

EITG05 – Digital Communications

Lecture 11

Intersymbol Interference Nyquist condition, Spectral raised cosine, Equalizers



Illustration of ISI in the receiver





Intersymbol Interference (ISI)

- For $R_s = 1/T_s < 1/T_u$ we can use the ML receiver from Chapter 4
- Question: can we use such a receiver for larger rates $R_s \ge 1/T_u$?
- Consider the following receiver structure (compare to last slide)



- ▶ Note that z(t) now is a superposition of overlapping pulses u(t)
- The signal y(t) after the receiver filter v(t) is

$$y(t) = \sum_{n=-\infty}^{\infty} A[n] x(t - nT_s) + w_c(t)$$

where $w_c(t)$ is a filtered Gaussian process

► The decision variable is obtained after sampling

$$\xi[i] = y(\mathcal{T} + iT_s) , \quad \mathcal{T} = t_0 + LT_s , \text{ where } LT_s \geq 0$$

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 T_{μ}

Discrete time model for ISI

According to our model the decision variable can be written as

$$\xi[i] = y(\mathcal{T} + iT_s) = \sum_{n=-\infty}^{\infty} A[n]x(\mathcal{T} + iT_s - nT_s) + w_c(\mathcal{T} + iT_s)$$

► Let us introduce the discrete sequences

$$x[i] = x(\mathcal{T} + iT_s)$$
, $w_c[i] = w_c(\mathcal{T} + iT_s)$

This leads to the following discrete-time model of our system

$$A[i] \longrightarrow x[i] \longrightarrow (+) \xrightarrow{\xi[i]} firshold \\ detection \longrightarrow \hat{m}[i]$$

$$\xi[i] = \sum_{n = -\infty}^{\infty} A[n] x[i - n] + w_c[i] = A[i] * x[i] + w_c[i]$$

Remark: the discrete-time impulse response x[i] represents pulse shape g(t), channel filter h(t), and receiver filter v(t)



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Example 6.1

The transmitted sequence of amplitudes A[i] is given as,

$$\begin{array}{c} A[i] \\ \uparrow \\ 1 - & \bullet & \bullet \\ \bullet & \bullet & 1 \\ \bullet & \bullet & 5 \\ \bullet & \bullet & 8 \\ \end{array}$$

Calculate, and plot, the sequence of decision variables $\xi[i]$ in Figure 6.2, for $0 \le i \le 8$, in the noiseless case (i.e. w(t) = 0) if $t_0 = 0$ and if the output pulse x(t) is:



Worst case ISI

The ISI term can be written as

$$ISI = \sum_{\substack{n = -\infty \\ n \neq i}}^{\infty} A[n] x[i - n] = \sum_{\substack{n = -\infty \\ n \neq 0}}^{\infty} A[i - n] x[n]$$

- Question: when does this term become largest?
- For symmetric *M*-ary PAM we have $\max |A[i]| = M 1$ and get

$$ISI_{wc}^{+} = \max(ISI) = \sum_{\substack{n = -\infty \\ n \neq 0}}^{\infty} \max(A[i-n]x[n]) = (M-1) \sum_{\substack{n = -\infty \\ n \neq 0}}^{\infty} |x[n]|$$

Similarly, the worst case minimal ISI becomes

$$ISI_{wc}^{-} = \min(ISI) = -(M-1) \sum_{\substack{n = -\infty \\ n \neq 0}}^{\infty} |x[n]|$$

Observe: the worst case ISI occurs for a information sequence A[i] consisting of a particular pattern of $\pm (M-1)$ values



How much ISI can we tolerate?

