

EITF75 Systems and Signals

Lecture 10

The Discrete Fourier transform

...or...

Honey, I shrank the Discrete-time Fourier Transform

Fredrik Rusek

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Background and motivation for yet another transform

For discrete-time systems, we have treated two transforms:

1. The z-transform

Good for solving difference equations

Good for algebraic analysis of systems

Limited insight from plotting

2. The discrete-time Fourier transform (DTFT)

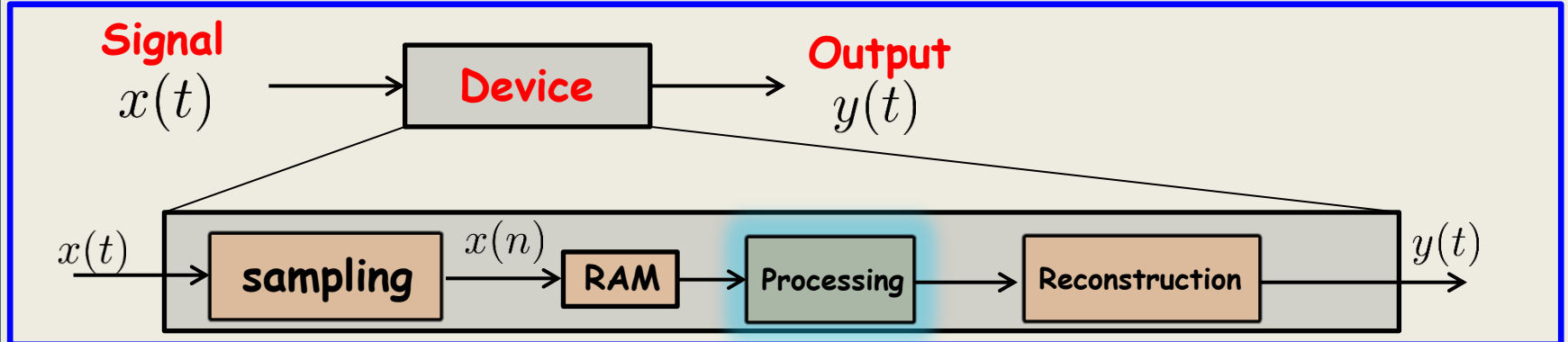
Excellent for understanding characteristics of systems

Insights from plotting

Relates to reality (bandwidth)

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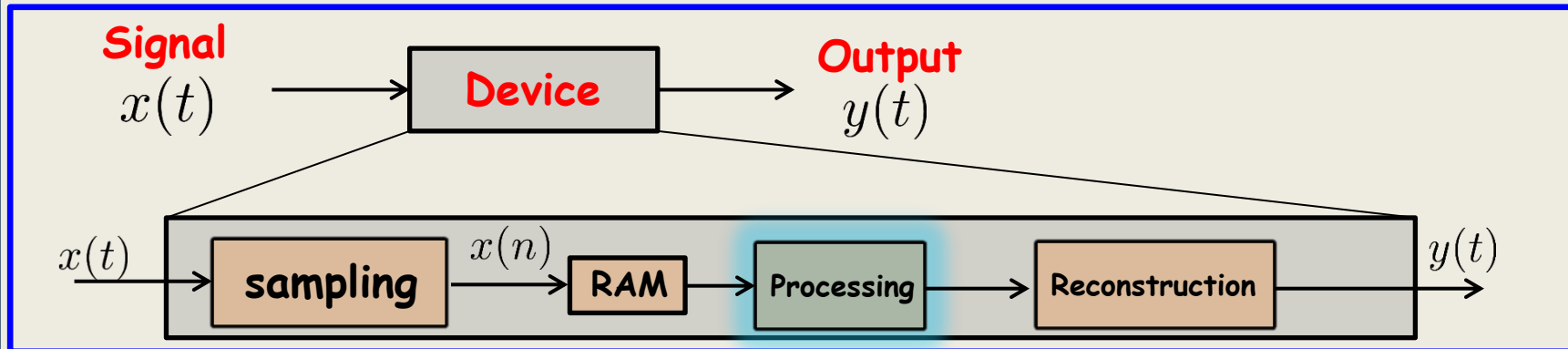
Background and motivation for yet another transform



Consider the Processing module. It should process the signal according to the application at hand. (Can be more than a filter, for example an entire C/C++ program)

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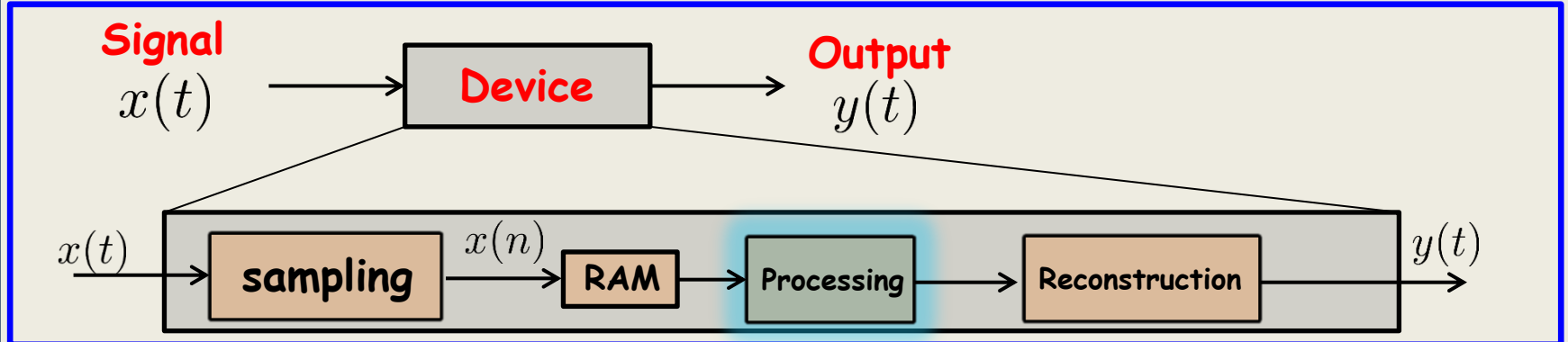


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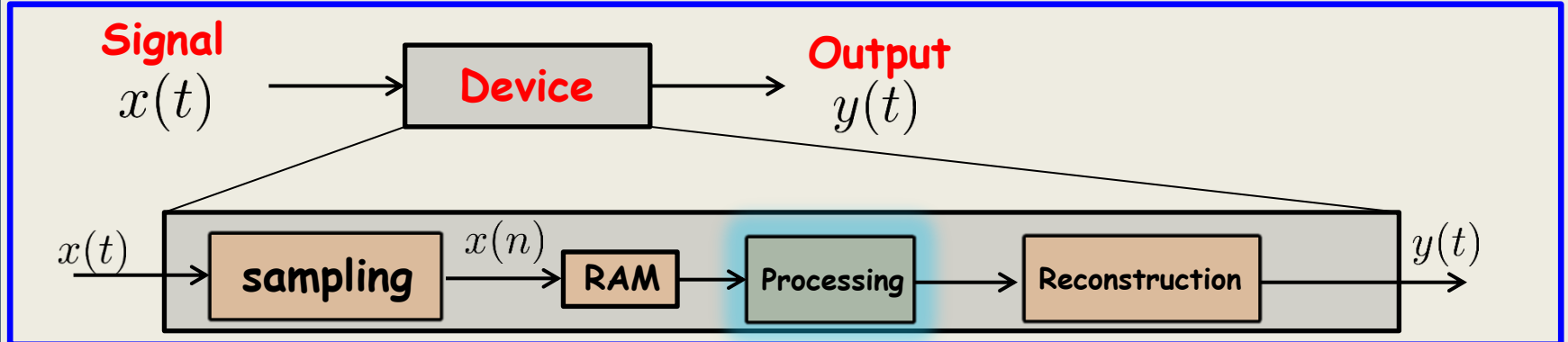
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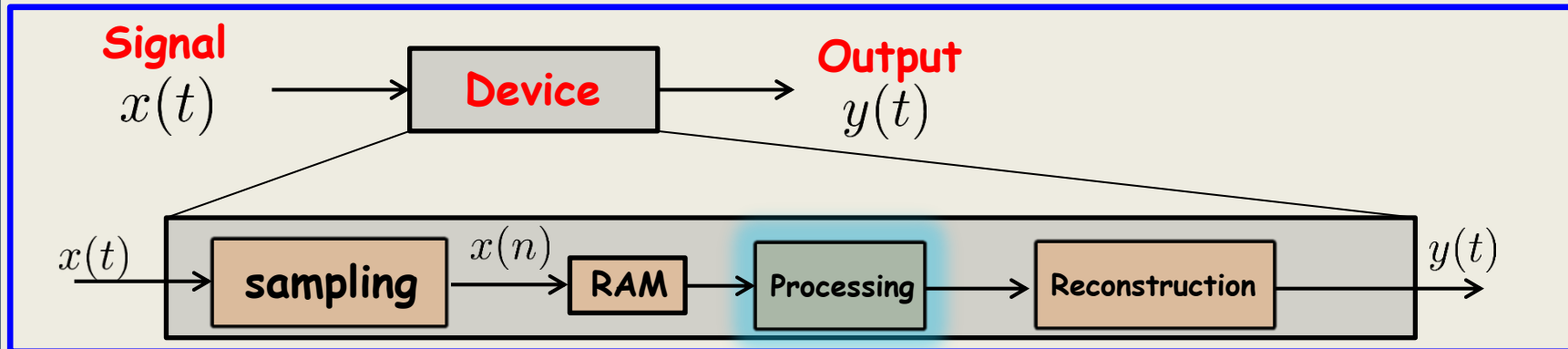
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Hint: Why couldn't a digital processor use $x(t)$ directly?

Because it is continuous, and a processor is digital

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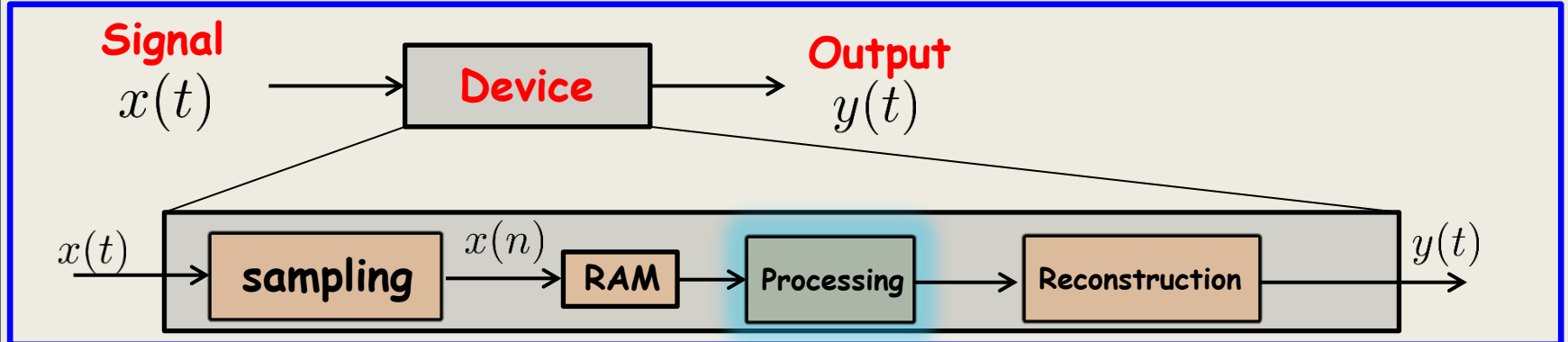
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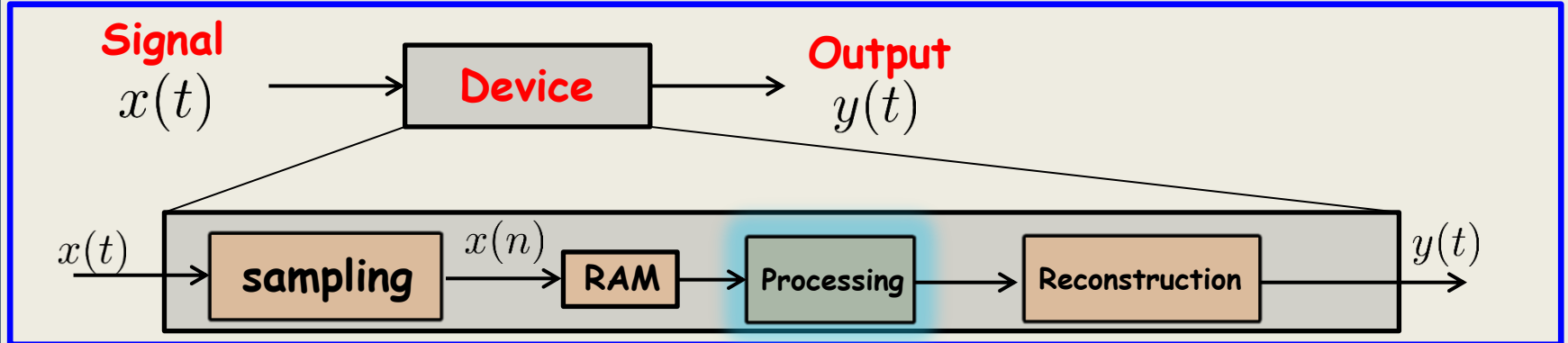
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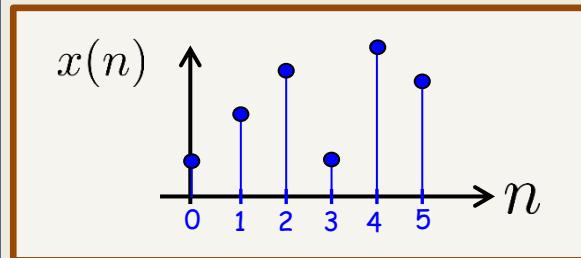
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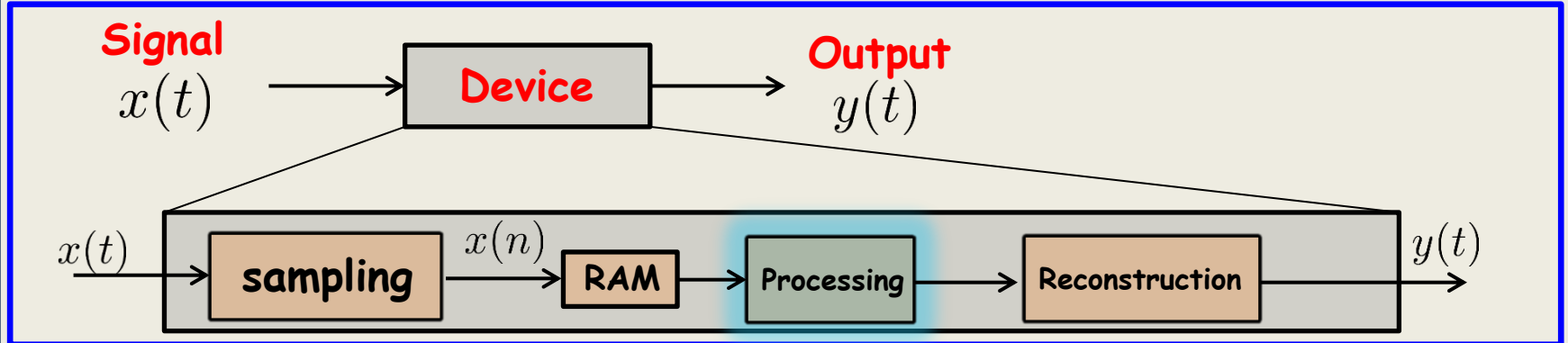
Besides, the DTFT is terribly inefficient



These 6 numbers, are in the frequency domain represented by...

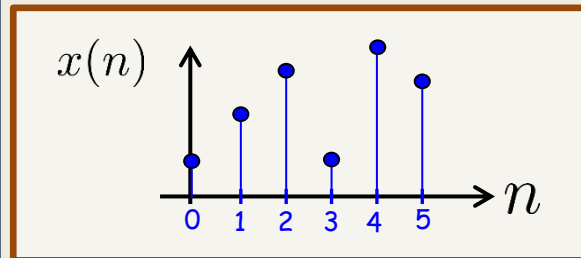
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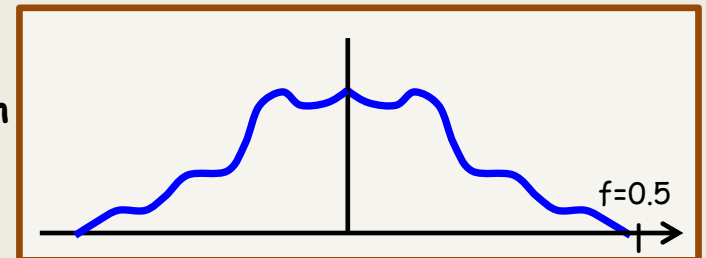


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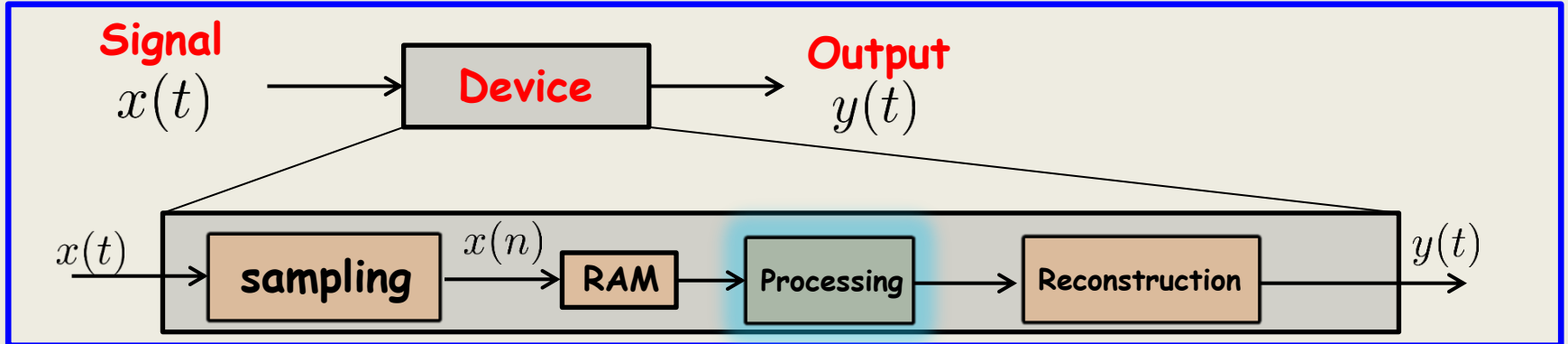


These 6 numbers, are in the frequency domain represented by a **continuous** curve !



