



LUND
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EITF35: Introduction to Structured VLSI Design

Part 1.2.2: VHDL-1

Liang Liu
liang.liu@eit.lth.se



Outline

- **VHDL Background**
- **Basic VHDL Component**
 - An example
- **FSM Design with VHDL**
- **Simulation & TestBench**



What is VHDL?

Very high speed integrated circuit

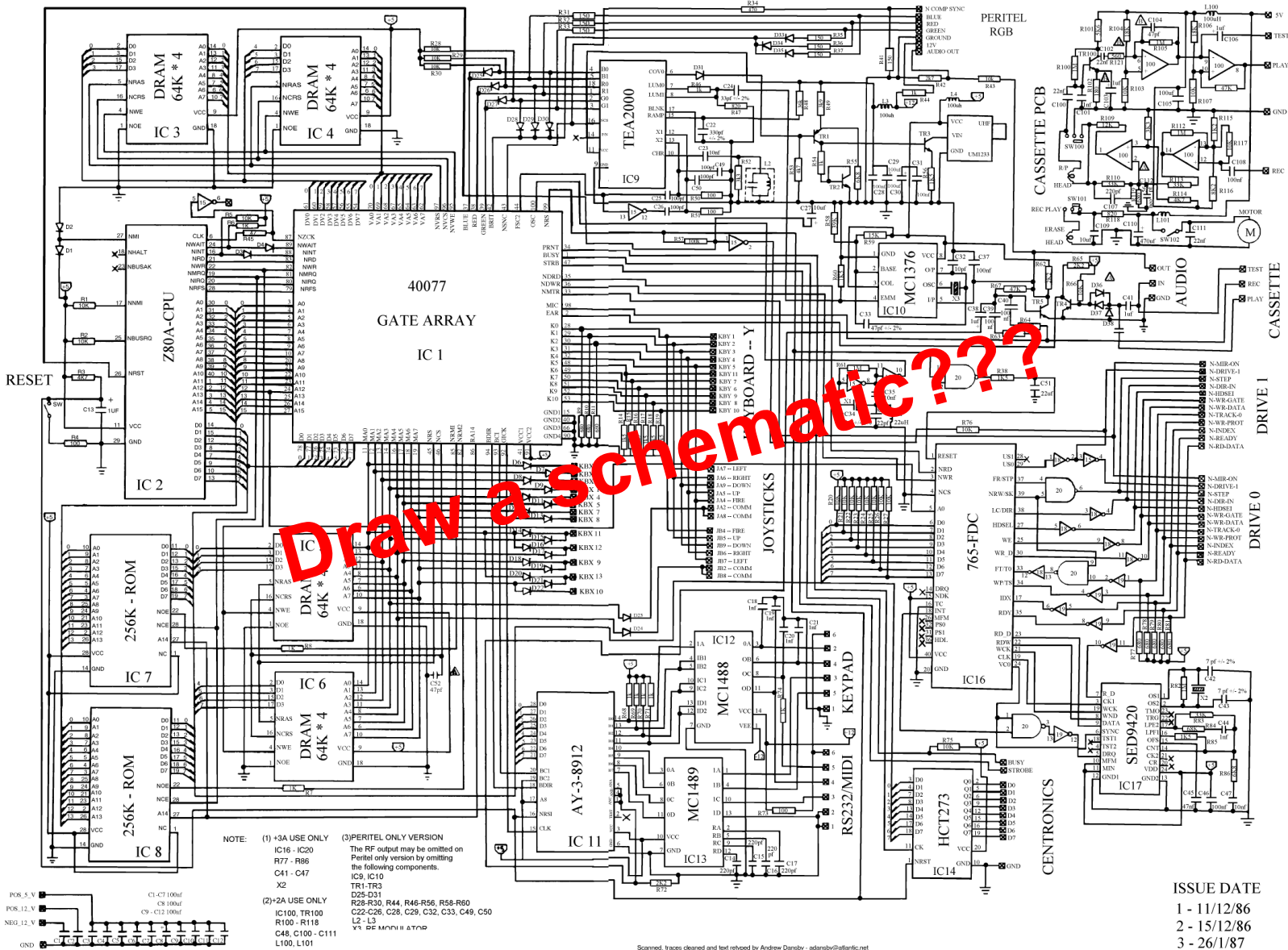
Hardware

Description

Language



Why use an HDL?