 We can divide the decision variable ξ[i] into a desired term (message) and an undesired term (interference plus noise)

$$\xi[i] = A[i]x[0] + \underbrace{\sum_{\substack{n=-\infty\\n\neq i}}^{\infty} A[n]x[i-n] + w_c[i]}_{\text{message}} \underbrace{\sum_{\substack{n=-\infty\\n\neq i}}^{\infty} A[n]x[i-n] + w_c[i]}_{\text{noise}}$$

► The influence of ISI depends on its relative strength





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Condition for ISI free reception

▶ Let us assume that *x*[*i*] satisfies the following condition:

$$x[i] = x(\mathcal{T} + iT_s) = x_0 \,\delta[i] = \begin{cases} x_0 & \text{if } i = 0\\ 0 & \text{if } i \neq 0 \end{cases}$$

Then

$$\xi[i] = \sum_{n = -\infty}^{\infty} A[n] x[i - n] + w_c[i] = A[i] x[0] + w_c[i]$$

- Otherwise there always will exist some non-zero ISI term
- ► For this reason we are interested in signals

$$x(t) = g(t) * h(t) * v(t)$$

for which the above condition is satisfied

Which parts of x(t) can we influence?



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Symbol rates for ISI free reception

- Suppose that the ISI free condition is satisfied for symbol rate R_s^*
- Then it will be satisfied for rates

$$R_s=\frac{R_s^*}{\ell},\quad \ell=1,2,3,\ldots$$

Example 6.6:

receiver?







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Nyquist condition in frequency domain

Let us now formulate the ISI free condition in frequency domain:

$$x[i] = x_0 \,\delta[i] \quad \Rightarrow \mathcal{X}(v) = \mathcal{F}\{x[i]\} = x_0 \quad \forall v$$

• Choosing $v = fT_s$ this leads to the equivalent Nyquist condition

$$\frac{\mathcal{X}(fT_s)}{R_s} = \sum_{n=-\infty}^{\infty} X_{nc}(f - nR_s) = \frac{x_0}{R_s} , \quad R_s = \frac{1}{T_s}$$

• Let W_{lp} denote the baseband bandwidth of $x_{nc}(t)$,

$$X_{nc}(f) = 0, \quad |f| > W_{lp}$$

Then ISI always will be present if the symbol rate satisfies

 $R_{s} > 2 W_{lp}$

(non-overlapping spectrum cannot add up to a constant)

▶ If we have $R_s \leq 2W_{lp}$: ISI-free reception is possible if $X_{nc}(f)$ has a proper shape



Representation in frequency domain

• The discrete sequence x[i] can be obtained by sampling a non-causal pulse $x_{nc}(t)$ at times iT_s ,

$$x[i] = x_{nc}(iT_s)$$
, where $x_{nc}(t) = x(\mathcal{T}+t)$,

• The Fourier transform $\mathcal{X}(v)$ of x[i] can then be expressed in terms of the Fourier transform $X_{nc}(f)$ of the signal $x_{nc}(t)$:

$$\mathcal{X}(\mathbf{v}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j2\pi \mathbf{v} n} = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X_{nc} \left(\frac{\mathbf{v}-n}{T_s} \right) ,$$

where

$$X_{nc}(f) = \int_{-\infty}^{\infty} x_{nc}(t) e^{-j2\pi f t} dt = G(f) H(f) V(f) e^{+j2\pi f T}$$

Observe: the spectrum of the sampled sequence x[i] consists of the periodically repeated spectrum of the continuous signal



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Example 6.7

Assume that $X_{nc}(f)$ is given below.



- a) Sketch the left hand side of (6.33), $\sum_{n=-\infty}^{\infty} X_{nc}(f-nR_s)$, if $R_s = 12000$ symbols per second.
- b) Does ISI occur in the receiver?

What happens if $R_s = 8000$?

And $R_s = 4000$?