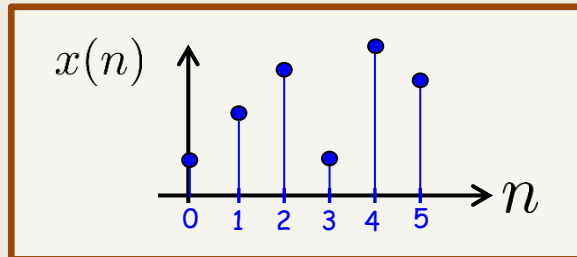
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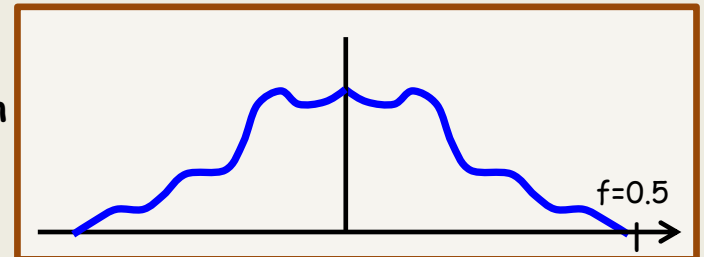
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It should be possible to Fourier represent $x(n]$ by 6 numbers as well



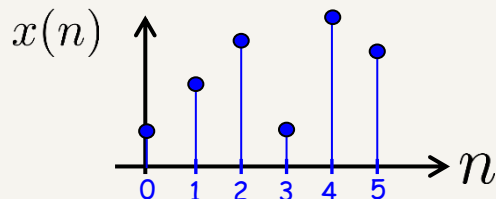
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Background and motivation for yet another transform

The discrete Fourier Transform (DFT) in one sentence:
A Fourier version of $x(n)$ with 6 numbers

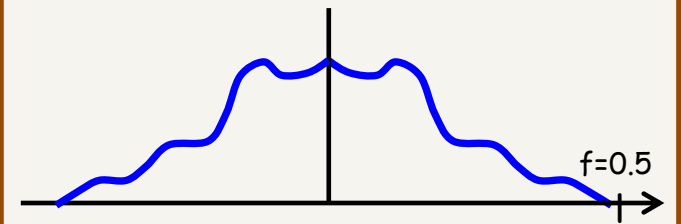
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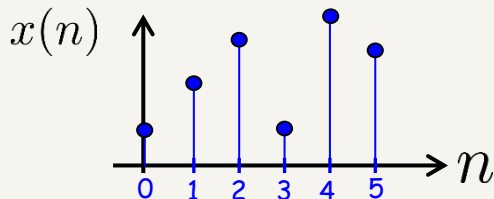
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Honey, I shrank the Discrete-time Fourier Transform

↑
Easy to remember: Less words, less numbers

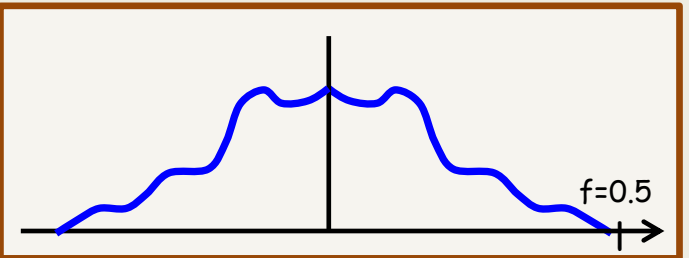
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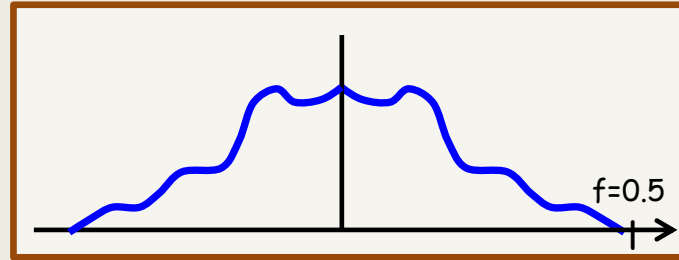
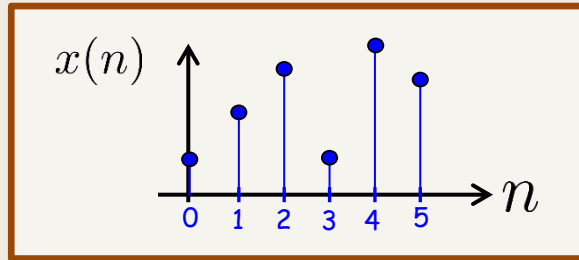


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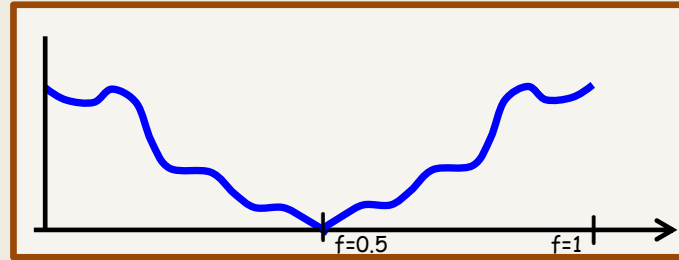
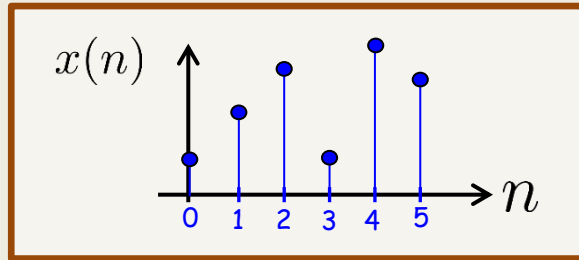


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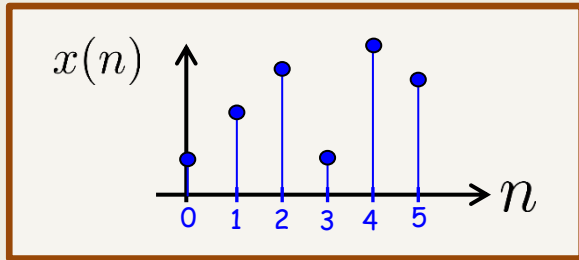
The DTFT is periodic

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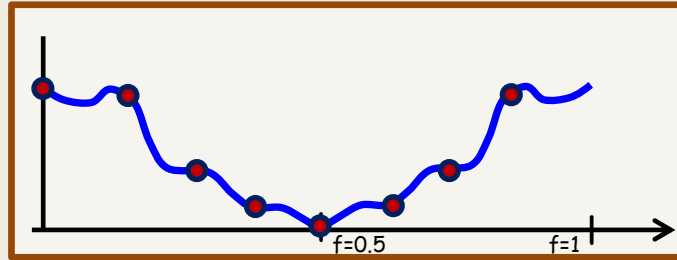


We can represent it like this

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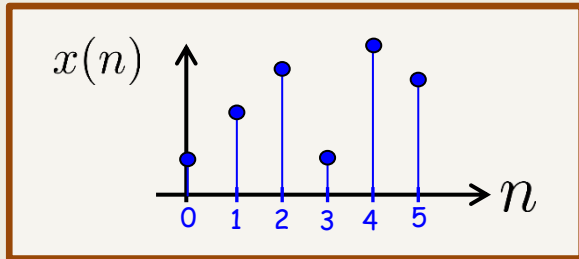


We don't assume N taps in $x(n]$

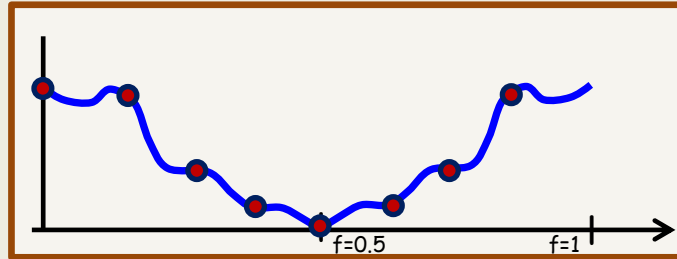


Assume that we take N samples of the DTFT

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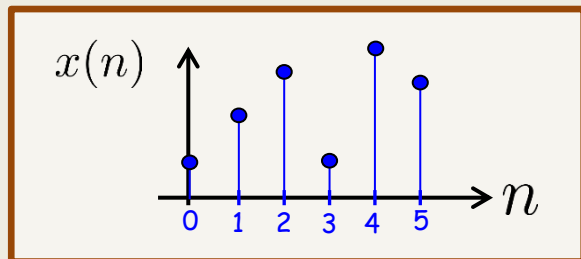


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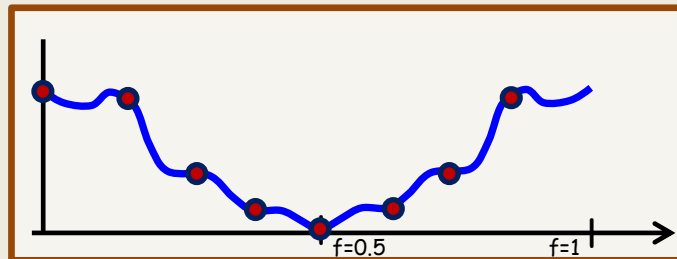
$$X(f) = \sum_{n=-\infty}^{\infty} x(n)e^{-i2\pi n f}$$

Formula for DTFT

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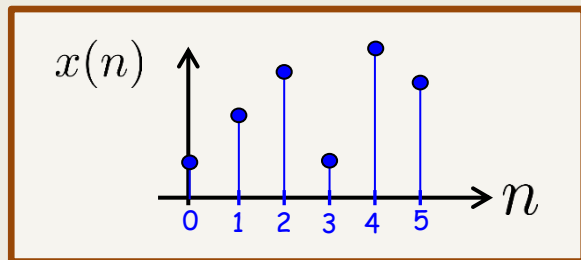
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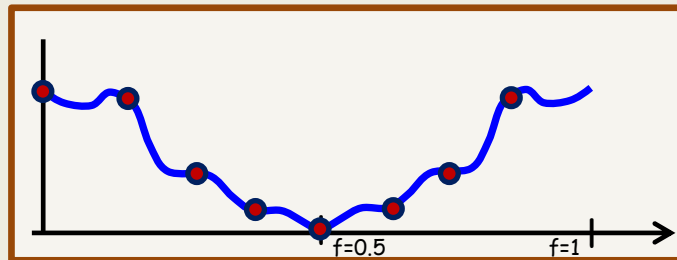
Samples located at $f = \frac{k}{N}$

$$k = 0, 1, \dots, N - 1$$

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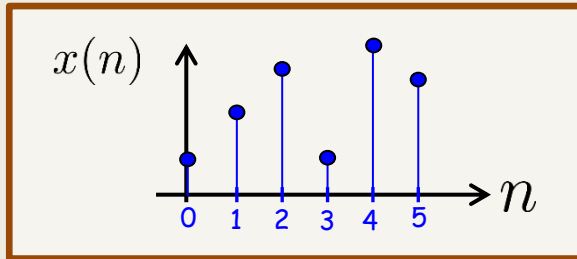
Formula for samples

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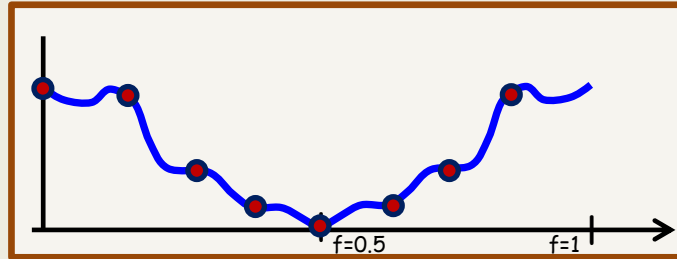
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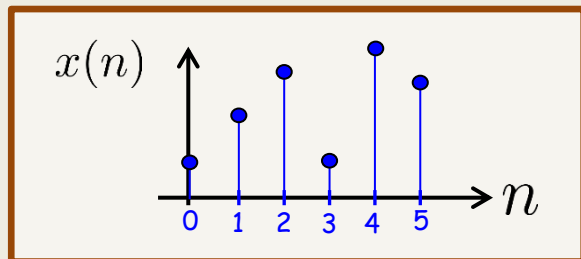
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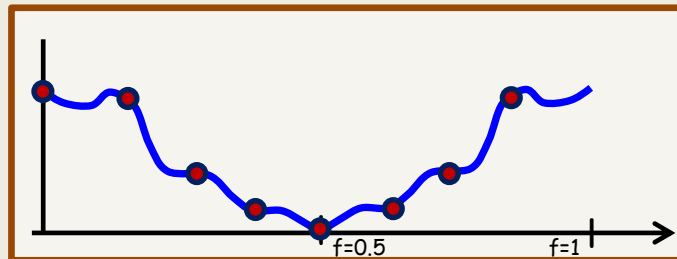
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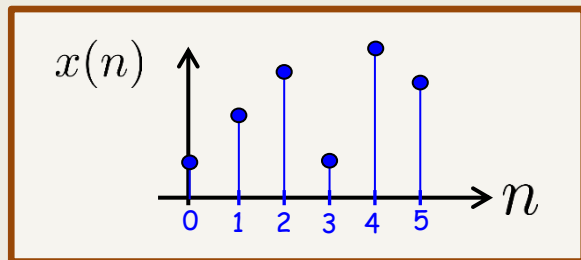
Let us try to invert using this formula

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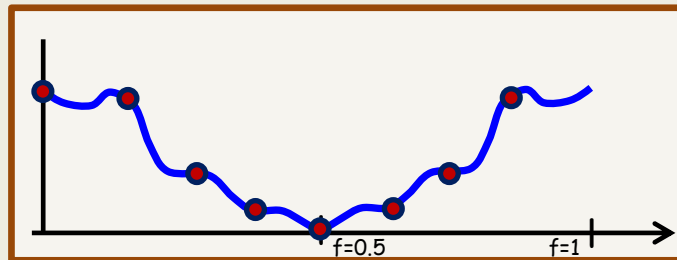
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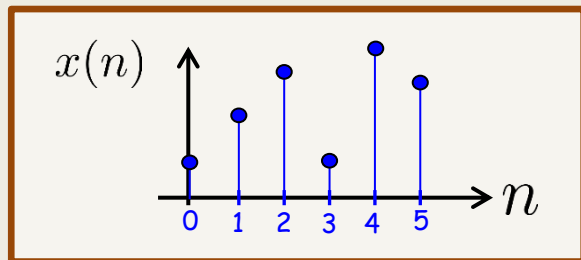
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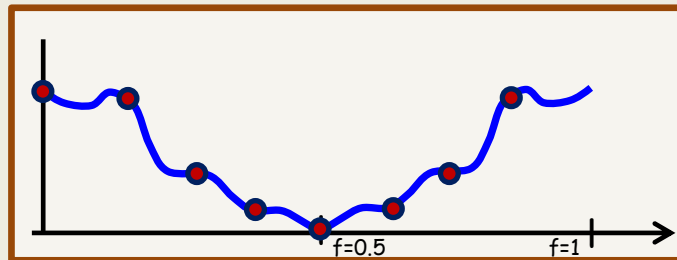
Plug in

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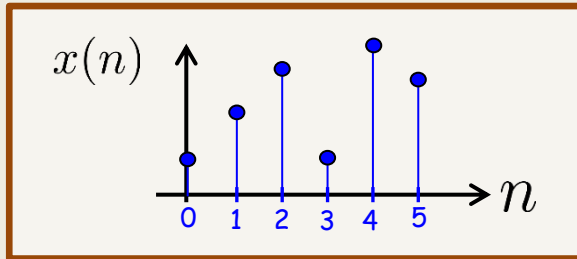
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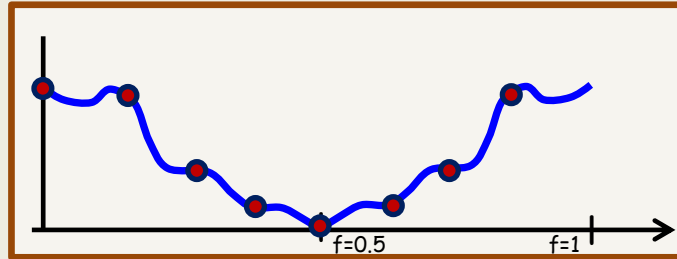
Standard approach when facing two sums ?