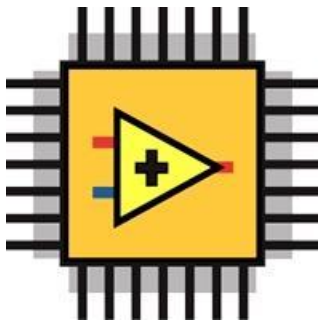
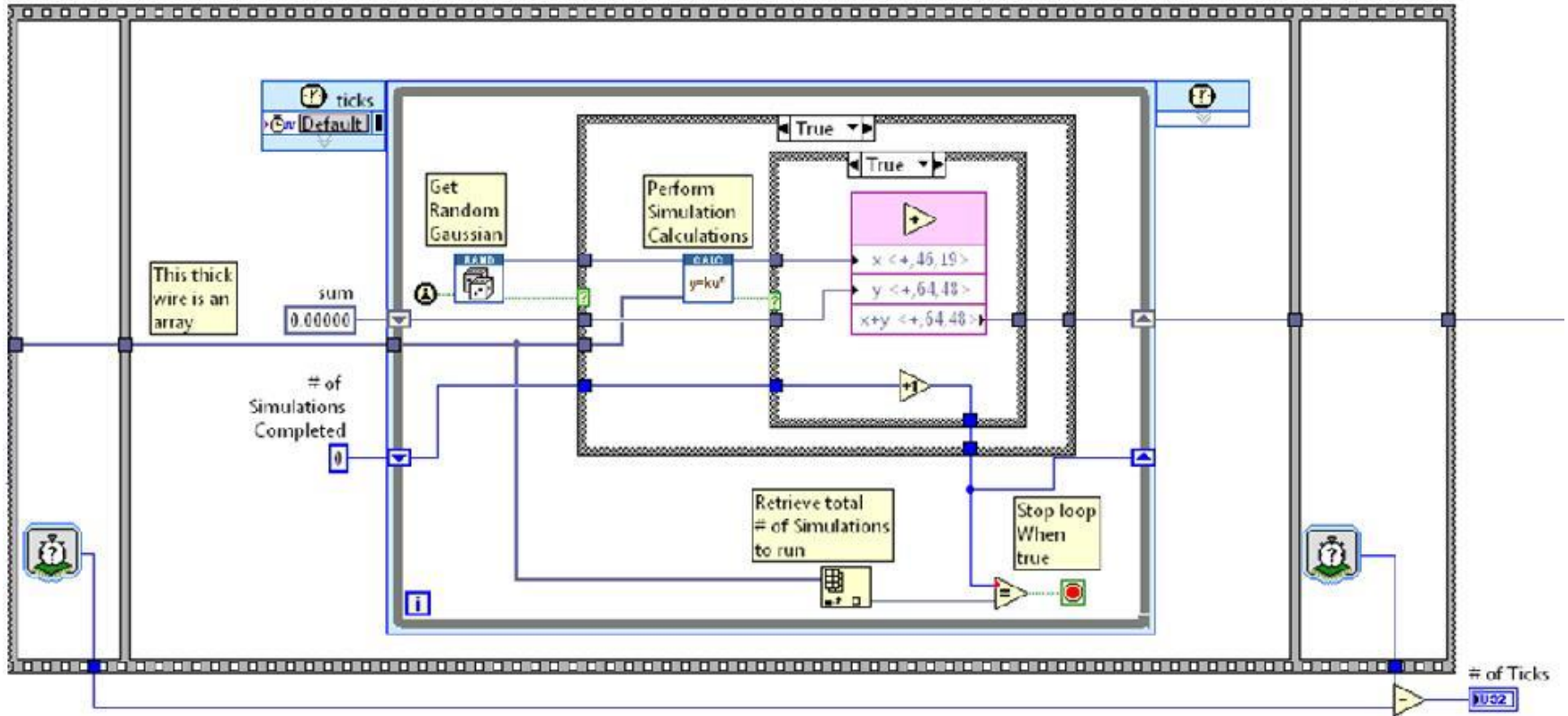


Scanned, traces cleaned and text relpyped by Andrew Danzky - andanzky@att.net



ISSUE DATE
 1 - 11/12/86
 2 - 15/12/86
 3 - 26/1/87

Not really in all cases...



Why use an HDL?

□ Advantages of VHDL

- Supports easy modeling of various abstraction levels
 - *from the gate level to the system level*
- Supported by all CAD Tools
- Technology "independent"
 - **easy to move VHDL code between different commercial platforms**
- Used by industry and academia worldwide – Specially in Europe



VHDL vs. Verilog

- Equivalent for RTL modeling
- Both are industrial standards and are supported by most software tools
- **VHDL** more popular in Europe/**Verilog** in US & Asian
- **VHDL** is more **flexible** in syntax and usage

VHDL

```
library IEEE;
use IEEE.STD_Logic_1164, all;

entity LATCH_IF_ELSEIF is
  port (En1, En2, En3, A1, A2, A3: in std_logic;
        Y: out std_logic);
end entity LATCH_IF_ELSEIF;

architecture RTL of LATCH_IF_ELSEIF is
begin
  process (En1, En2, En3, A1, A2, A3)
  begin
    if (En1 = '1') then
      Y <= A1;
    elseif (En2 = '1') then
      Y <= A2;
    elseif (En3 = '1') then
      Y <= A3;
    end if;
  end process;
end architecture RTL;
```

Verilog

```
module LATCH_IF_ELSEIF (En1, En2, En3, A1, A2, A3, Y);
  input En1, En2, En3, A1, A2, A3;
  output Y;

  reg Y;

  always @(En1 or En2 or En3 or A1 or A2 or A3)
    if (En1 == 1)
      Y = A1;
    else if (En2 == 1)
      Y = A2;
    else if (En3 == 1)
      Y = A3;

end module
```



VHDL vs. Verilog

□ System Modeling

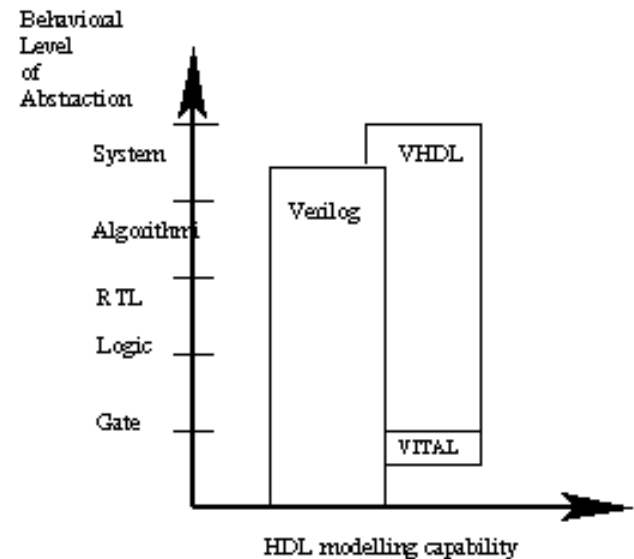
- For **high level** behavioral modeling, VHDL is better
- VHDL had package and library concept
- Verilog has built-in **gate level** and **transistor level** primitives
- Verilog is better than VHDL at below the RTL level.

