$ is sufficiently large

	c	d_{\min}^2
M-ary PAM	2(1-1/M)	$\frac{6\log_2(M)}{M^2 - 1}$
M-ary PSK $(M > 2)$	2	$2\log_2(M)\sin^2(\pi/M)$
M-ary FSK	M-1	$\log_2(M)$
M-ary QAM	$4(1-1/\sqrt{M})$	$\frac{3\log_2(M)}{M-1}$

Table 4.1: The coefficient c, and d_{\min}^2 , for some common signal constellations. Equally likely signal alternatives are assumed. See Subsection 2.4.1.1 for the M-ary PAM case, and Subsection 2.4.5.1 for the M-ary QAM case. M equal energy orthogonal FSK signals are also assumed.

Example 4.19

Assume two signal constellations, denoted A and B respectively, with corresponding parameters $d_{\min,A}^2$ and $d_{\min,B}^2$. From the equality (see e.g. the dominating term in the union bound),

$$d_{\min,A}^2 \mathcal{E}_{b,A}/N_0 = d_{\min,B}^2 \mathcal{E}_{b,B}/N_0$$

we find that the difference (in dB) in received energy per information bit is (compare with (2.13) on page 16),

$$10\log_{10}(\mathcal{E}_{b,B}) - 10\log_{10}(\mathcal{E}_{b,A}) = 10\log_{10}\left(\frac{d_{\min,A}^2}{d_{\min,B}^2}\right)$$

Calculate the value $10 \log_{10} \left(\frac{d_{\min,A}^2}{d_{\min,B}^2} \right)$ if "A" is binary antipodal PAM, and if "B" is 4-ary PAM. Assume, that the conditions leading to (2.50) are satisfied.

► For *M*-ary PAM we have (Table 4.1 or Table 5.1)

$$d_{min}^2 = 6\log_2(M)/(M^2 - 1)$$
 $\Rightarrow d_{min,A}^2 = 2, d_{min,B}^2 = 4/5$

► $10\log_{10}d_{min\ A}^2/d_{min\ B}^2 = 10\log_{10}5/2 = 3.98\ dB$

Binary PAM is 3.98 dB more energy efficient than 4-ary PAM!



Short summary

- ► The binary receiver in Fig. 4.10 (one correlator / matched filter) is equivalent to the general receiver in Fig. 4.9 with M = 2
- For binary signaling (M = 2), the bit error probability P_b of the ML receiver can be computed using equation (4.53) on page 252
- For the M-ary case: union bound on P_s is given on p. 274
- ► Energy efficiency: measureable by normalized distances $d_{i,j}^2$ M=2: antipodal signaling with $d_{0,1}^2=2$ is optimal
- ► Study the relationships between P_b / P_s and rate, bandwidth, energy, power, given on p. 261–262 and p. 281–282

