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Examination, Systems and Signals EITF75

All tools allowed. Send scanned solutions to fredrik.rusek@eit.lth.se no later than 13.15.

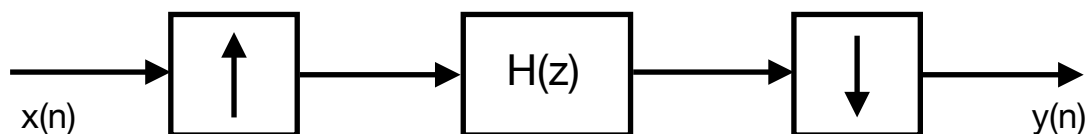
Problem 1 (10p)

For the difference equation $y(n) + \frac{1}{2}y(n-1) = 3x(n) - x(n-1)$, find

1. The system transfer function $H(z)$
2. The pole-zero diagram corresponding to the difference equation
3. The impulse response $h(n)$
4. The Discrete-time Fourier transform of the impulse response $H(f)$
5. The output for the input signal $x(n) = [1 \ 1 \ -1 \ 1]$
6. The steady state response to the input $x(n) = u(n)$ (a step)
7. The transient response to the input $x(n) = u(n)$

Problem 2 (10p)

Consider the following circuit, where an “up-arrow” means upsampling with a factor 2, and a “down-arrow” means downsampling with a factor 2.



where $H(z) = \frac{1}{1 + 0.5z^{-1}}$.

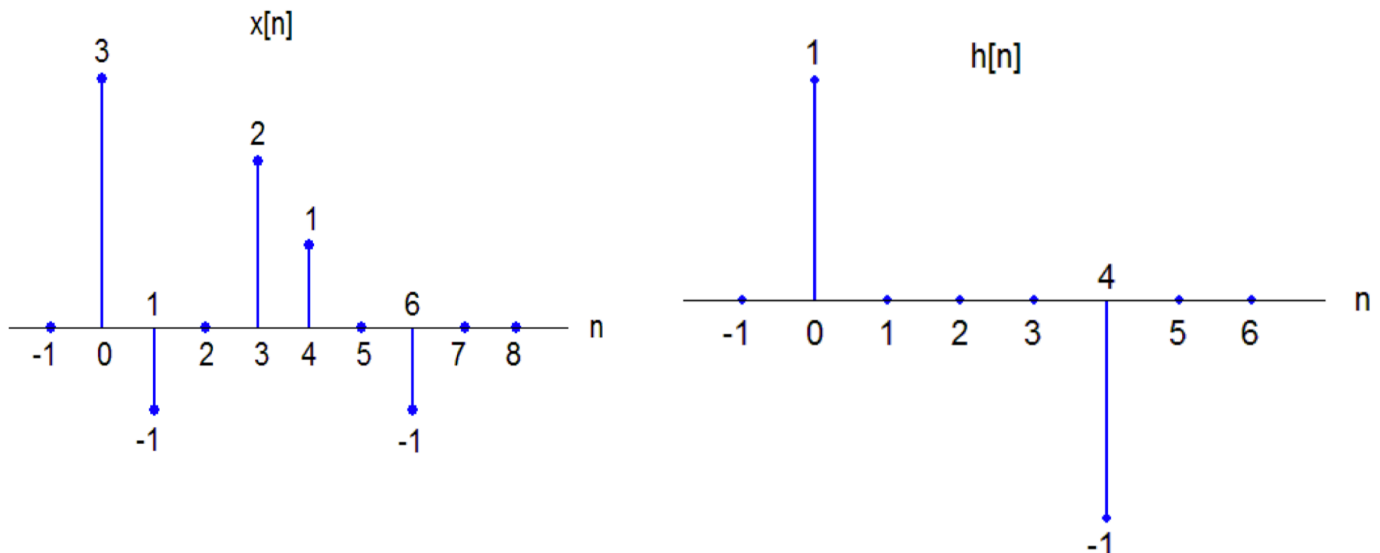
It is possible to express the input-output relation between $x(n)$ and $y(n)$ as $y(z) = G(z)x(z)$ where $G(z)$ is found from the upsampling, the filter $H(z)$ and the downsampling. Determine $G(z)$.

Problem 3 (5+5p)

This problem deals with the DFT.