□ Data Type

- Verilog does not have ability to define new data types
- VHDL has more data types but is strict and **NOT ALL** data types can be used for hardware.

□ Back annotation

- SDF (Standard Delay Format) for Verilog



Other “HDLs”

□ SystemVerilog (*)

- a superset of Verilog, with enhancements to address system-level design and verification

□ Verilog/VHDL-AMS

- a standardized language for mixed analog/digital simulation

□ SystemC

- a standardized class of C++ libraries for high-level behavioral and transaction modeling of digital hardware at a high level of abstraction

□ High-level synthesis

- Fast prototyping and proof of concept
- Catapult C (DSP Design)
- Vivado HLS
- Suggestion: Do **NOT** use it before you can handle traditional HDL



Outline

□ VHDL Background

- What is VHDL?
- Why VHDL?

□ Basic VHDL Component

- An example

□ FSM Design with VHDL

□ Simulation & TestBench



Simple Tutorial to VHDL

□ For all **C/C++/Matlab** guys—

“Forget” everything you know!

□ Do NOT code if you don't know what
HARDWARE will be generated



Traditional PL v.s. VHDL

□ Traditional PL

- Operations performed in a **sequential** order
- Help human's thinking process to develop an algorithm step by step (dangerous in HDL)
- Resemble the operations of a basic **computer model**

□ HDL – Characteristics of digital VLSI

- Connection of parts
- Concurrent operations
- Concept of propagation delay and timing



Design Flow

1. Text description (spec.)
2. Pseudocode (algorithms)
3. Block diagrams (datapath, controller, and interface)
4. ASM chart of the controller
5. RTL (VHDL/Verilog) code
6. Testbench, functional simulation and debugging
7. Synthesis and post-synthesis simulation
8. Implementation and timing simulation
9. Experimental testing



Sample Design Flow

□ Design Target (Spec.)

- Design a single bit half adder with carry and enable
- Performance?

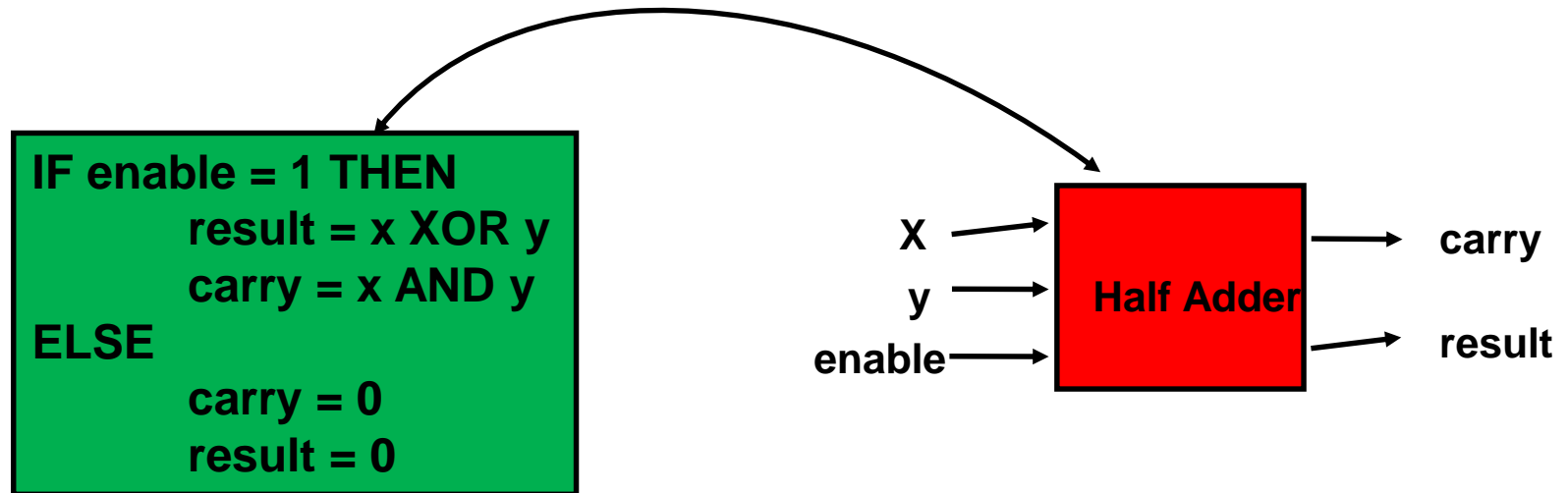
□ Detailed Functionality

- Passes results only on enable high and zero on enable low
- Result gets x plus y
- Carry gets any carry of x plus y



Step1: Behavioral Design

- Starting with an algorithm, a high level description of the adder is created.