If samples are representing $X(f)$, then we should be able to get $x(n)$ back from them

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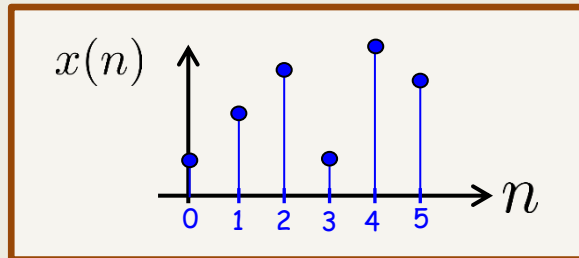
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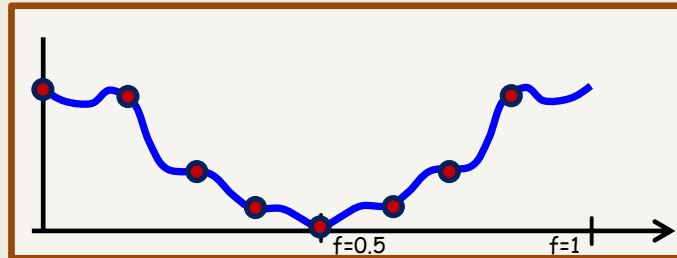
Switch order

If samples are representing $X(f)$, then we should be able to get $x(n)$ back from them

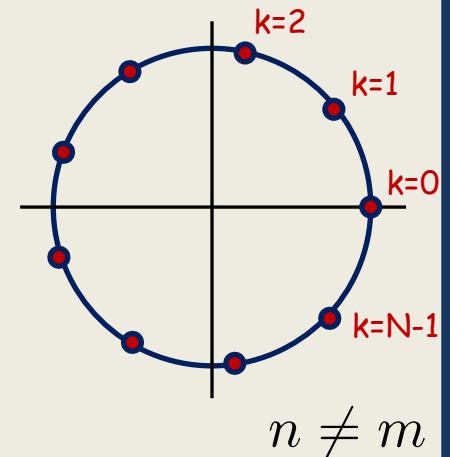
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We don't assume N taps in $x(n)$



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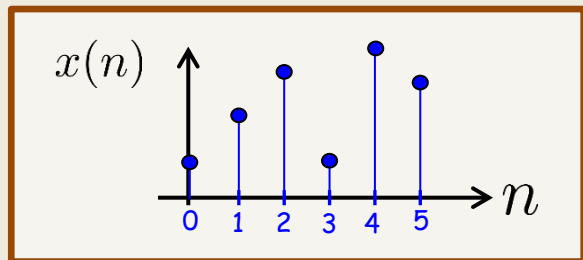
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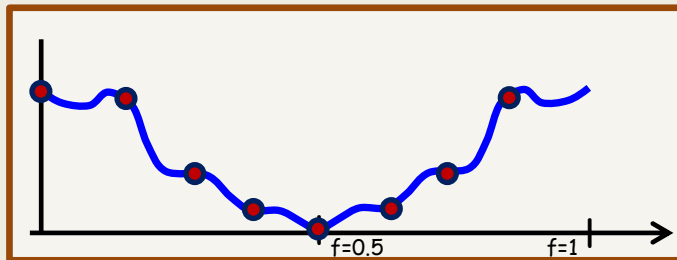
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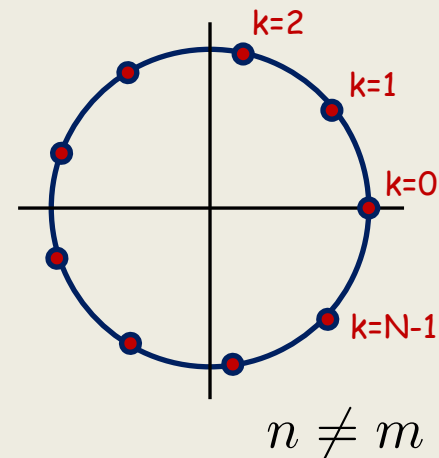
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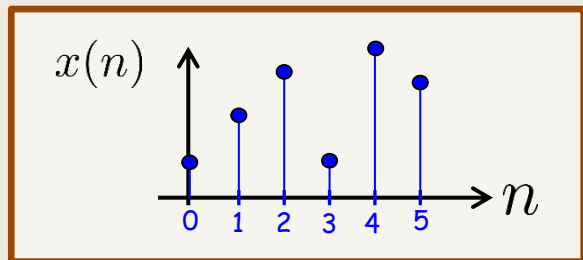
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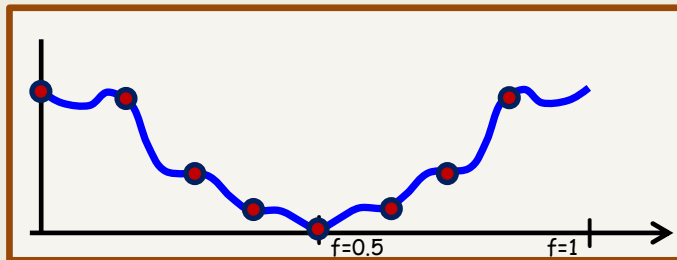
= 0

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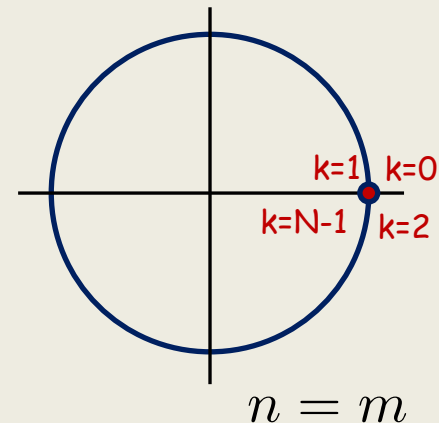
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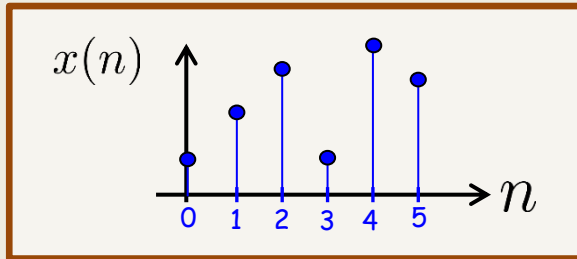
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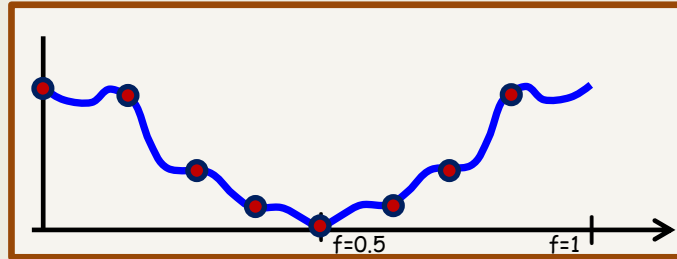
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We don't assume N taps in $x(n]$



Assume that we take N samples of the DTFT

Let us try to invert using this formula

$$x(n) \stackrel{?}{=} \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \frac{1}{N} \cdot \sum_{k=0}^{N-1} \sum_{m=-\infty}^{\infty} x(m) e^{-j2\pi \cdot \frac{m}{N} \cdot k} \cdot e^{j2\pi \cdot \frac{n}{N} \cdot k}$$

$$X(k) = \sum_{m=-\infty}^{\infty} x(m) e^{-i2\pi mk/N}$$

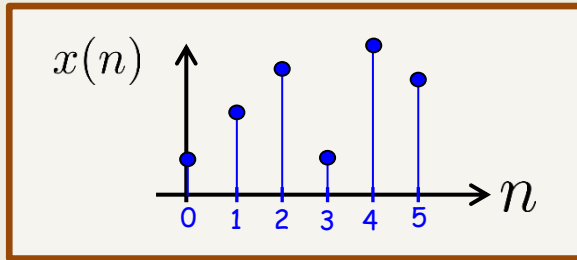
$$= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot \sum_{k=0}^{N-1} e^{j2\pi \cdot \frac{n-m}{N} \cdot k}$$

$$= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot N \cdot \delta(n - m \mod N)$$

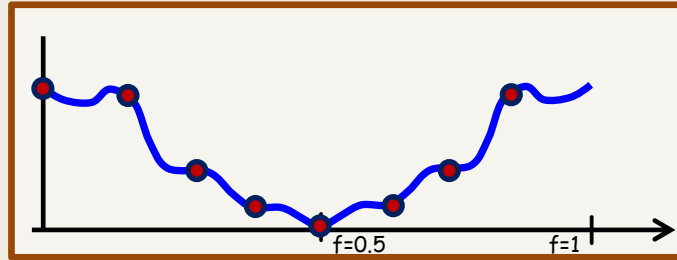
If samples are representing $X(f)$, then we should be able to get $x(n]$ back from them

Compact notation.

EITF75 Systems and Signals



We don't assume N taps in $x(n)$



Assume that we take N samples of the DTFT

In general $x(n) \neq \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \frac{1}{N} \cdot \sum_{k=0}^{N-1} \sum_{m=-\infty}^{\infty} x(m) e^{-j2\pi \cdot \frac{m}{N} \cdot k} \cdot e^{j2\pi \cdot \frac{n}{N} \cdot k}$

$$X(k) = \sum_{m=-\infty}^{\infty} x(m) e^{-i2\pi mk/N}$$

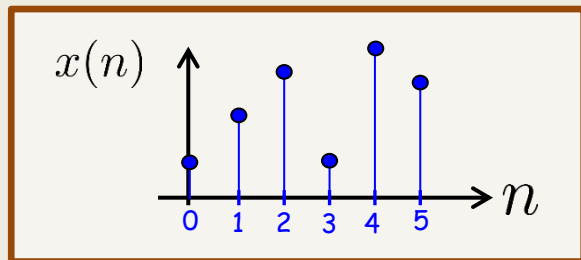
$$= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot \sum_{k=0}^{N-1} e^{j2\pi \cdot \frac{n-m}{N} \cdot k}$$

$$= \frac{1}{N} \cdot \sum_{m=-\infty}^{\infty} x(m) \cdot N \cdot \delta(n - m \mod N)$$

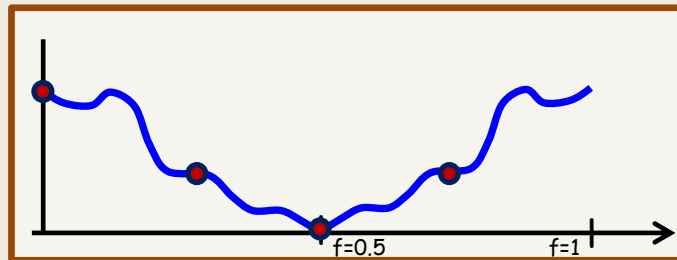
If samples are representing $X(f)$, then we should be able to get $x(n)$ back from them

$$= \sum_{m=-\infty}^{\infty} x(n - mN)$$

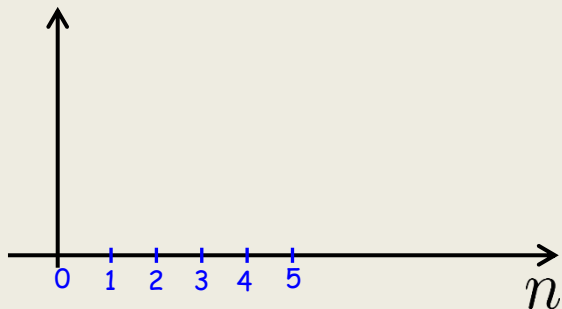
EITF75 Systems and Signals



There are 6 taps here



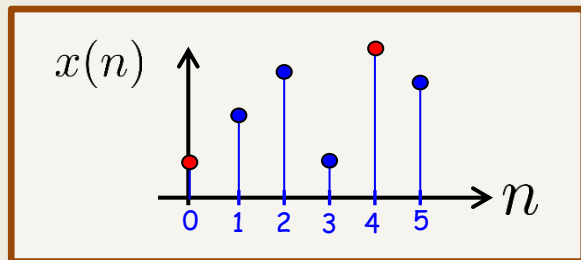
Assume that we take $N=4$ samples of the DTFT



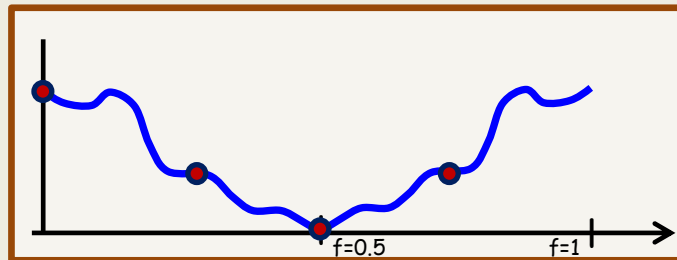
Let us plot this

$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

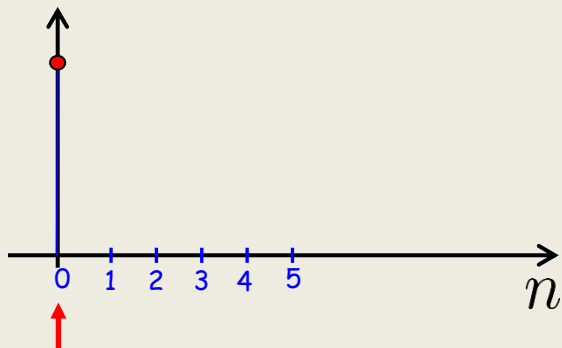
EITF75 Systems and Signals



There are 6 taps here

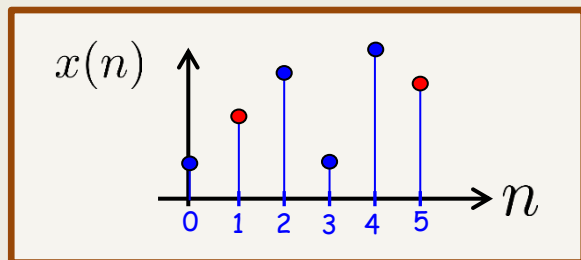


Assume that we take $N=4$ samples of the DTFT

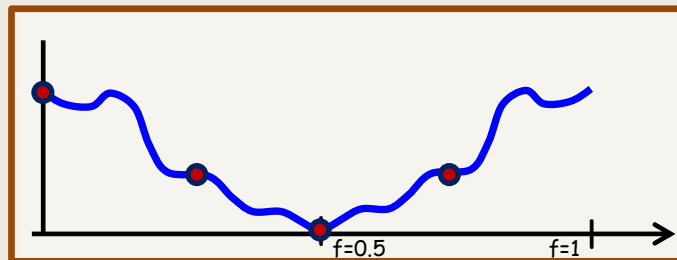


$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN) \quad x(0) + x(4)$$

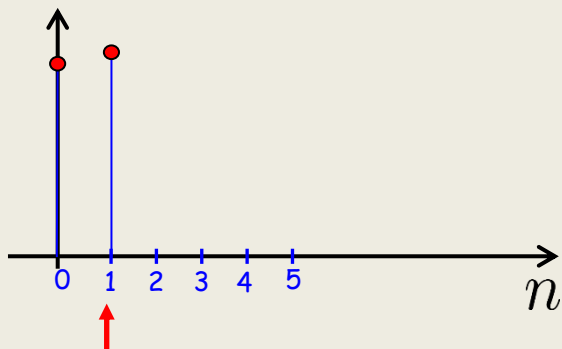
EITF75 Systems and Signals



There are 6 taps here

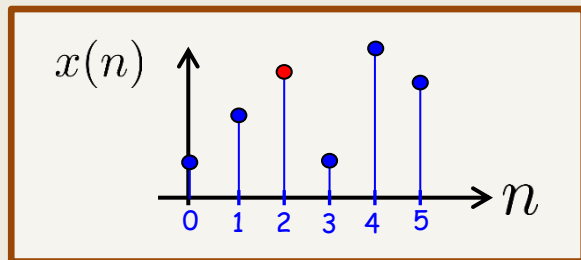


Assume that we take $N=4$ samples of the DTFT

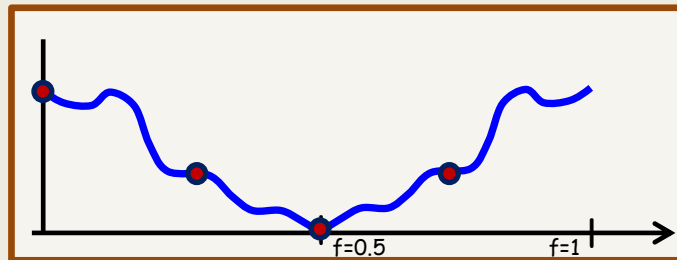


$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN) \quad x(1) + x(5)$$

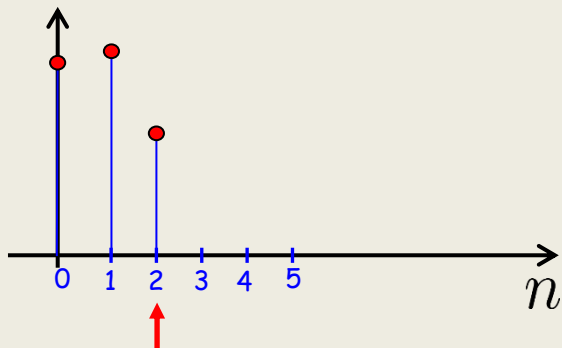
EITF75 Systems and Signals



There are 6 taps here



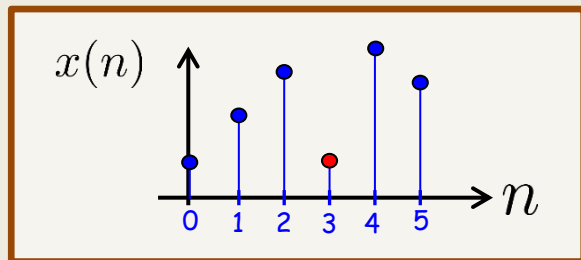
Assume that we take $N=4$ samples of the DTFT