Example 6.8

Assume that $X_{nc}(f)$ is,



 $A = x_0 T_s.$



Solution:



Some comments on bandwidth

- Remember: in Chapter 2 we have seen that strictly band-limited signals always have to be unlimited in time
- In practice we have to find compromises, which was leading to different definitions of bandwidth for time-limited signals

Pulse shape	W_{lobe}	% power	W_{90}	W_{99}	$W_{99.9}$	Asymptotic
		in W_{lobe}				decay
rec	2/T	90.3	1.70/T	20.6/T	204/T	f^{-2}
tri	4/T	99.7	1.70/T	2.60/T	6.24/T	f^{-4}
hcs	3/T	99.5	1.56/T	2.36/T	5.48/T	f^{-4}
rc	4/T	99.95	1.90/T	2.82/T	3.46/T	f^{-6}
Nyquist	R_s	100	$0.9R_s$	$0.99R_s$	$0.999R_{s}$	ideal

- We can see that time-limited signals need at least about twice the Nyquist bandwidth
- ► For OFDM with many sub-carriers *N* this is negligible (why?)
- For single-carrier systems, some close-to-Nyquist pulses are typically used in practice



Ideal Nyquist pulse

► The maximum possible signaling rate for ISI-free reception is

$$R_{nyq} = R_s = \frac{1}{T_s} = 2 W_{lp}$$
 (Nyquist rate

► With ideal Nyquist signaling, the bandwidth efficiency is

$$\rho_{nyq} = \frac{R_b}{W_{lp}} = \frac{R_{nyq} \log_2(M)}{R_{nyq}/2} = 2 \log_2 M = 2k \text{ [bps/Hz]}$$

The ideal Nyquist pulse must have rectangular spectrum

$$X_{nc}(f) = \begin{cases} x_0/R_{nyq} , & \text{if } |f| \le R_{nyq}/2 \\ 0 , & \text{else} \end{cases} \Rightarrow x_{nc}(t) = x_0 \ \frac{\sin(\pi R_{nyq} t)}{\pi R_{nyq} t}$$



Spectral Raised Cosine Pulses

 The spectral raised cosine pulse shape is defined by the following spectrum _{Xnc(f)}



The name refers to the way the shape is composed



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Spectral Raised Cosine Pulses

The parameter β, 0 ≤ β ≤ 1, is called the rolloff factor and can be used to smoothly control the bandwidth efficiency

$$\rho_{src} = \frac{R_b}{W_{lp}} = \frac{R_s \log_2 M}{(1+\beta)R_s/2} = \frac{2\log_2 M}{1+\beta} = \frac{2k}{1+\beta}$$

► In time domain the signal can be expressed as

$$x_{nc}(t) = x_0 \frac{\sin(\pi t/T_s)}{\pi t/T_s} \cdot \frac{\cos(\pi \beta t/T_s)}{1 - (2\beta t/T_s)^2}, \quad -\infty \le t \le \infty$$

• Larger rolloff factors $\beta \Rightarrow$ faster amplitude decay of $x_{nc}(t)$



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Signaling with overlapping pulses: $\beta = 1$



Spectral Raised Cosine Pulses





Signaling with overlapping pulses: $\beta = 0$





Spectral Root Raised Cosine Pulse

When analyzing the Nyquist condition we have considered the output signal of the receiver filter v(t), i.e.,

$$x_{nc}(t) = g(t) * h(t) * v(t) = u(t) * v(t)$$

► The matched filter for our receiver structure with delay $T = LT_s$ should be equal to

 $v(t) = u(LT_s - t)$

► As a consequence, we need to choose pulse shape g(t) and receiver filter v(t) in such a way that

$$V(f)| = \sqrt{X_{nc}^{rc}(f)}$$
 and $|G(f)H(f)| = \sqrt{X_{nc}^{rc}(f)}$

in order to ensure a raised cosine spectrum for $X_{nc}(f) = |G(f)H(f)|^2 = |V(f)|^2 = X_{nc}^{rc}(f)$

• Hence v(t) is a pulse with root-raised cosine spectrum

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Introduction to equalizers

► We have considered the receiver structure



- When ISI occurs this receiver is suboptimal and is no longer equivalent to the ML rule (sequence estimation, Viterbi algorithm)
- Equalization: instead of tolerating the ISI in the above structure, an equalizer can be used for removing (or reducing) the effect of ISI
- Linear equalizer: zero-forcing, MMSE can be implemented by linear filters, low complexity
- Decision feedback equalizer:

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non-linear device with feedback, aims at subtracting the estimated ISI from the signal

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Introduction to equalizers