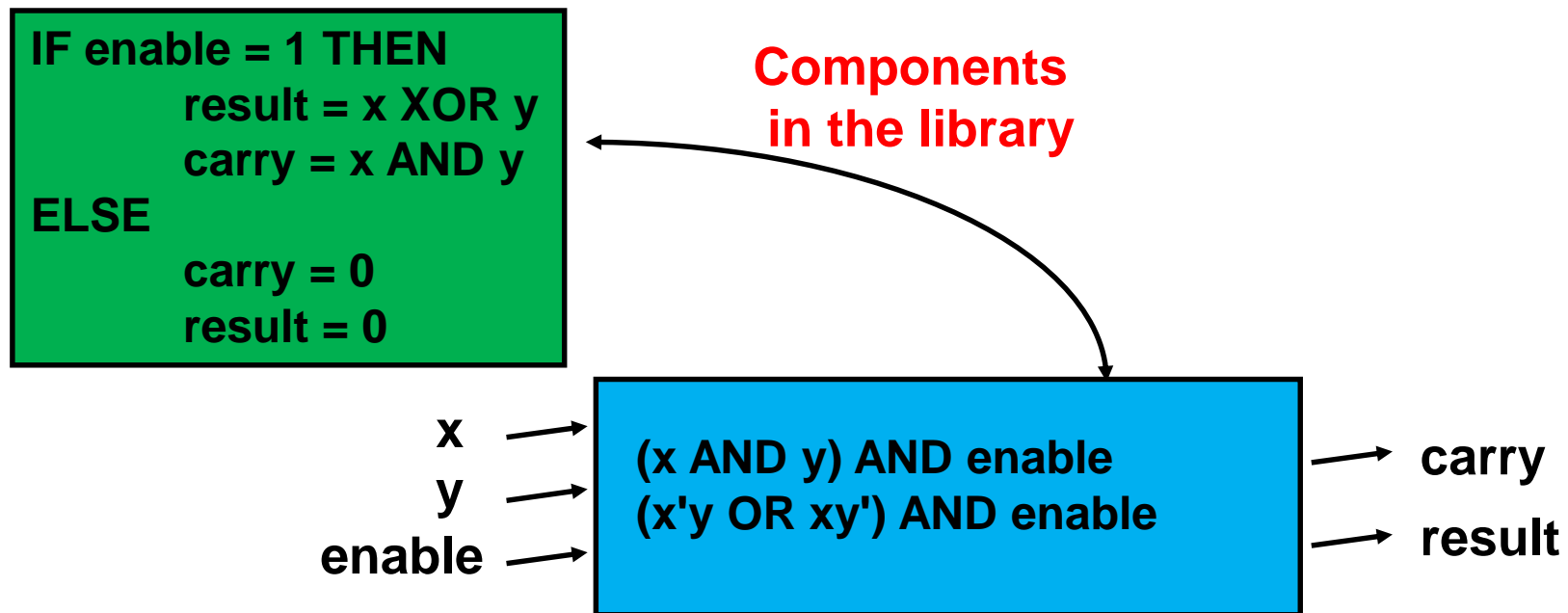


- The model can (MUST) be simulated at this high level description to verify correct understanding of the problem, e.g., Matlab