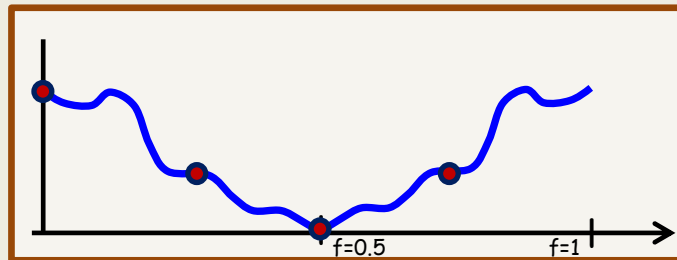
$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

$$x(\cancel{-2}) + x(2) + x(\cancel{6})$$

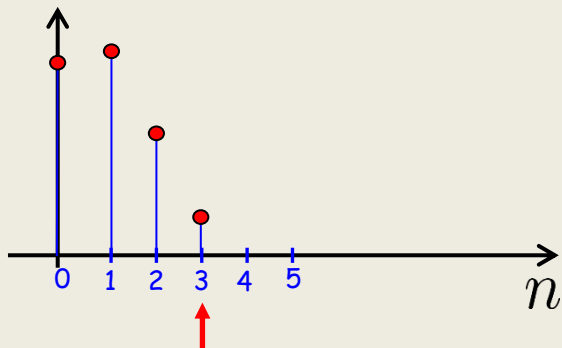
EITF75 Systems and Signals



There are 6 taps here



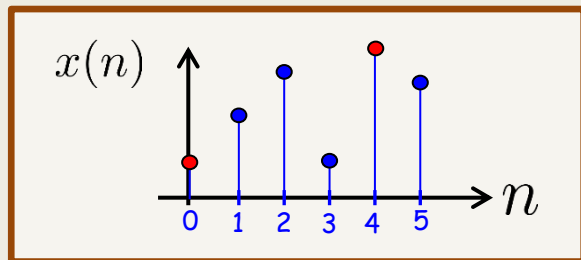
Assume that we take $N=4$ samples of the DTFT



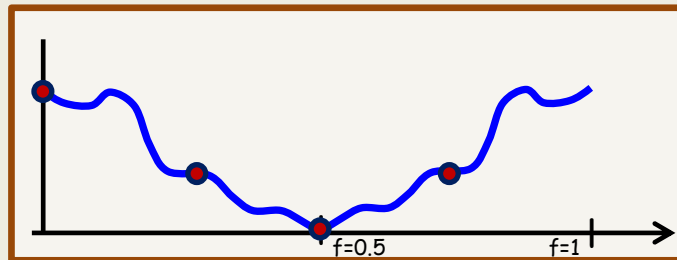
$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

$x(3)$

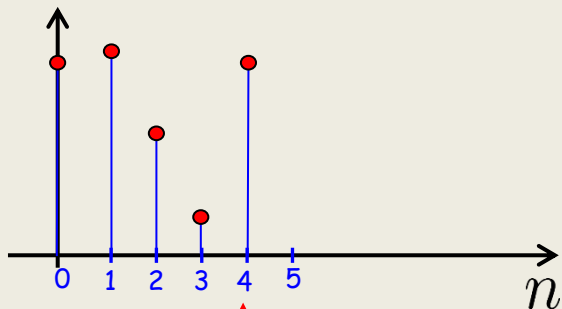
EITF75 Systems and Signals



There are 6 taps here

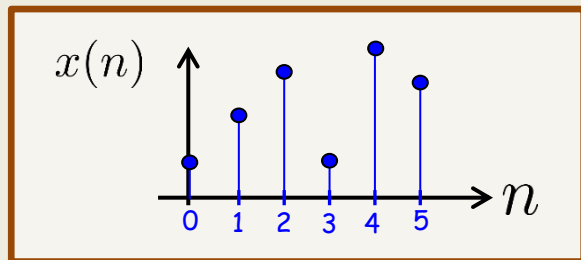


Assume that we take $N=4$ samples of the DTFT

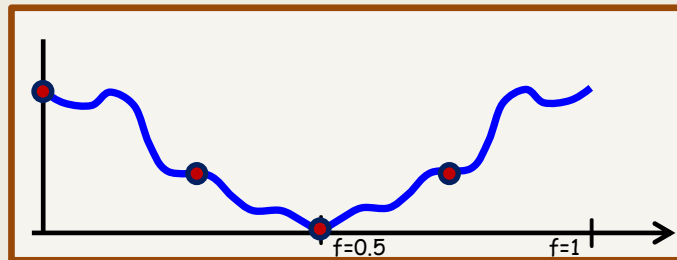


$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN) \quad x(0) + x(4)$$

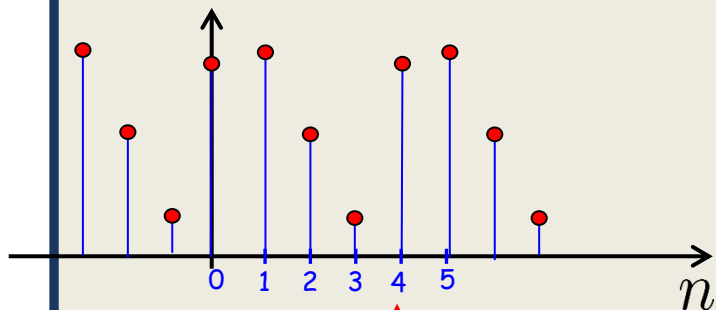
EITF75 Systems and Signals



There are 6 taps here



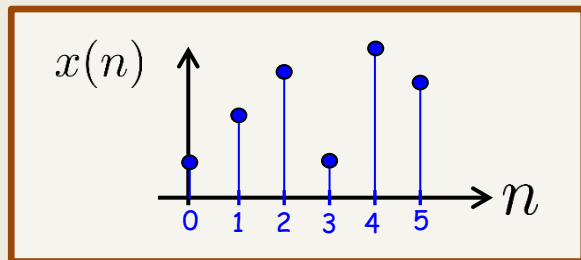
Assume that we take $N=4$ samples of the DTFT



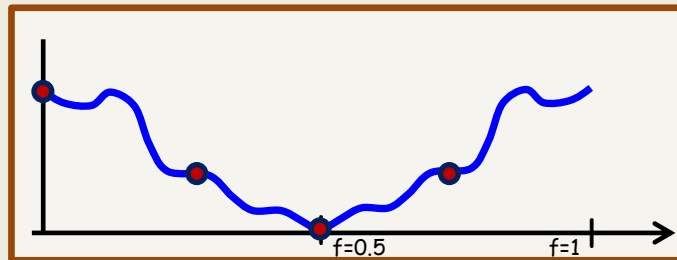
Periodic sequence

$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

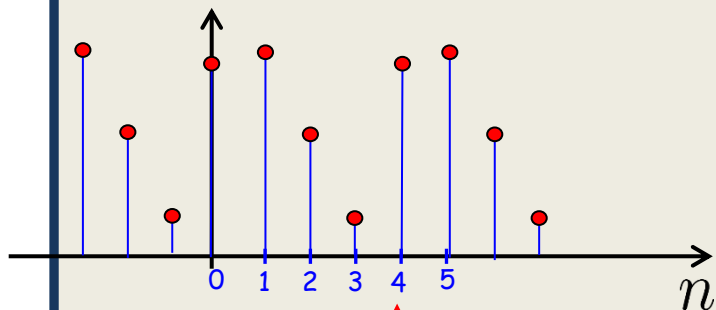
EITF75 Systems and Signals



There are 6 taps here



Assume that we take $N=4$ samples of the DTFT

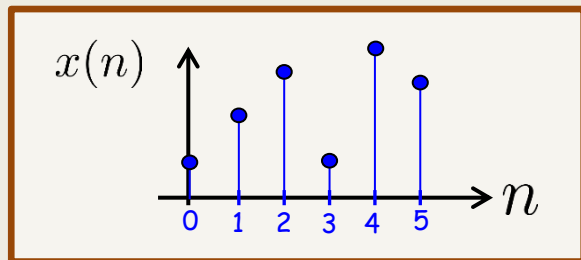


Periodic sequence

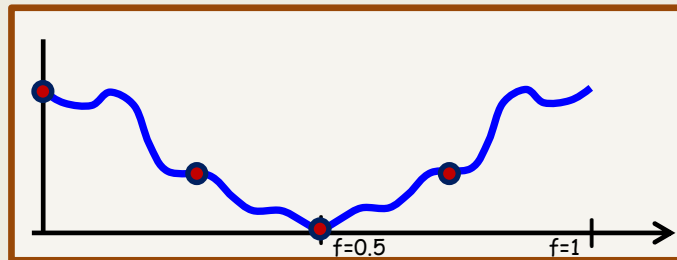
Not equal to $x(n]$

$$x(n) \neq \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

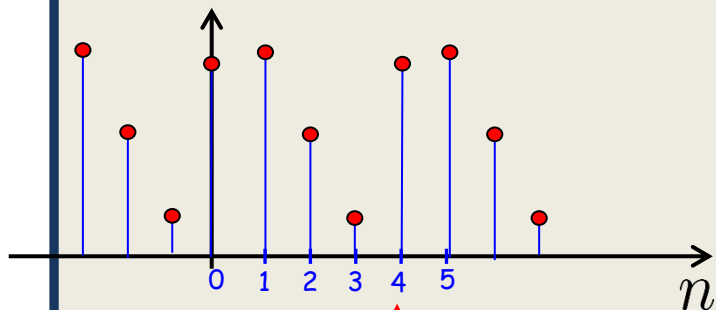
EITF75 Systems and Signals



There are 6 taps here



Assume that we take $N=4$ samples of the DTFT



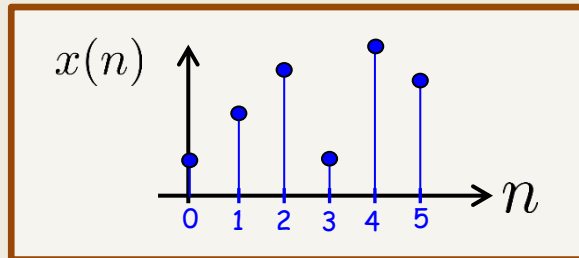
Periodic sequence

Not equal to $x(n)$

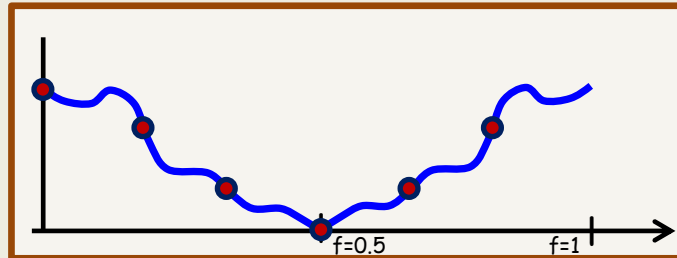
Samples not enough to represent $X(f)$ or $X(n)$

$$x(n) \neq \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

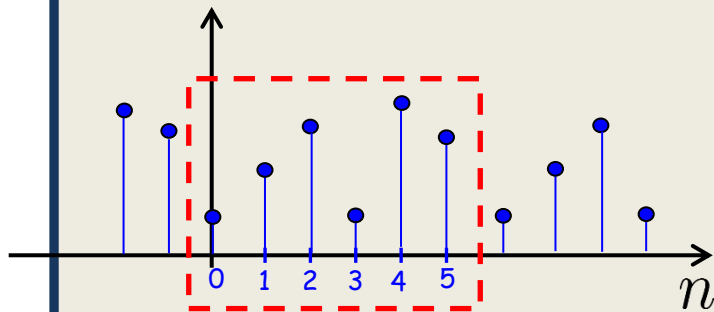
EITF75 Systems and Signals



There are 6 taps here



Assume that we take $N=6$ samples of the DTFT



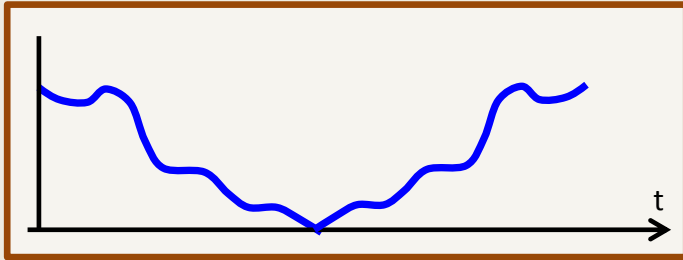
Periodic sequence

$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k} = \sum_{m=-\infty}^{\infty} x(n - mN)$$

Samples enough to represent $X(f)$ and $X(n)$
($m=0$ only term)

EITF75 Systems and Signals

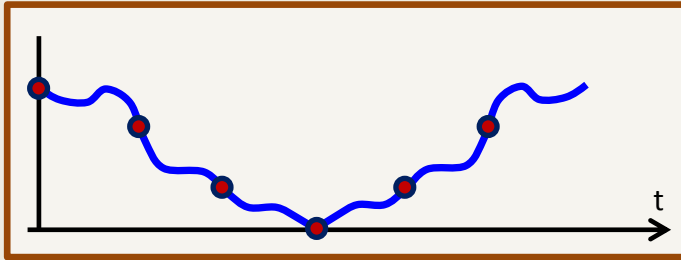
Not strange



Assume a **time-signal**

EITF75 Systems and Signals

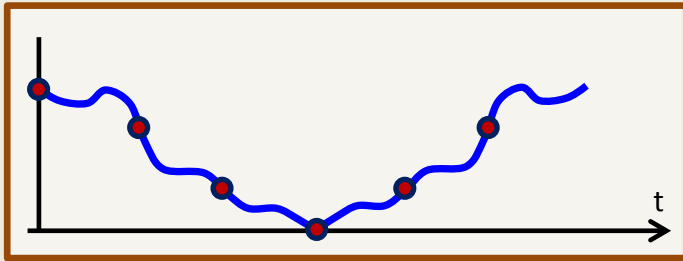
Not strange



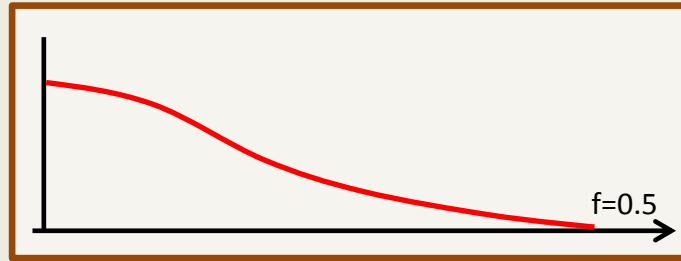
Sample it

EITF75 Systems and Signals

Not strange



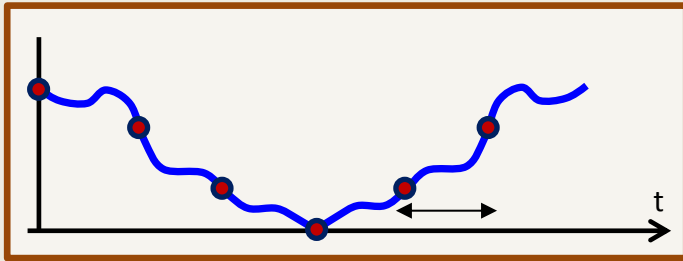
Sample it



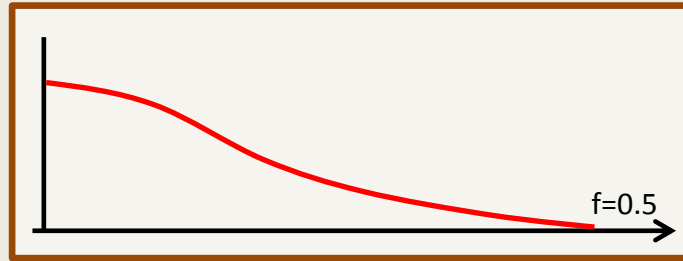
Compute the "other domain"
representation from samples
In this case, the Fourier domain

EITF75 Systems and Signals

Not strange



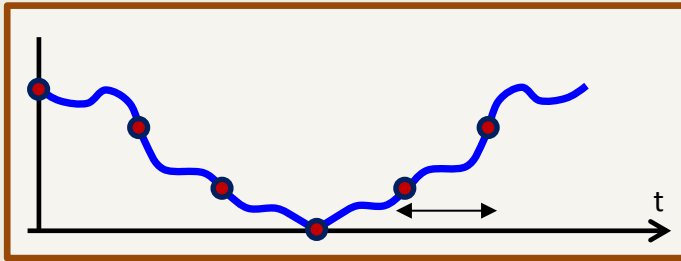
But if sample
spacing is too small...



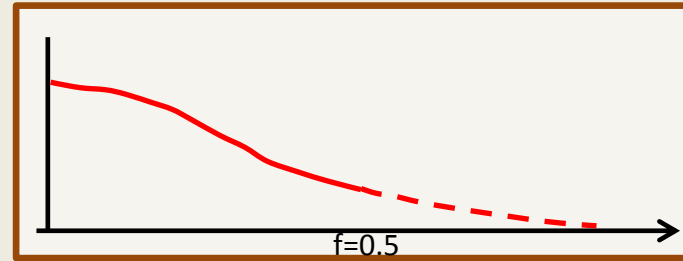
Compute the "other domain"
representation from samples
In this case, the Fourier domain

EITF75 Systems and Signals

Not strange



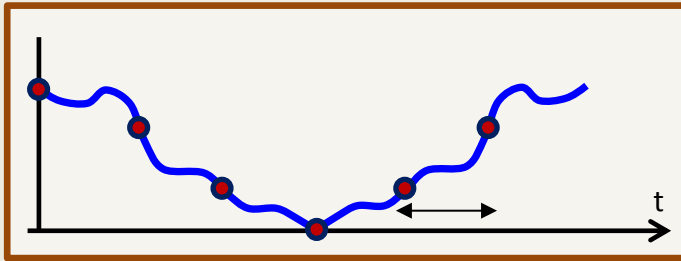
But if sample
spacing is too small...