HINT: It is possible to solve the entire problem without calculating any DFT, its inverse, or the DTFT. This is possible by using properties of DFTs.

Let $x(n)$ and $h(n)$ be the two signals shown below.



PART A)

Take the 8-point DFT of both $x(n)$ and $h(n)$ to obtain $X[k]$ and $H[k]$. Multiply to obtain $Y[k]=H[k]X[k]$. Now take the inverse 8-point IDFT of $Y[k]$ to obtain $y(n)$. What is $y(n)$?

RECALL THE HINT: there is a quicker way to determine $y(n)$ than to numerically calculate the DFTs and then calculating the IDFT.

PART B)

Calculate the DTFT of $x(n)$, i.e., obtain $X(f)$, $0 < f < 1$. Sample $X(f)$ at sample points $f=\{0,0.25,0.5,0.75\}$ to obtain

$$R[0] = X(0), R[1] = X(0.25), R[2] = X(0.5), R[3] = X(0.75).$$

Now, compute the 4-point IDFT of $R[0], R[1], R[2], R[3]$. Sketch your result.

RECALL THE HINT: there is a quicker way to determine $y(n)$ than to numerically calculate the DTFT, sample, and then calculating the IDFT.

Problem 4 (10p)

Assume that we have a continuous (analog) time signal $x(t)$ of length 100ms, and assume further that it is band-limited to 10000Hz, i.e., if $X(F)$ is the analog Fourier transform, then $|X(F)|=0$, $|F|>10000$.

The goal of this problem is to compute samples of $X(F)$ with 5Hz sample spacing in the range $0 < F < 10000$. This can be done with a 4000-point DFT. Specifically, we want to obtain a 4000-point sequence $x(n)$ for which the 4000-point DFT $X[k]$ is related to $X(F)$ by:

$$X[k] = \alpha X(F = 5k), \quad k = 0 \dots 1999 \quad (1)$$

where α is a scale factor that is not important to us. Note that there are more than 2000 values of $X[k]$, but we only care about the first 2000.

The following method to obtain a 4000-point sequence is proposed. First the signal $x(t)$ is sampled with a sample period of $T = 50\mu s$. The resulting 2000 samples are used to form $z(n)$ as follows:

$$z(n) = \begin{cases} x(kT), & 0 \leq n \leq 1999 \\ x((k - 2000)T), & 2000 \leq n \leq 3999 \\ 0, & \text{otherwise.} \end{cases}$$

The 4000-point DFT $Z[k]$ is computed.

For this method, determine how $Z[k]$ is related to $X(F)$. Indicate the relationship using a “typical” Fourier transform $X(F)$. Explicitly state whether or not $Z[k]$ is the desired result, i.e., if $Z[k]$ equals $X[k]$ as specified in Equation 1.

Problem 5 (10p)

Consider the difference equation:

$$y(n) + (2 \cdot 0.7 \cdot 0.8)y(n-1) + 0.8^2y(n-2) = x(n) + \frac{1}{2}x(n-1)$$

where “ \cdot ” means normal multiplication, i.e., the coefficient of $y(n-1)$ is 1.12.

We have the following 3 input signals:

$$x_1(n) = u(n) \quad (\text{a step}) \quad x_2(n) = u(n)\cos(2\pi n/4) \quad x_3(n) = u(n)\cos(2\pi n/2)$$

We have the following 5 steady-state output signals:

$$y_1(n) = A_1u(n) \quad y_2(n) = A_2u(n)\cos(2\pi n/4 - \alpha_2) \quad y_3(n) = A_3u(n)\cos(2\pi n/2)$$

$$y_4(n) = A_4u(n)\cos(2\pi n/2 - \pi/2) \quad y_5(n) = A_5u(n)\cos(2\pi n - \alpha_5).$$

Of the 5 output signals, only 3 can occur for the 3 input signals. Or, in other words, each input signal corresponds to one steady-state output signal, so there are two outputs with no matching input.

You should:

1. Determine the output signals that cannot occur.
2. For the 3 outputs that can occur, determine their amplitude values, i.e., the A_k variables.

Observe: You do not have to determine the values α_2 and α_5 in case $y_2(n)$ or $y_5(n)$ are valid output signals.