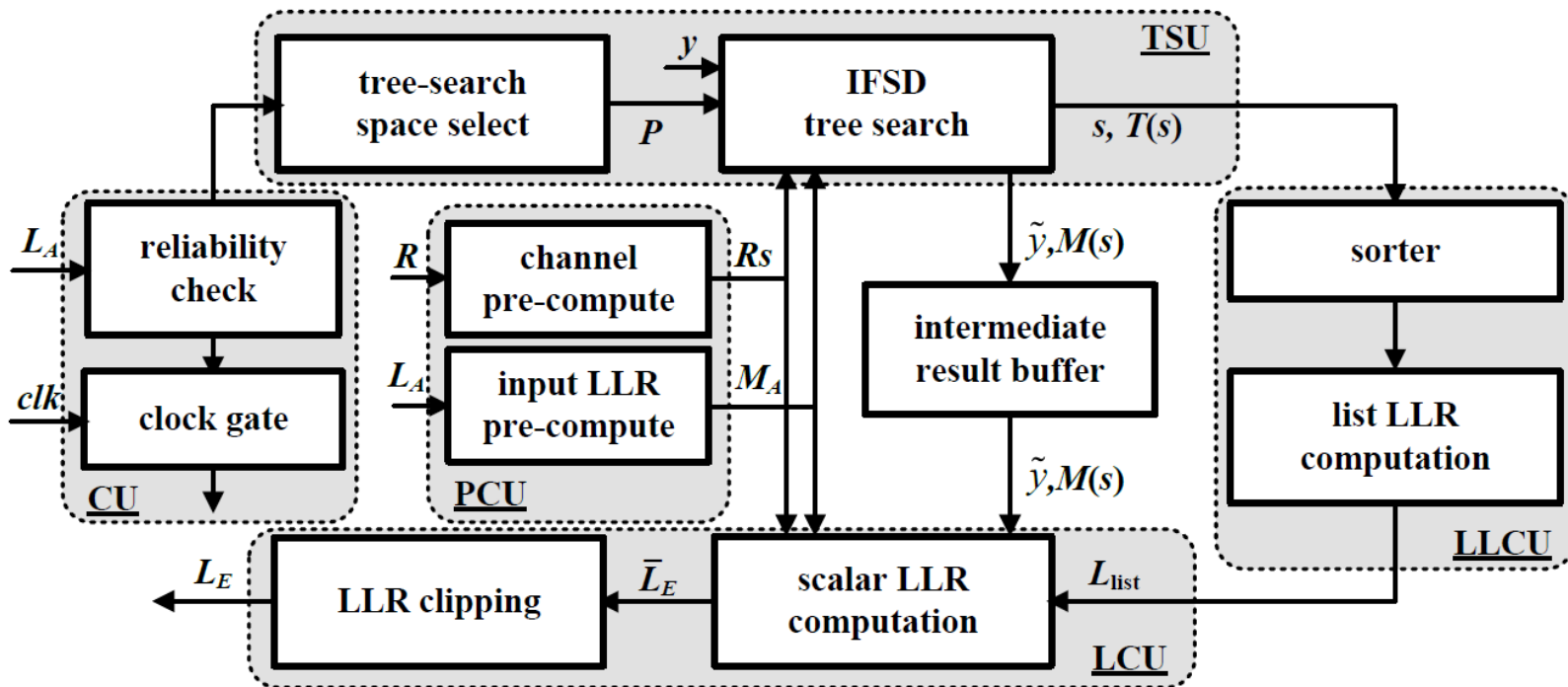
Step2: Circuit Design

□ A structural description is created at the “module” level, circuit design



Step2: Circuit Design

- A structural description is created at the “module” level, circuit design
- These “modules” should be pulled from a **library** of parts



Suggestion: Always draw block diagram before coding



Step3: VHDL Coding



Entity Declaration

- An entity declaration describes the *interface* of the component
- PORT clause indicates input and output ports
- An entity can be thought of as a *symbol* for a component

```
library IEEE;  
use IEEE.std_logic_1164.all;  
ENTITY half_adder IS  
    PORT (x, y, enable: IN bit;  
          carry, result: OUT bit);  
END half_adder;  
ARCHITECTURE data_flow OF half_adder IS  
BEGIN  
    carry <= (x AND y) AND enable;  
    result <= (x XOR y) AND enable;  
END data_flow;
```

LIBRARY DECLARATION

ENTITY DECLARATION

ARCHITECTURE BODY

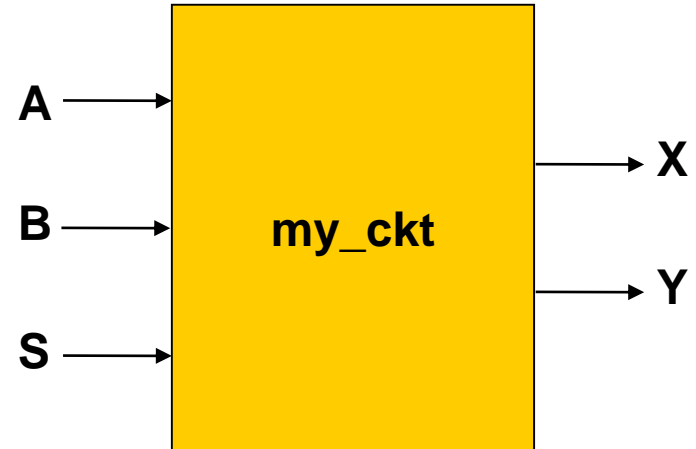
See Packages in IEEE library:

<http://www.csee.umbc.edu/portal/help/VHDL/stdpkg.html>



VHDL Entity

```
• entity my_ckt is  
  port (  
    A: in bit;  
    B: in bit;  
    S: in bit;  
    X: out bit;  
    Y: out bit  
  );  
end my_ckt;
```



- Name of the circuit
- User-defined
- **One entity per file**
- **Filename same as circuit name. Example:**
 - **Circuit name: my_ckt**
 - **Filename: my_ckt.vhd**

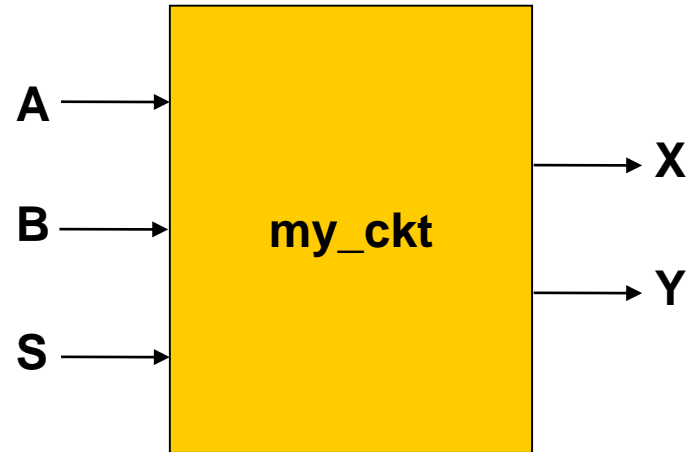


VHDL Entity

- entity **my_ckt** is
port (

A: in bit;
B: in bit;
S: in bit;
X: out bit;
Y: out bit

end **my_ckt**;