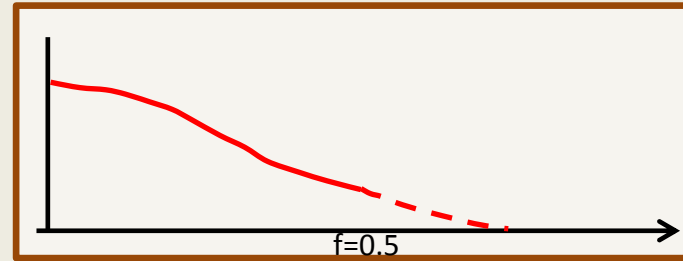
There is aliasing

EITF75 Systems and Signals

Not strange



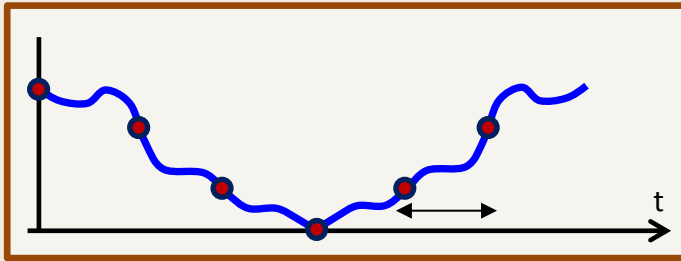
But if sample
spacing is too small...



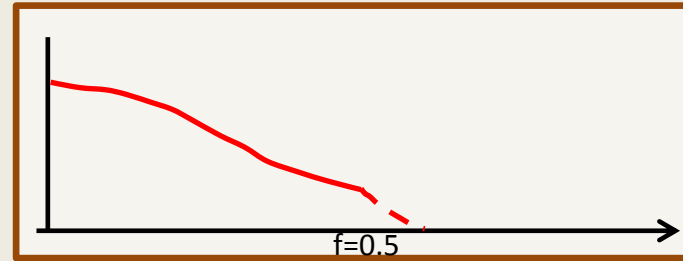
There is aliasing

EITF75 Systems and Signals

Not strange



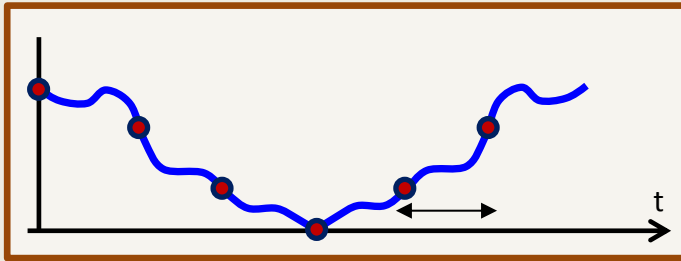
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spacing is too small...



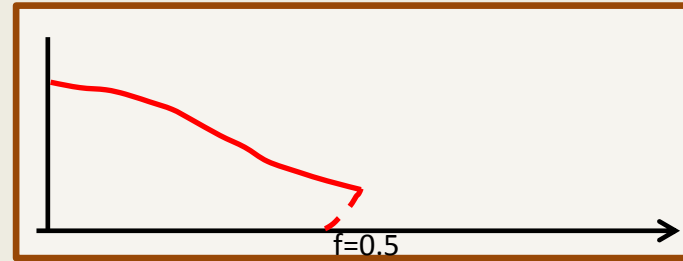
There is aliasing

EITF75 Systems and Signals

Not strange



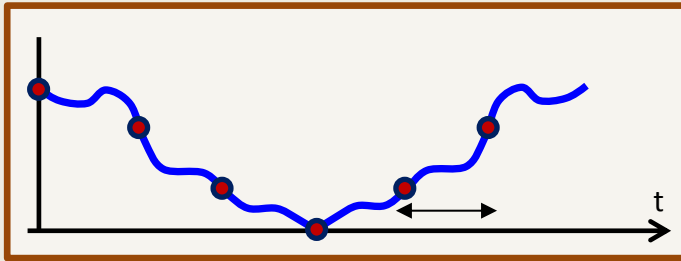
But if sample
spacing is too small...



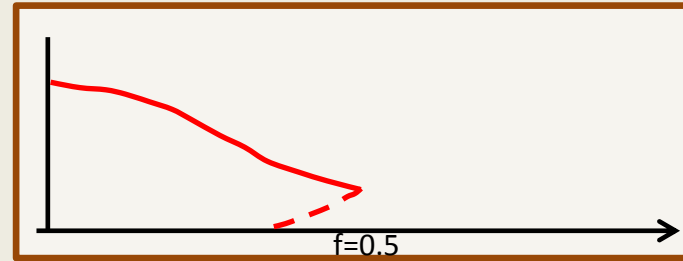
There is aliasing

EITF75 Systems and Signals

Not strange



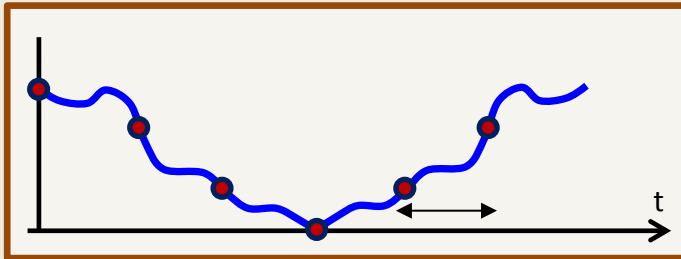
But if sample
spacing is too small...



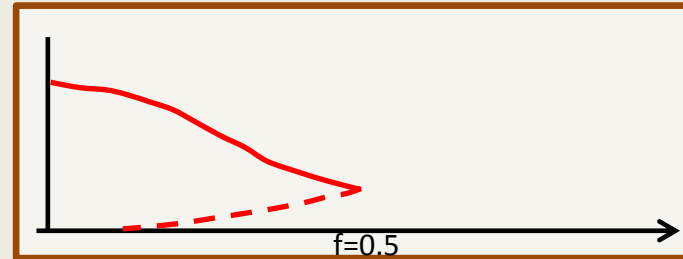
There is aliasing

EITF75 Systems and Signals

Not strange



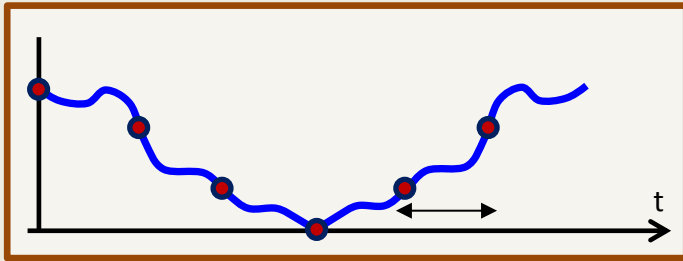
But if sample
spacing is too small...



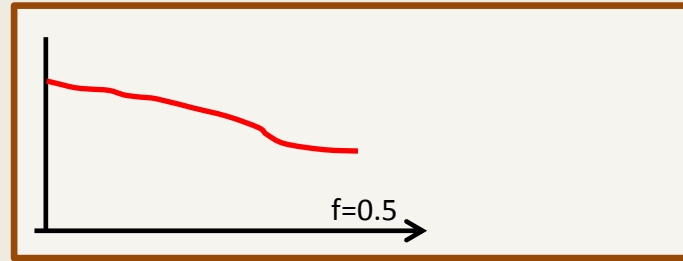
There is aliasing

EITF75 Systems and Signals

Not strange



But if sample
spacing is too small...



There is aliasing

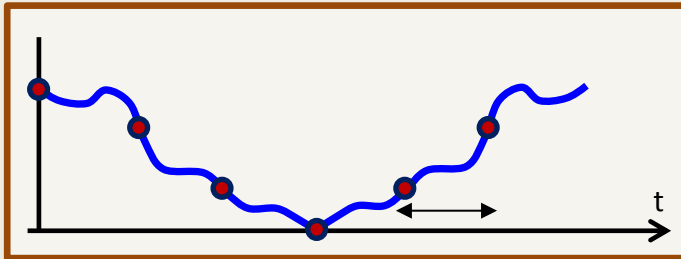
Aliasing

No aliasing

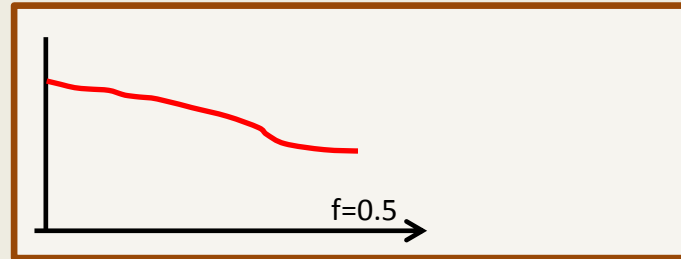
$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

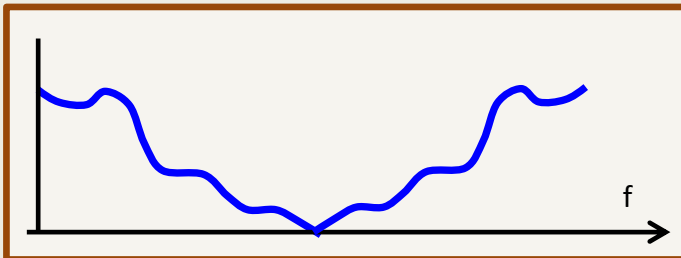


There is aliasing

Aliasing

No aliasing

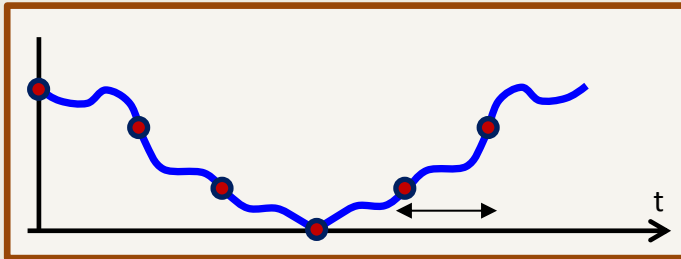
$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$



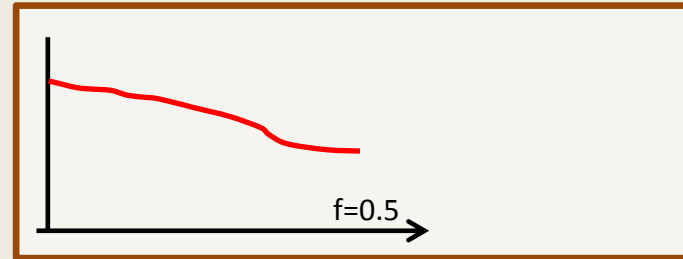
Assume a **frequency-signal**

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

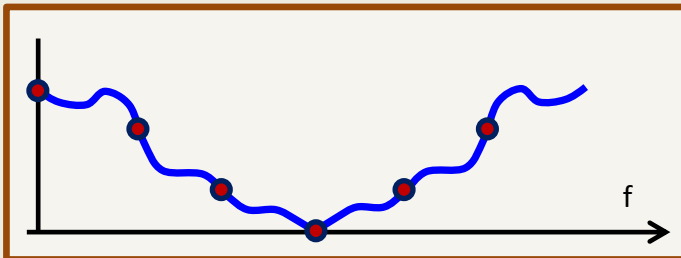


There is aliasing

Aliasing

No aliasing

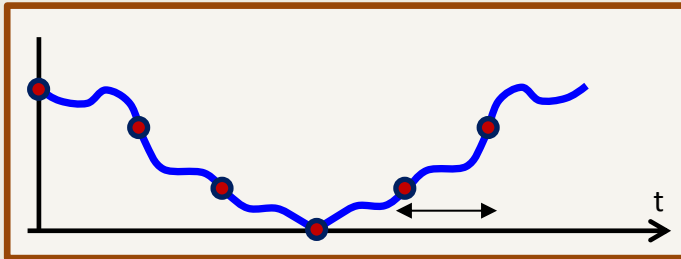
$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$



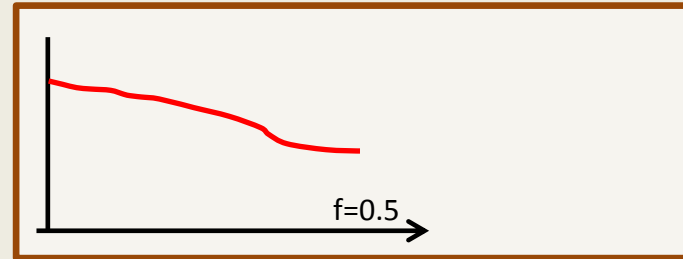
Sample it

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

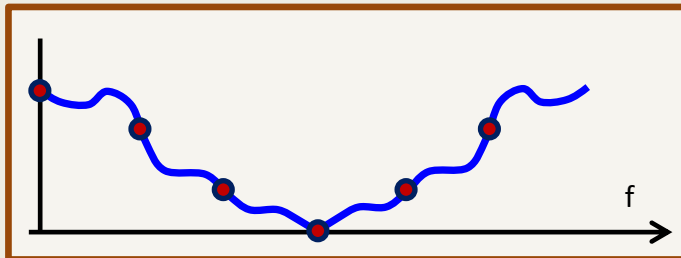


There is aliasing

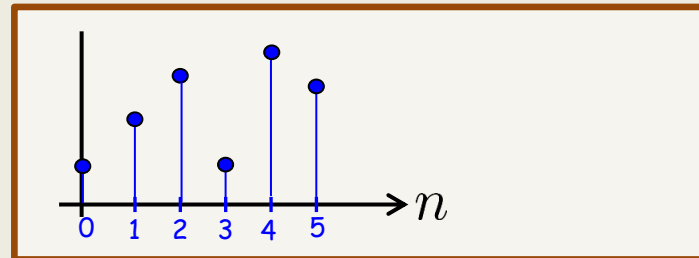
Aliasing

No aliasing

$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$



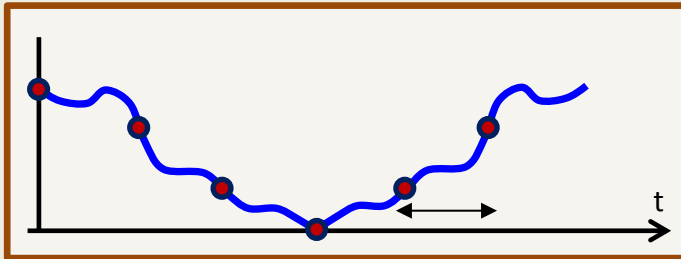
Sample it



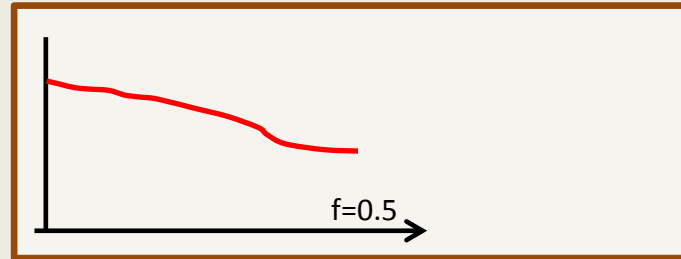
Compute the "other domain" representation from samples. **In this case, the time domain**

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

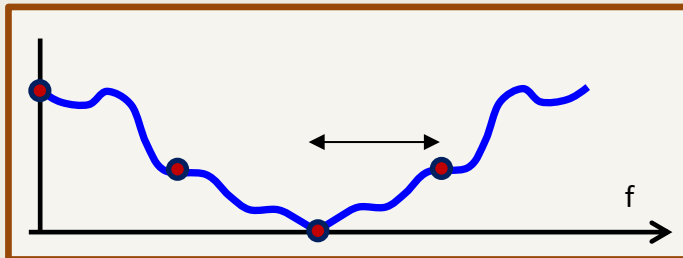


There is aliasing

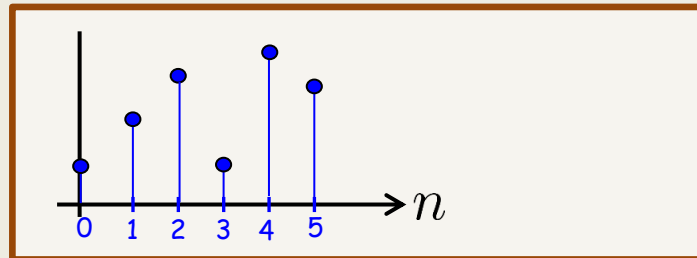
Aliasing

No aliasing

$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$



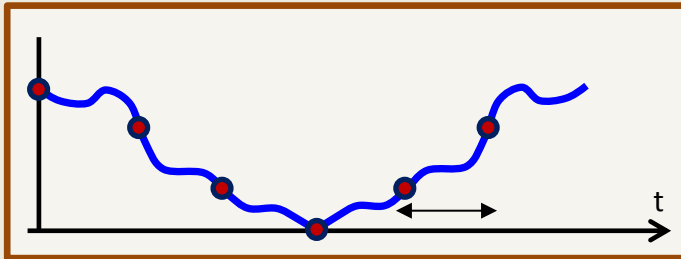
But if sample spacing is too small...



