

Answers & Hints to the exam in the course Digital Communications (ETT051), October 20, 2009, 08-13.

Problem 1.

- a) FALSE, see on-off signal pairs.
- b) FALSE, since $W_{lobe} = 3/T = 640$ kbps.
- c) TRUE, since $d_{min}^2 = 2\sin^2(\pi/64)\log_2(64) \approx 2.89 \cdot 10^{-2}$ and $P_s \approx 2Q(\sqrt{d_{min}^2 \mathcal{E}_b/N_0}) = 2Q(5.63) \approx 2 \cdot 10^{-8}$.
- d) TRUE, since QPSK has twice as high bandwidth efficiency as BPSK, and both methods have the same d_{min}^2 .
- e) FALSE, see M-FSK.

Problem 2.

$$P_b = Q(\sqrt{D^2/(2N_0)}) \leq 10^{-12} = Q(7.0345). \quad 2/T = 1.6 \cdot 10^6.$$

It is found that $D_{z_0, z_1}^2 = \alpha^2 E_g = \alpha^2 A^2 T$.

So, $D^2/(2N_0) = \alpha^2 A^2 T/(2N_0) \geq 7.0345^2$, which leads to that $A^2/N_0 \geq 7.92 \cdot 10^7/\alpha^2$.

$$\mathcal{E}_b = (E_{z_0} + E_{z_1})/2 = \alpha^2 E_g 5/2$$

$$d^2 = \alpha^2 E_g / (\alpha^2 E_g 5) = 0.2 \text{ (Independent of pulse shape.)}$$

Therefore, the energy efficiency is 10 dB worse than antipodal signal alternatives.

$d^2 \mathcal{E}_b/N_0 = d^2 P_z/(R_b N_0) \geq 7.0345^2$ leads to that $P_z/N_0 \geq 1.48 \cdot 10^8$ (Independent of pulse shape.)

If $g_{hcs}(t)$ with amplitude A and duration T_1 is used:

The same requirement on the ratio P_z/N_0 as above.

$$D_{z_0, z_1}^2 = \alpha^2 E_g = \alpha^2 A^2 T_1/2, \text{ and } 3/T_1 = 1.6 \cdot 10^6 \text{ leads to that } A^2/N_0 \geq 7.0345^2 \cdot 1.6 \cdot 10^6 \cdot 4/(3\alpha^2) = 1.06 \cdot 10^8/\alpha^2.$$

Problem 3.

$$d_{min}^2 \mathcal{E}_b/N_0 = 6\log_2(M)/(M^2 - 1) \cdot P_z/(R_b N_0) = 6/(M^2 - 1) \cdot T_s P_z/N_0.$$

If $M = 8$ it is given that $6/63 \cdot T_s P_z/N_0 = 169.03^2$, which implies that $T_s P_z/N_0 = 3 \cdot 10^5$.

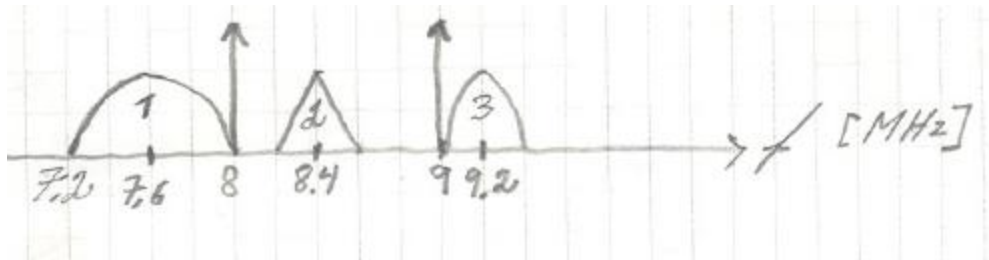
The bit error probability requirement leads to that: $6/(M^2 - 1) \cdot T_s P_z/N_0 \geq 6.706^2$ from which we obtain that $M \leq 200.07$. Hence, $M = 128$ and $R_b = 7/T_s$.

M-QAM has higher d_{min}^2 than M-PAM.

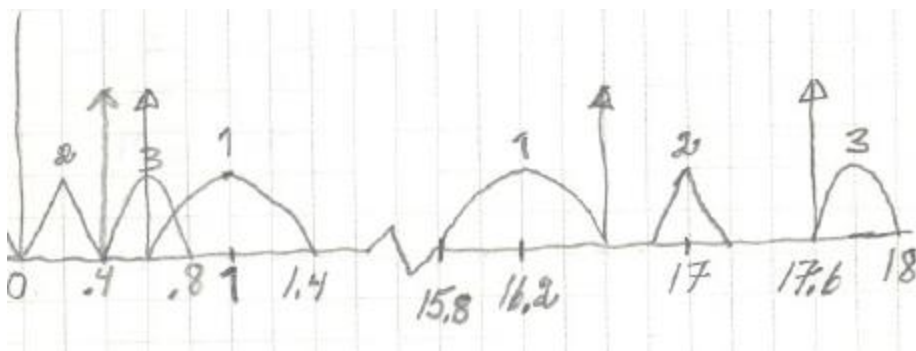
Problem 4.

a)

r(t): (Symmetry around f=0)



y(t): (Symmetry around f=0)



The choice of 8.6 MHz in the receiver is a bad choice. It should be 7.6, 8.4 or 9.2 (MHz), then the corresponding user signal will be found around the frequency f=0.

b) See the compendium.

Problem 5.

a)

$$D_{0,1}^2 = 4E. \text{ All the other squared Euclidean distances} = 2E = D_{min}^2.$$

$$c = ((2 + 3 + 3 + 2)/4 = 2.5, \text{ and } c_1 = (1 + 0 + 0 + 1)/4 = 1/2.$$

$$\text{Hence, the union bound} = 2.5Q(\sqrt{E/N_0}) + 0.5Q(\sqrt{2E/N_0}).$$

At high signal-to-noise ratios the union bound is very good and it is then approximately equal to $cQ(\sqrt{D_{min}^2/(2N_0)})$. At low signal-to-noise ratios the union bound can be much larger than the true P_s , making it less useful.

b)

We can use the correlation receiver in figure 4.10 in the compendium with:

$$z_1(t) - z_0(t) = 2\alpha g_{rec}(t) - \alpha g_{rec}(t) = \alpha g_{rec}(t).$$

$$\text{Integration time} = T = 2/(1.6 \cdot 10^6),$$

$$\text{and decision threshold} = (E_{z_1} - E_{z_0})/2 = 3\alpha^2 A^2 T/2.$$