Port names or
Signal names
i_clk_r, i_rst_n



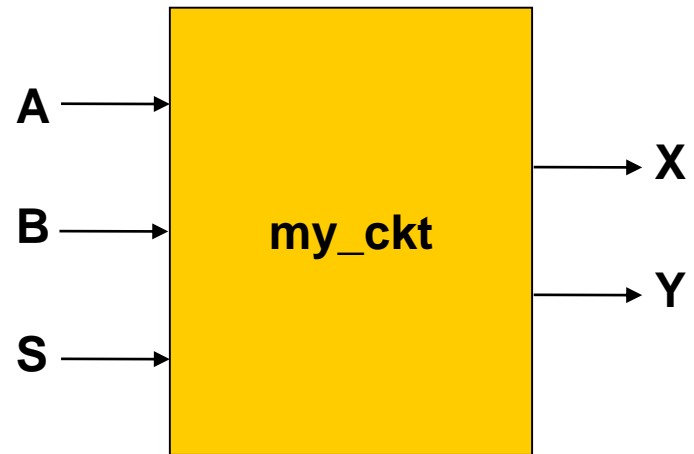
VHDL Entity

- entity `my_ckt` is
port (

```
A: in bit;  
B: in bit;  
S: in bit;  
X: out bit;  
Y: out bit
```

```
);
```

```
end my_ckt;
```



Direction of port

3 main types:

- `in`: Input
- `out`: Output
- `inout`: Bidirectional



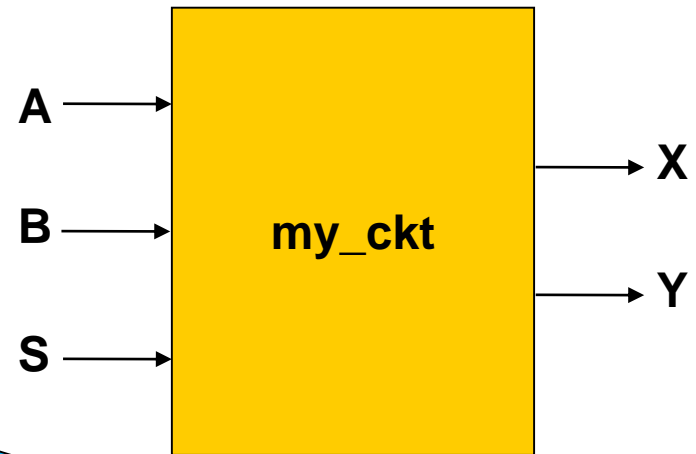
VHDL Entity

• `entity my_ckt is`
`port (`

```
A: in bit;  
B: in bit;  
S: in bit;  
X: out bit;  
Y: out bit
```

`);`

`end my_ckt;`



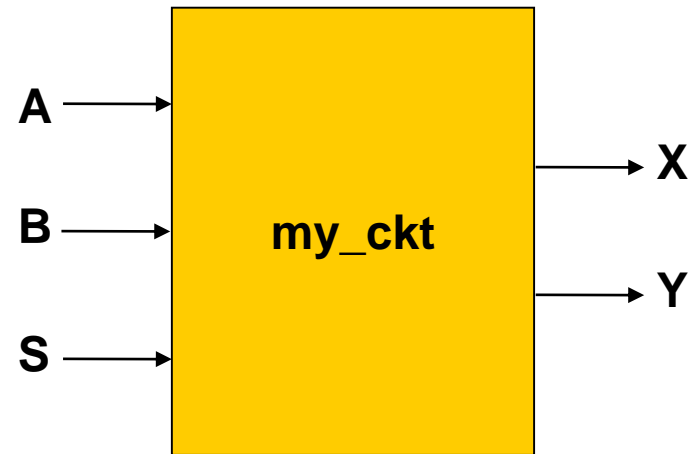
Datatypes:

- bit, bit_vector
- integer
- **std_logic,**
std_logic_vector
- User-defined



VHDL Entity

```
• entity my_ckt is  
  port (  
    A: in bit;  
    B: in bit;  
    S: in bit;  
    X: out bit;  
    Y: out bit;  
  );  
end my_ckt;
```



Note the absence of semicolon “;” at the end of the last signal and the presence at the end of the closing bracket



VHDL Coding

□ Architecture

- A pattern, a template, a way of doing it
- Architecture declarations describe the **operation of the component**
- **Many architectures** may exist for one entity

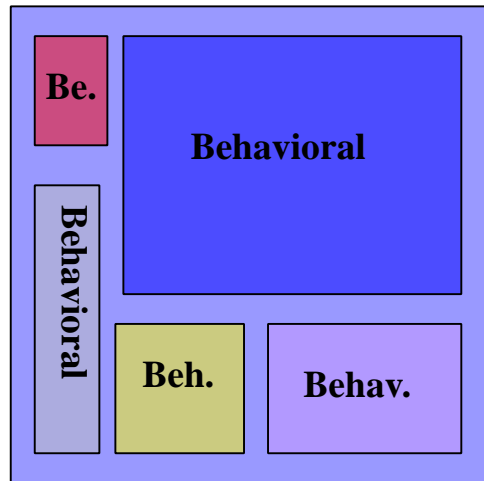
```
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use IEEE.std_logic_1164.all;  
ENTITY half_adder IS  
    PORT (x, y, enable: IN bit;  
          carry, result: OUT bit);  
END half_adder;  
ARCHITECTURE data_flow OF half_adder IS  
BEGIN  
    carry <= (x AND y) AND enable;  
    result <= (x XOR y) AND enable;  
END data_flow;
```