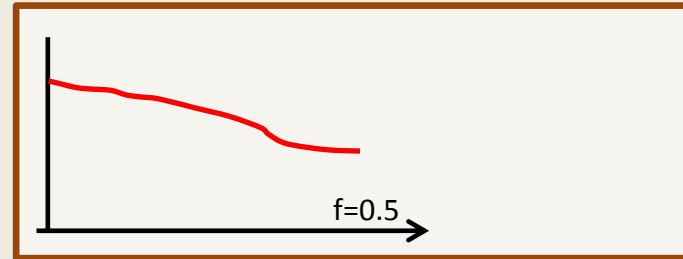
Compute the "other domain" representation from samples. **In this case, the time domain**

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

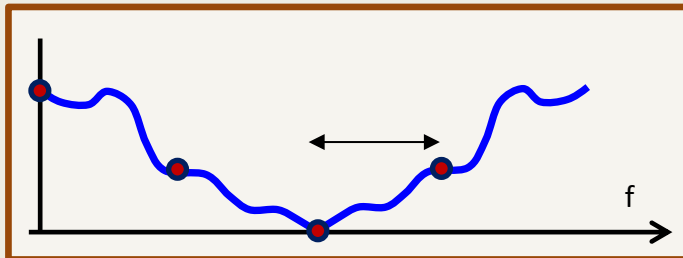


There is aliasing

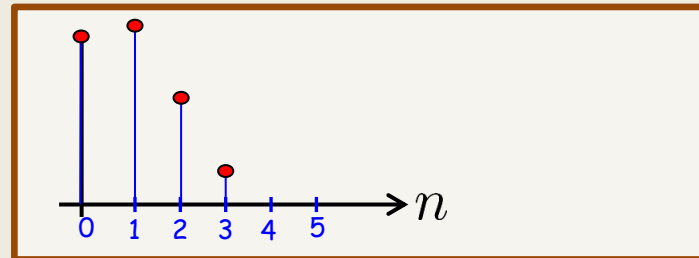
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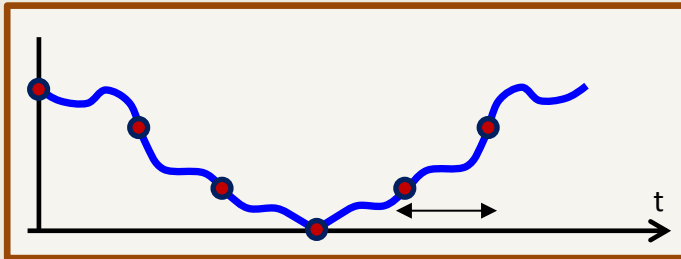
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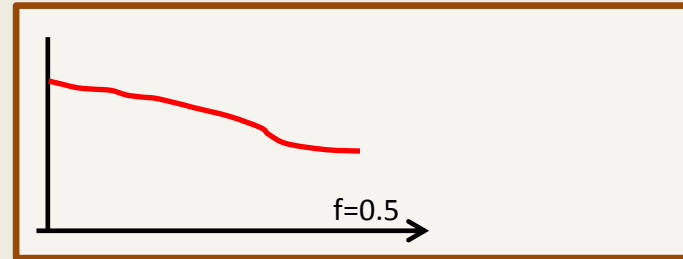
There is aliasing

EITF75 Systems and Signals

Not strange



But if sample spacing is too small...

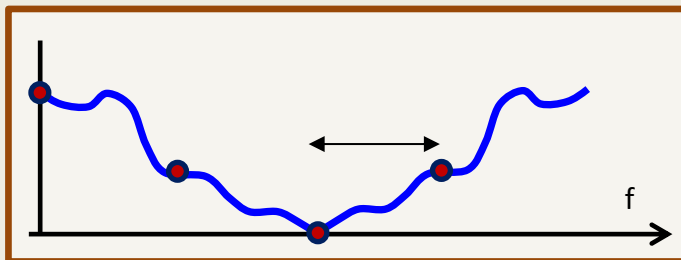


There is aliasing

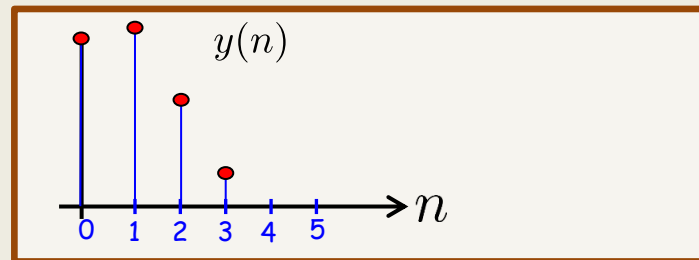
Aliasing

No aliasing

$$X(f) = F_s \sum_{k=-\infty}^{\infty} X_a((f - k)F_s) \quad X(f) = F_s X_a(f F_s)$$



But if sample spacing is too small...



There is aliasing

Periodically extended

Aliasing $y(n) = \sum_{m=-\infty}^{\infty} x(n - mN)$

No aliasing $y(n) = x(n)$

EITF75 Systems and Signals

Formal definition

For a sequence $x(n)$ of arbitrary length, the N-point DFT is defined as

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

and the inverse transform (IDFT) as

$$x_{\text{IDFT}}(n) = \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } n = 0, 1, \dots, N-1$$

Result

if the length of $x(n)$ is N, then

$$x_{\text{IDFT}}(n) = x(n) \quad \text{and} \quad X_{\text{DFT}}(k) = X(f \mid f = k/N)$$

EITF75 Systems and Signals

Obvious Question

Why would anybody want to compute a DFT of less length than that of $x(n)$?

Result

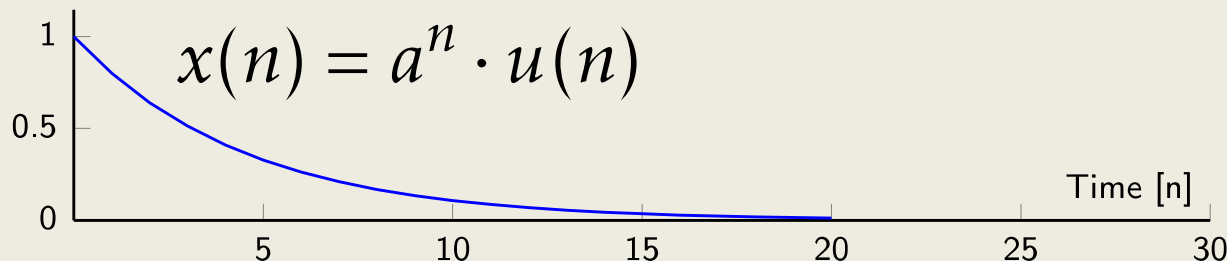
if the length of $x(n)$ is N , then

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EITF75 Systems and Signals

Less obvious answer

Signals with infinite time-support requires this



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EITF75 Systems and Signals

Less obvious answer

Signals with infinite time-support requires this

$$x(n) = a^n \cdot u(n)$$

We have two options, a computer has one

1. Compute the N-point DFT according to

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

2. Compute $X(f)$, and sample it to obtain $X(k)$

(computer cannot do 2 if it just encounters a signal. 2 requires us to know its math formula)

EITF75 Systems and Signals

Less obvious answer

Signals with infinite time-support requires this

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Let us invert 1&2, and compare

1. Compute the N-point DFT as

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

$$\frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) e^{j2\pi \cdot \frac{n}{N} \cdot k}$$

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EITF75 Systems and Signals

Less obvious answer

Signals with infinite time-support requires this

$$x(n) = a^n \cdot u(n)$$

Inversion of 1: we know the result

$$a^n \cdot u(n) \quad n = 0, 1, \dots, N - 1$$

Let us invert 1&2, and compare

1. Compute the N-point DFT as

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N - 1$$

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EITF75 Systems and Signals

Less obvious answer

Signals with infinite time-support requires this

$$x(n) = a^n \cdot u(n)$$

Inversion of 2: we know the result

$$\sum_{m=-\infty}^{\infty} x(n - mN) \quad n = 0, 1, \dots, N - 1$$

Let us invert 1&2, and compare

1. Compute the N-point DFT as

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EITF75 Systems and Signals

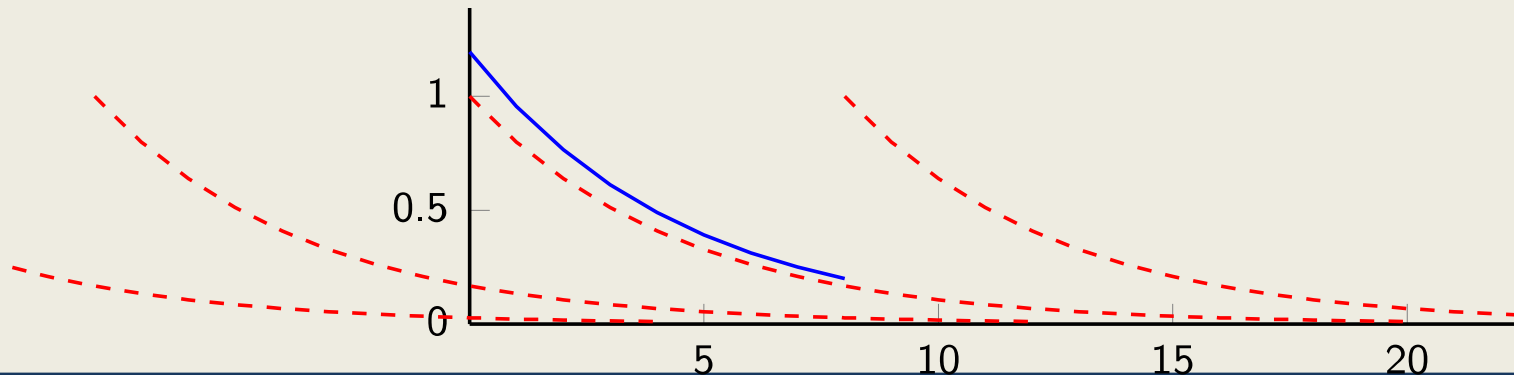
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EITF75 Systems and Signals

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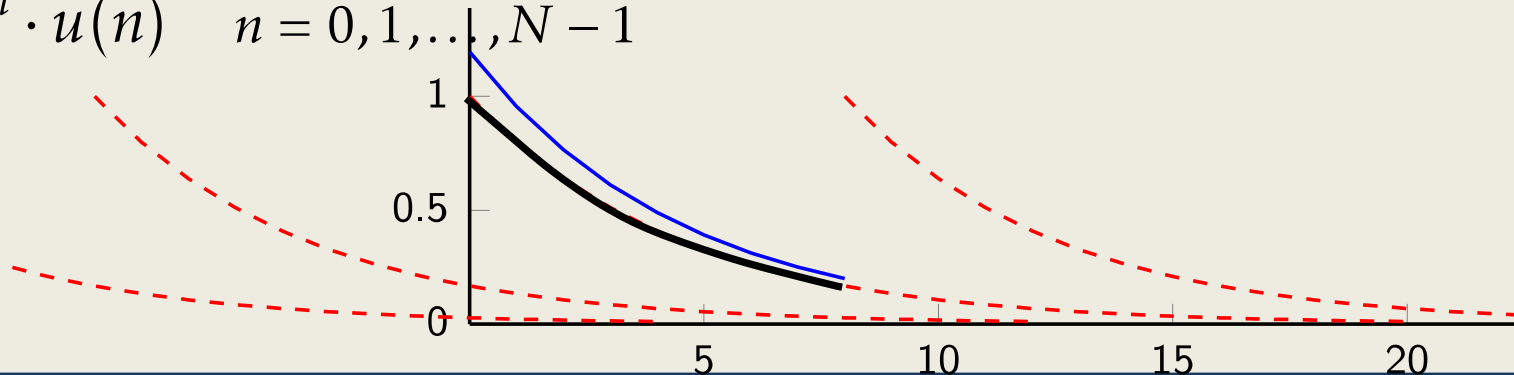
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EITF75 Systems and Signals

Computational complexity

DFT defined as

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

Number of operations needed:

EITF75 Systems and Signals

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Number of operations needed:

N values $X_{\text{DFT}}(k)$ to be computed

EITF75 Systems and Signals

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Number of operations needed:

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Each value requires N multiplications $x(n) \cdot e^{-j2\pi kn/N}$

EITF75 Systems and Signals

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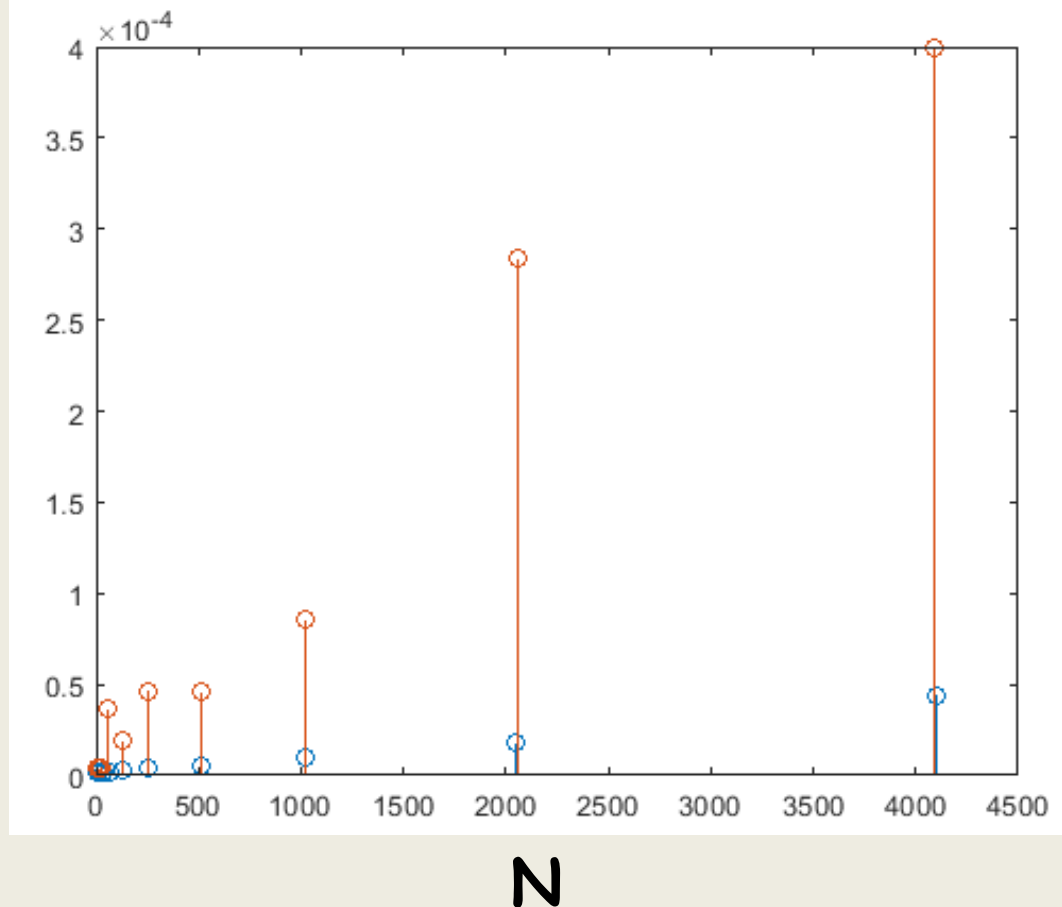
Total complexity N^2

EITF75 Systems and Signals

Computational complexity

Test in Matlab

Average time to compute an N-point DFT



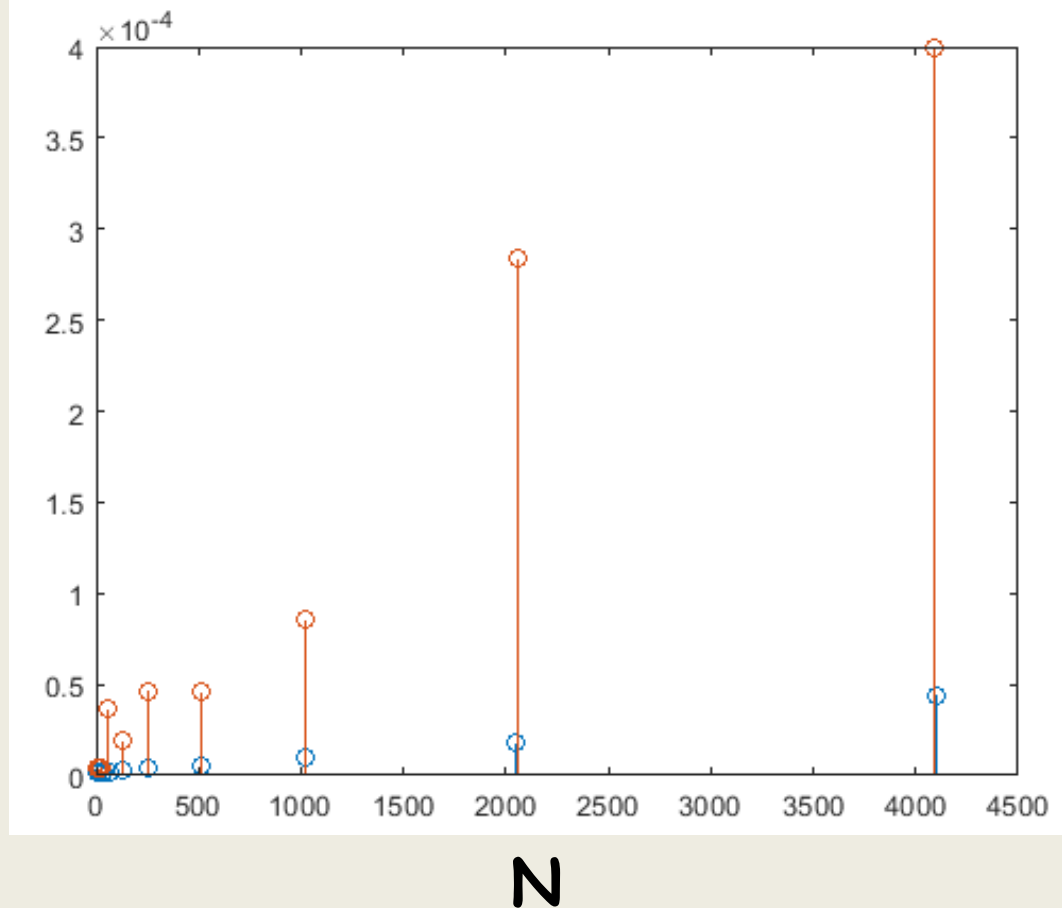
EITF75 Systems and Signals

Computational complexity

Test in Matlab

We see that for some values of N , much less time is needed

Average time to compute an N -point DFT



EITF75 Systems and Signals

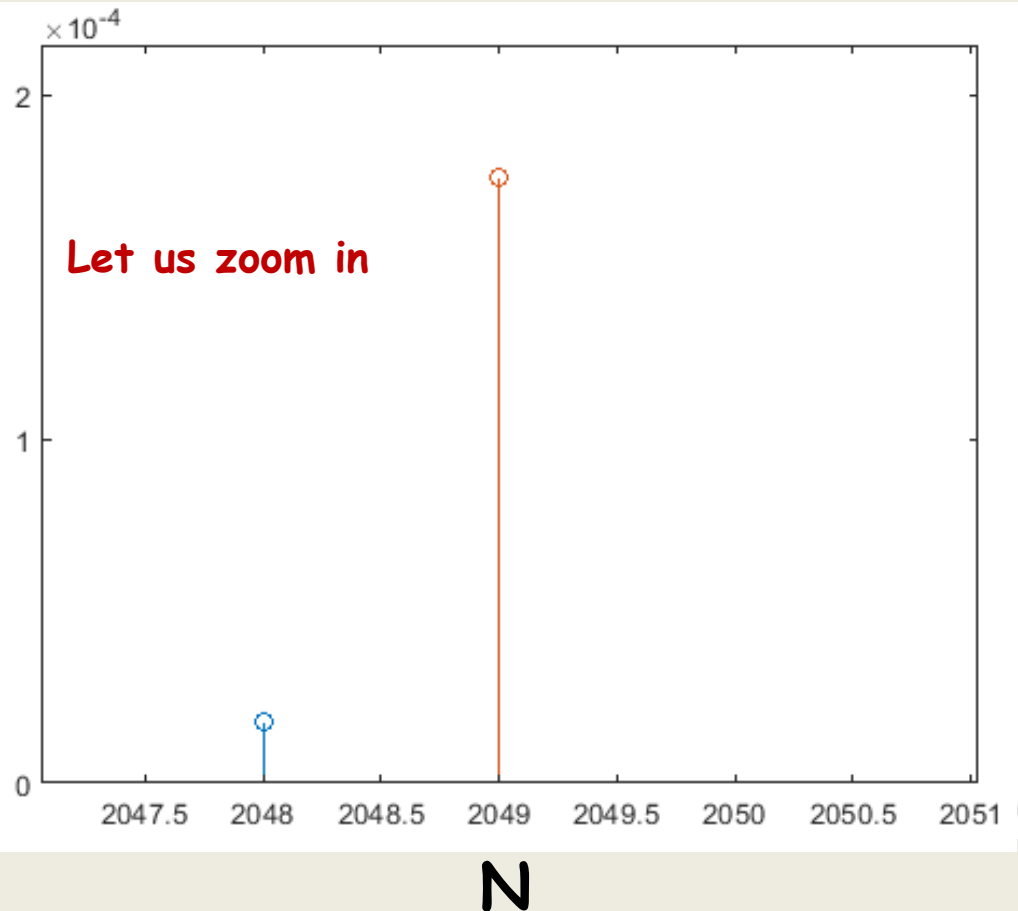
Computational complexity

Test in Matlab

2048 is 2^{11}

2049 not power of 2

Average time to compute an N-point DFT



EITF75 Systems and Signals

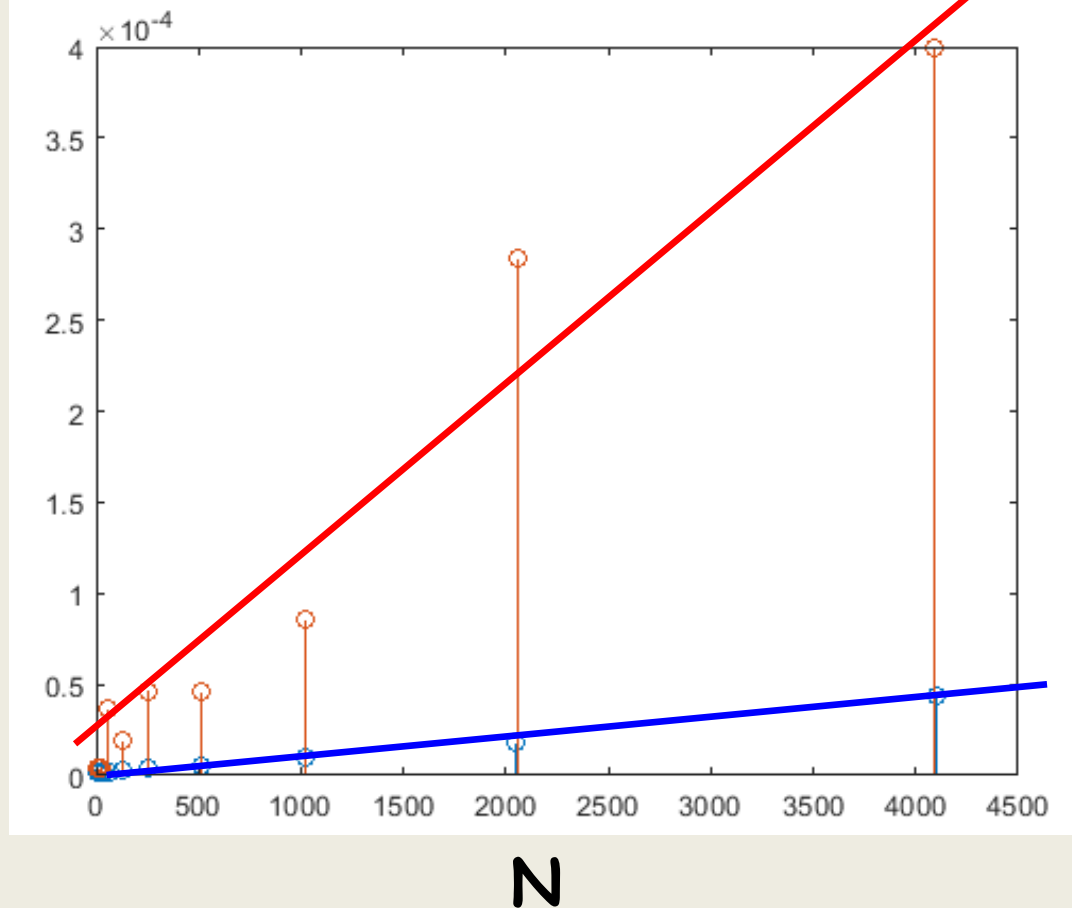
Computational complexity

Test in Matlab

2048 is 2^{11}

Significant speed-up
possible for $N=2^k$

Average time to compute an N-point DFT



EITF75 Systems and Signals

Computational complexity

FFT not included in course, but good to know about

Test in Matlab

Fast Fourier transform (FFT)

If $N=2^k$, then $N \log_2(N)$ complexity to compute

$$X_{\text{DFT}}(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi \cdot \frac{k}{N} \cdot n} \quad \text{for } k = 0, 1, \dots, N-1$$

Made possible by some algebraic manipulations and tricks.

Cooley and Tukey 1965

Method known to, and used by, Gauss in 1805

EITF75 Systems and Signals

Computational complexity

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Test in Matlab

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Made possible by some algebraic manipulations and tricks.

The importance of the FFT cannot be underestimated. WIFI and 4G, etc could not been implemented without the FFT

For a computer,

1. It can avoid the continuous DTFT
2. It can compute the DFT extremely fast

EITF75 Systems and Signals

Properties

For DTFTs, we have

$$x(n) \star y(n) \leftrightarrow X(f)Y(f)$$

$$x(n) \leftrightarrow X(f) \quad x(n - n_0) \leftrightarrow X(f)e^{-i2\pi f n_0}$$

Still true ? I.e.

$$x(n) \star y(n) \leftrightarrow X(k)Y(k)$$

$$x(n) \leftrightarrow X(f) \quad x(n - n_0) \leftrightarrow X(k)e^{-i2\pi k n_0 / N}$$

EITF75 Systems and Signals

Properties

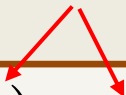
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Still true ? I.e.

Assume length N sequences


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EITF75 Systems and Signals

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Assume length N sequences. Follows that DFTs also length N


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EITF75 Systems and Signals

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But this is length 2N-1

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EITF75 Systems and Signals

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Assume length N sequences. Follows that DFTs also length N
But this is length 2N-1. So its DFT must be length 2N-1

~~$$x(n) \star y(n) \leftrightarrow X(k)Y(k)$$~~

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EITF75 Systems and Signals

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Assume length N. Ex {1 2 3 4}



$$x(n) \leftrightarrow X(f) \quad x(n - n_0) \leftrightarrow X(k)e^{-i2\pi k n_0 / N}$$

EITF75 Systems and Signals

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Also length N. Becomes {10 2+2i 2 2-2i}

EITF75 Systems and Signals

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Assume length N. Ex {1 2 3 4}

Length N+n₀. Ex {0 1 2 3 4}

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EITF75 Systems and Signals

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Also length N. Becomes {10 2+2i 2 2-2i}

Still length N₀

Makes no sense...

EITF75 Systems and Signals

Properties

For DTFTs, we have

$$x(n) \star y(n) \leftrightarrow X(f)Y(f)$$

$$x(n) \leftrightarrow X(f) \quad x(n - n_0) \leftrightarrow X(f)e^{-i2\pi f n_0}$$

Still true ? NO

EITF75 Systems and Signals

Properties

For DTFTs, we have

$$x(n) \star y(n) \leftrightarrow X(f)Y(f)$$

$$x(n) \leftrightarrow X(f) \quad x(n - n_0) \leftrightarrow X(f)e^{-i2\pi f n_0}$$

For DFTs, we have

$$x_1(n) \otimes x_2(n) \leftrightarrow X(k)Y(k)$$

$$x(n - n_0 \bmod N) \leftrightarrow X(k)e^{-i2\pi k n_0 / N}$$

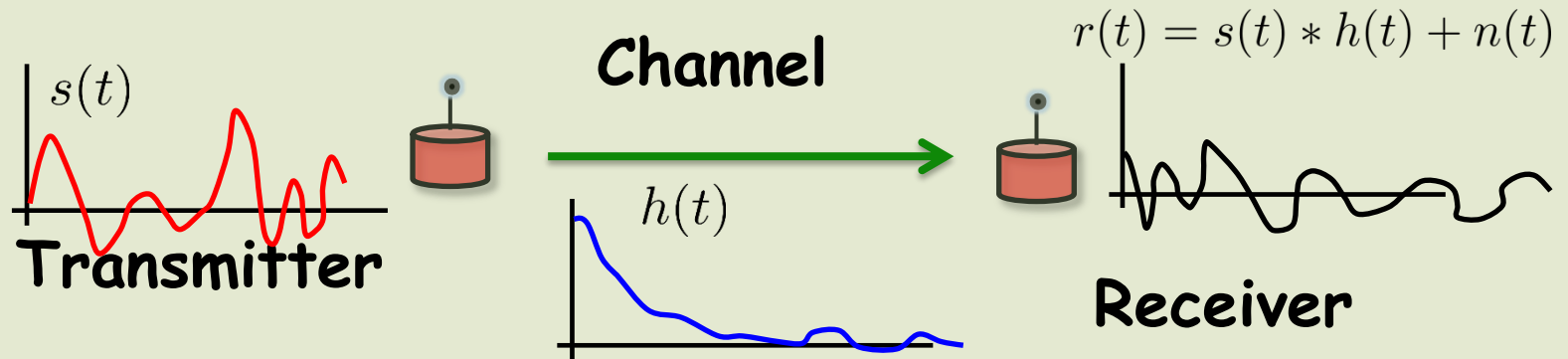
where

$$x_1(n) \otimes x_2(n) = \sum_{k=0}^{N-1} x_1(k)x_2(n - k \bmod N)$$

Circular convolution

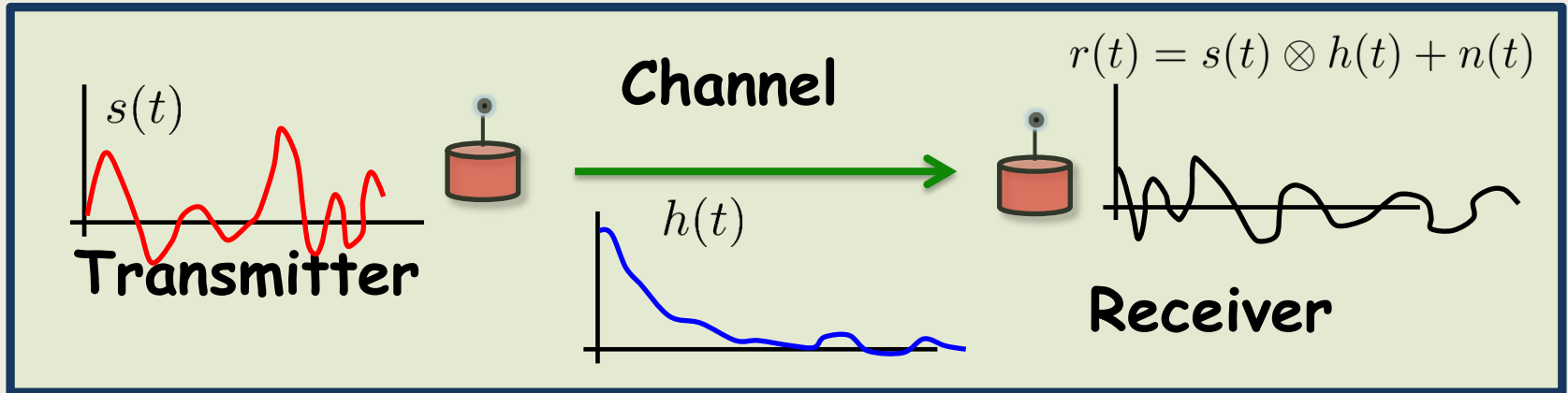
EITF75 Systems and Signals

Interlude



EITF75 Systems and Signals

Interlude



In WIFI, 4G, 5G etc etc, we give up 5-10% of the possible data rate in order to turn channel convolution into a circular convolution.
Then we can use the FFT and save complexity

EITF75 Systems and Signals

Example

Circular convolution

$$x(n) = \{1 \ 2 \ 3 \ 4\}$$

$$h(n) = \{2 \ 2 \ 1 \ 1\}$$

$$y_C(n) = x(n) \otimes h(n)$$

EITF75 Systems and Signals

Example

Circular convolution

$$x(n) = \{\underline{1} \ 2 \ 3 \ 4\}$$

$$h(n) = \{\underline{2} \ 2 \ 1 \ 1\}$$

$$y_C(n) = x(n) \otimes h(n)$$

Method 3

$h(k)$	1	1	2	<u>2</u>	$\rightarrow$										
$x(k)$	0	0	0	<u>1</u>	2	3	4	0	0	0	0	1	2	3	
$y_L(k)$				<u>2</u>	6	11	17	13	7	4	0				

Method 1

$h(k)$	1	1	2	<u>2</u>	$\rightarrow$					
$x(k)$	2	3	4	<u>1</u>	2	3	4	1	2	3
$y_C(k)$				<u>15</u>	13	15	17			

Method 2

	2	3	4	<u>1</u>	2	3	4
<u>2</u>	4	6	8	<u>2</u>	4	6	8
2	4	6	8	2	4	6	8
1	2	3	4	1	2	3	4
1	2	3	4	1	2	3	4

EITF75 Systems and Signals

Example

Circular convolution

Method 4

```
>> x = [1 2 3 4];
>> h = [2 2 1 1];
>> yc = ifft(fft(x).*fft(h))
yc =
    15    13    15    17
```

Method 3

$h(k)$	1	1	2	<u>2</u>	$\rightarrow$									
$x(k)$	0	0	0	<u>1</u>	2	3	4	0	0	0	0	1	2	3
$y_L(k)$					<u>2</u>	6	11	17	13	7	4	0		

Method 1

$h(k)$	1	1	2	<u>2</u>	$\rightarrow$					
$x(k)$	2	3	4	<u>1</u>	2	3	4	1	2	3
$y_C(k)$					<u>15</u>	13	15	17		

Method 2

	2	3	4	<u>1</u>	2	3	4
<u>2</u>	4	6	8	<u>2</u>	4	6	8
2	4	6	8	2	4	6	8
1	2	3	4	1	2	3	4
1	2	3	4	1	2	3	4

Red arrows indicate the summation process for the output values: 15, 13, 15, 17.