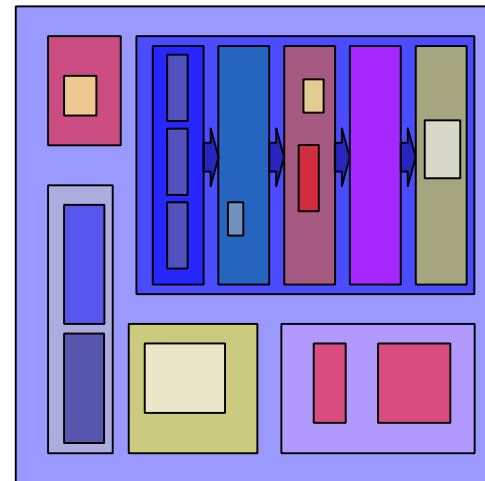
Architecture

□ Basically three types of architectures:

- Dataflow: how is the data transmitted from input to output
- Behavioral: using sequential processes
- Structural: top level, component instantiation, concurrent processes



Fully
behavioral



Pipelined
structural

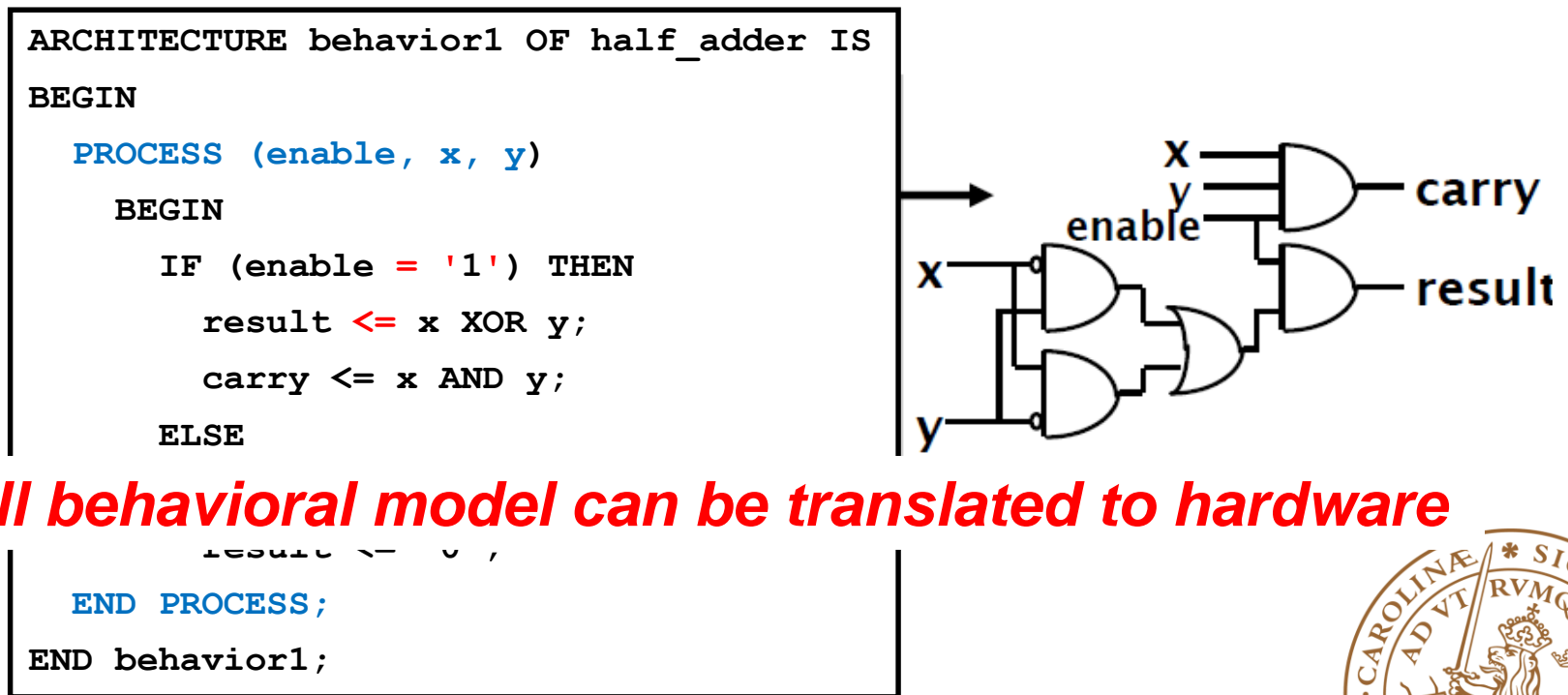


Architecture Body # 1

□ Behavioral Architecture: Describes the algorithm performed by the module, e.g., FSM

□ May contain

- Process statements
- Sequential statements
- Signal assignment statements



Not all behavioral model can be translated to hardware



Architecture Body # 2

□ **Structural architecture:** Implements a module as a composition of components (modules), a textual description of a **schematic**