EITF75 Systems and Signals

Example

Linear convolution computed via DFTs

Given: Two length N sequences, $x(n)$, $y(n)$

Task: Compute their linear convolution by using DFT and its inverse IDFT

EITF75 Systems and Signals

Example

Linear convolution computed via DFTs

Given: Two length N sequences, $x(n)$, $y(n)$

Task: Compute their linear convolution by using DFT and its inverse IDFT

```
>> x=[1 2 3 4];  
>> y=[2 2 1 1];  
>> yL=conv(x,y)  
yL =
```

```
2      6     11     17     13      7      4
```

This is the result, But
not computed via DFT

EITF75 Systems and Signals

Example

Linear convolution computed via DFTs

Given: Two length N sequences, $x(n)$, $y(n)$

Task: Compute their linear convolution by using DFT and its inverse IDFT

```
>> x=[1 2 3 4];  
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yL =  
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This is the result, But
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```
>> x = [1 2 3 4];  
>> h = [2 2 1 1];  
>> yc = ifft(fft(x).*fft(h))  
yc =  
    15    13    15    17
```

This fails

EITF75 Systems and Signals

Example

Linear convolution computed via DFTs

Given: Two length N sequences, $x(n)$, $y(n)$

Task: Compute their linear convolution by using DFT and its inverse IDFT

```
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yL =  
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This is the result, But
not computed via DFT

```
>> xp=[1 2 3 4 0 0 0 0];  
>> yp=[2 2 1 1 0 0 0 0];  
>> yL=ifft(fft(xp).*fft(yp))  
yL =  
  2.0000  6.0000 11.0000 17.0000 13.0000  7.0000  4.0000 -0.0000
```

Still a circular convolution carried out, but due to zero-padding, it behaves linear.

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More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1\}$$

Compute 16-point DFT (N=16) $X(k)$, $k = 0, 1, \dots, 15$

EITF75 Systems and Signals

More examples

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Compute inverse transform $x_{\text{IDFT}}(n) = \frac{1}{N} \sum_{k=0}^{N-1} X^2(k) e^{i2\pi kn/N}$

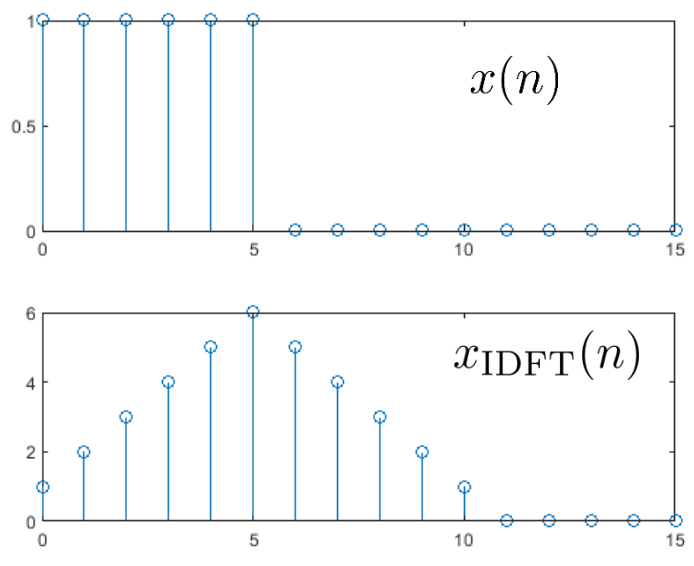
EITF75 Systems and Signals

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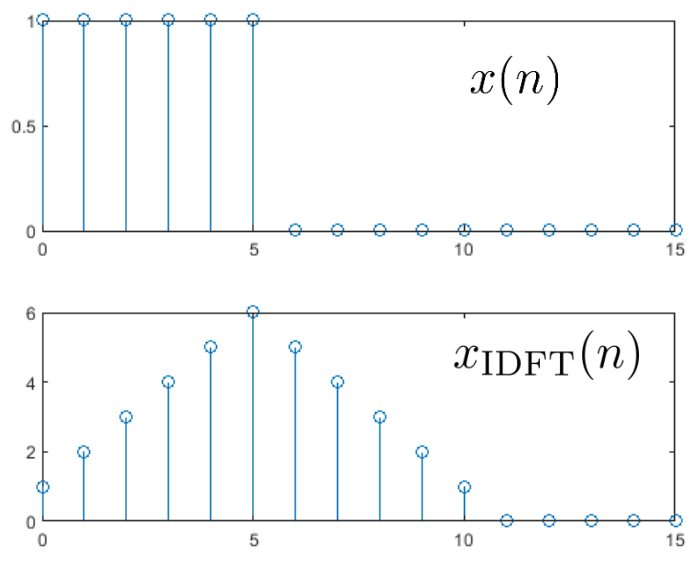
More examples

Repeat for $x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1\}$

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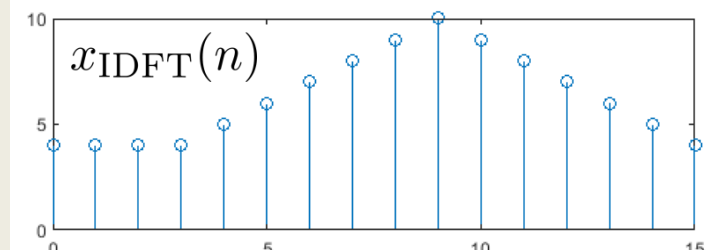
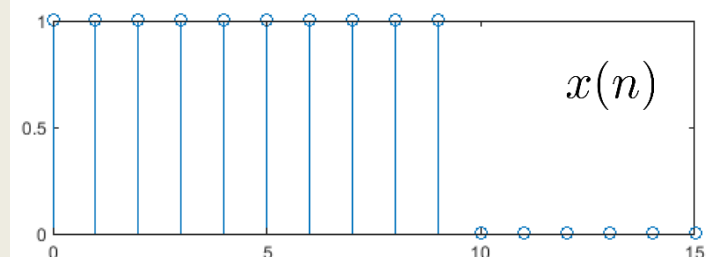
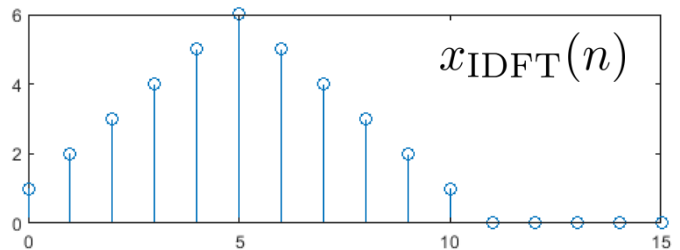
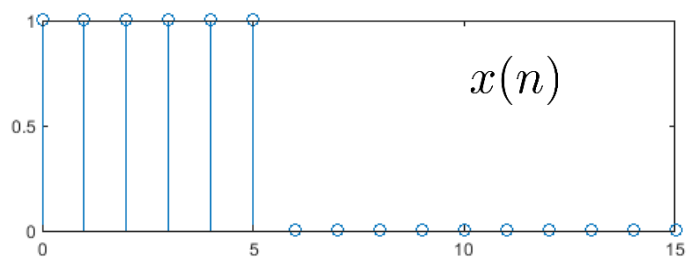
More examples

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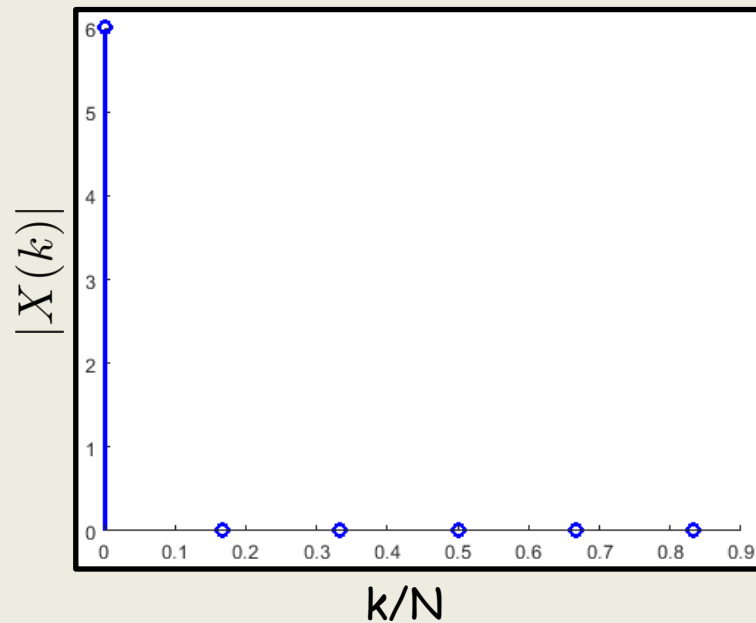


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More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1\}$$

Compute DFT (N=6)

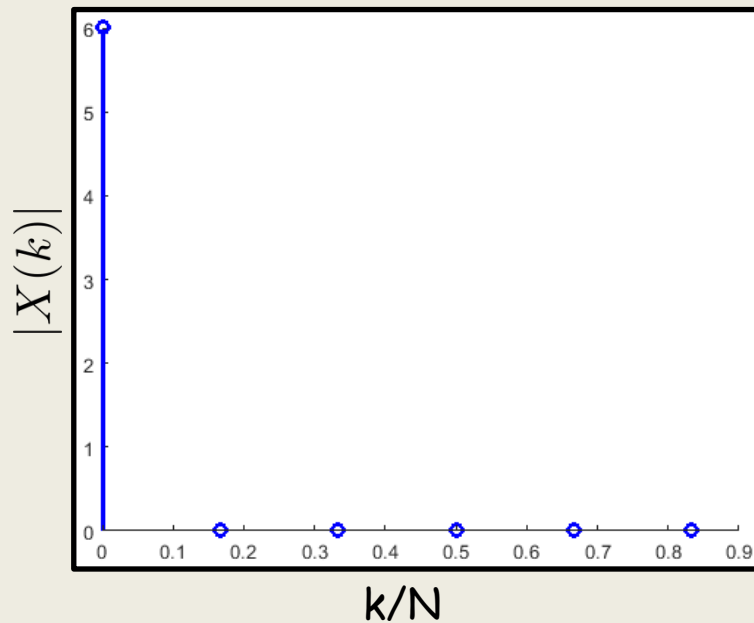


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More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 0\}$$

Compute DFT (N=8)

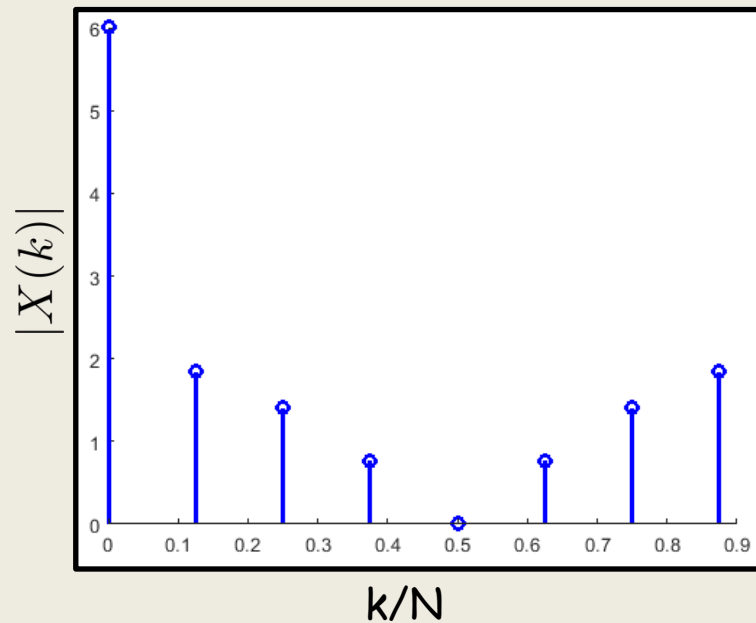


EITF75 Systems and Signals

More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 0\}$$

Compute DFT (N=8)

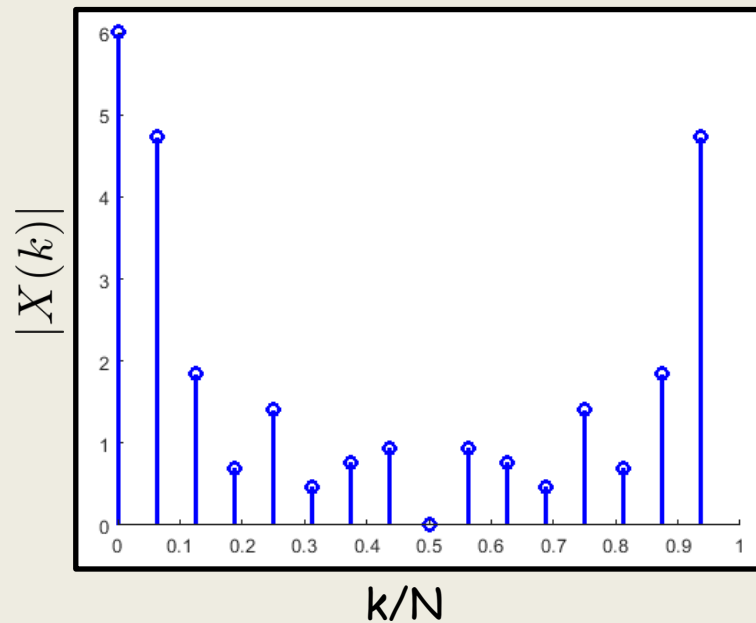


EITF75 Systems and Signals

More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 0 \dots\dots\}$$

Compute DFT (N=16)

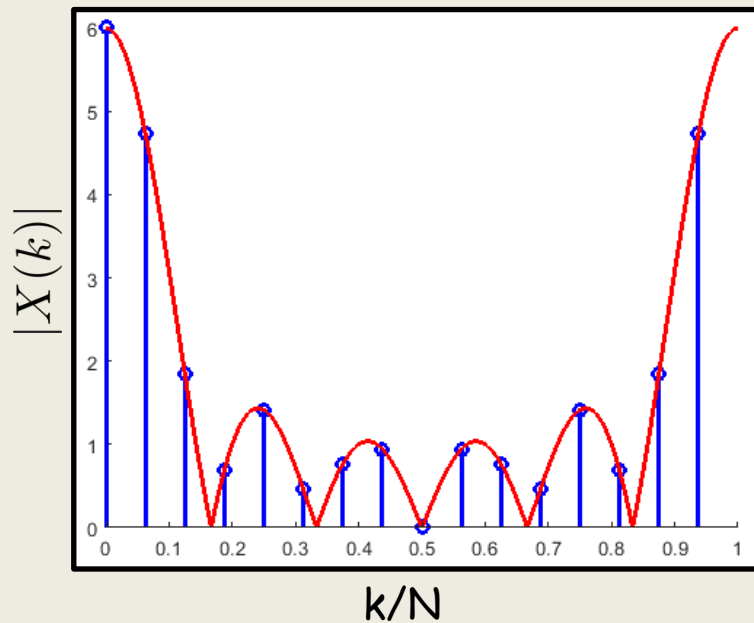


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More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 0 \dots\dots\}$$

Compute DFT (N=16)



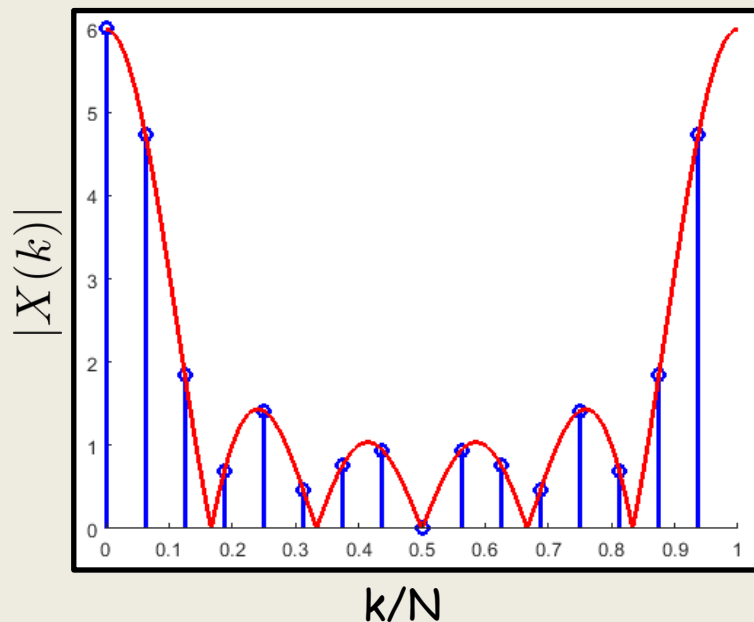
What is this line?

EITF75 Systems and Signals

More examples

$$x(n) = \{1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 0 \ 0 \dots\dots\}$$

Compute DFT (N=16)



What is this line?

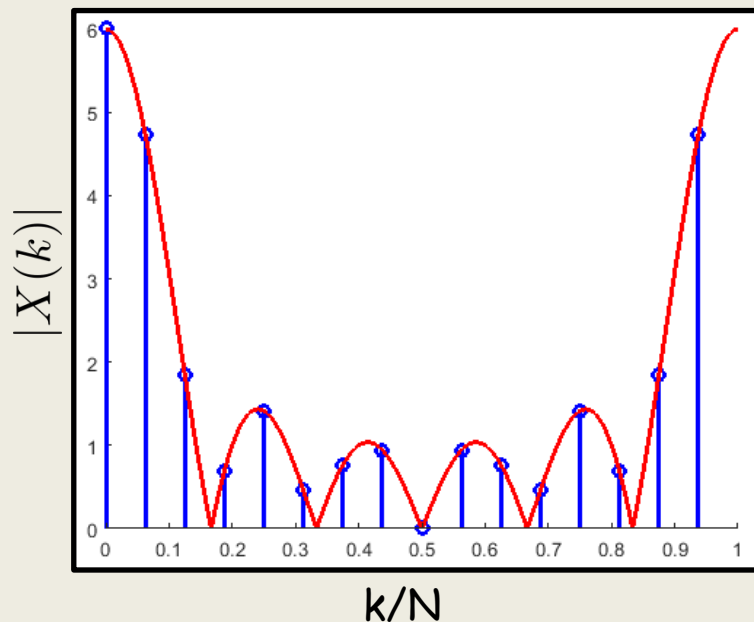
DFT size larger-or-equal to
the length of $x(n)$

EITF75 Systems and Signals

More examples

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Compute DFT (N=16)



What is this line?

DFT size larger-or-equal to
the length of $x(n)$

Therefore, DFT samples of **DTFT**

EITF75 Systems and Signals

As a matrix computation

$$X(k) = \sum_{n=0}^{N-1} x(n)e^{-i2\pi kn/N}$$

We can write a DFT as a matrix multiplication

$$\begin{bmatrix} X(0) \\ X(1) \\ \vdots \\ X(N-1) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & e^{-i2\pi/N} & e^{-i2\pi 2/N} & \cdots & e^{-i2\pi(N-1)/N} \\ 1 & e^{-i2\pi 2/N} & e^{-i2\pi 2 \cdot 2/N} & \cdots & e^{-i2\pi 2 \cdot (N-1)/N} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & e^{-i2\pi(N-1)/N} & e^{-i2\pi(N-1) \cdot 2/N} & \cdots & e^{-i2\pi(N-1) \cdot (N-1)/N} \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}$$

$$\mathbf{X} = \mathbf{W}\mathbf{x}$$

EITF75 Systems and Signals

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$$\mathbf{X} = \mathbf{W}\mathbf{x}$$

Therefore

$$\mathbf{x} = \mathbf{W}^{-1}\mathbf{X}$$

Easy to show that $\mathbf{W}$ is unitary (orthogonal, but for complex matrices) $\mathbf{W}^H \mathbf{W} = \mathbf{I}$