□ **Contains**

- **Component, Signal declarations**

- *define the components (gates) and wires to be used*

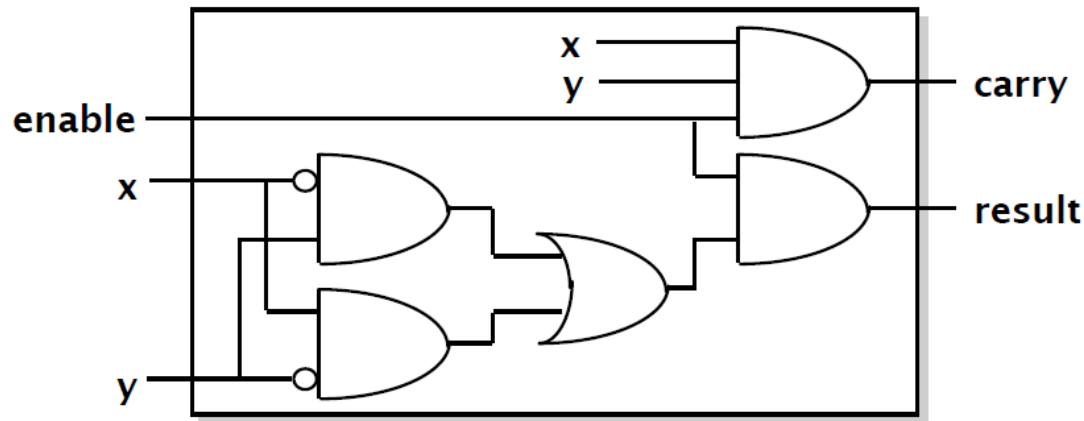
- *entity ports are treated as signals*

- **Component instances**

- *instances of previously declared entity/architecture pairs*

- **Port maps** in component instances

- *connect signals to component ports*



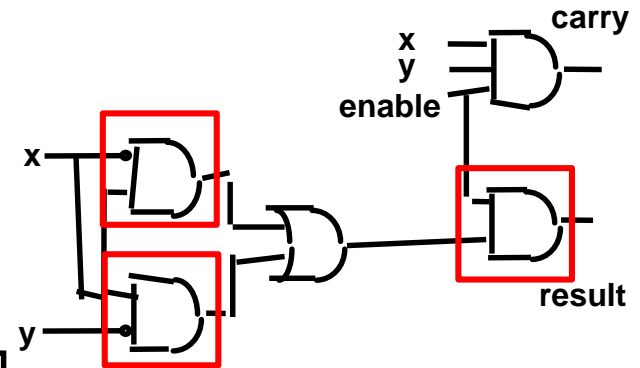
Architecture Body # 2 (cntd.)

```
ENTITY not_1 IS
    PORT (a: IN bit; output: OUT bit);
END not_1;

ARCHITECTURE data_flow OF not_1 IS
BEGIN
    output <= NOT(a);
END data_flow;
```

```
ENTITY and_2 IS
    PORT (a,b: IN bit; output: OUT bit);
END and_2;

ARCHITECTURE data_flow OF and_2 IS
BEGIN
    output <= a AND b;
END data_flow;
```



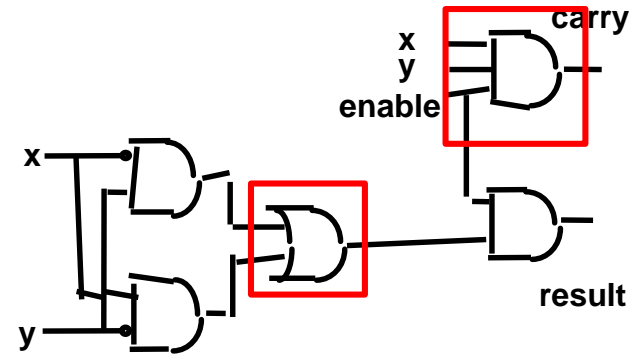
Architecture Body # 2 (cntd.)

```
ENTITY or_2 IS
    PORT (a,b: IN bit; output: OUT bit);
END or_2;

ARCHITECTURE data_flow OF or_2 IS
BEGIN
    output <= a OR b;
END data_flow;
```

```
ENTITY and_3 IS
    PORT (a,b,c: IN bit; output: OUT bit);
END and_3;

ARCHITECTURE data_flow OF and_3 IS
BEGIN
    output <= a AND b AND c;
END data_flow;
```



Architecture Body # 2 (cntd.)

ARCHITECTURE structural OF half adder IS

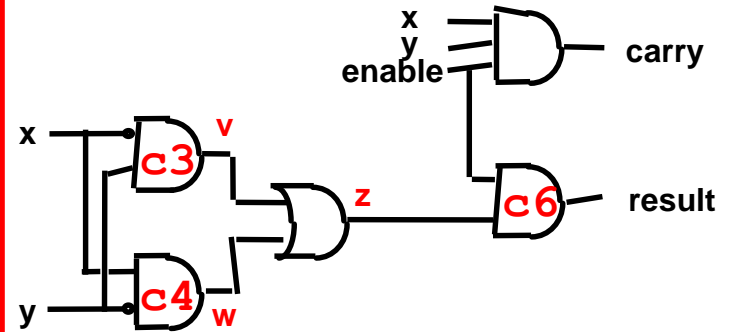
```
COMPONENT and2 PORT(a,b: IN bit; output: OUT bit); END COMPONENT;  
COMPONENT and3 PORT(a,b,c: IN bit; output: OUT bit); END COMPONENT;  
COMPONENT or2 PORT(a,b: IN bit; output: OUT bit); END COMPONENT;  
COMPONENT not1 PORT(a: IN bit; output: OUT bit); END COMPONENT;
```

```
SIGNAL v,w,z,nx,nz: BIT;
```

BEGIN

```
c1: not1 PORT MAP (a=>x,output=>nx);  
c2: not1 PORT MAP (y,ny);  
c3: and2 PORT MAP (nx,y,v);  
c4: and2 PORT MAP (x,ny,w);  
c5: or2 PORT MAP (v,w,z);  
c6: and2 PORT MAP (enable,z,result);  
c7: and3 PORT MAP (x,y,enable,carry);
```

END structural;



Advantages of Structural description

□ Hierarchy

- Allows for the simplification of the design

□ Component Reusability

- Allows the re-use of specific components of the design (Latch, Flip-flops, half-adders, etc)

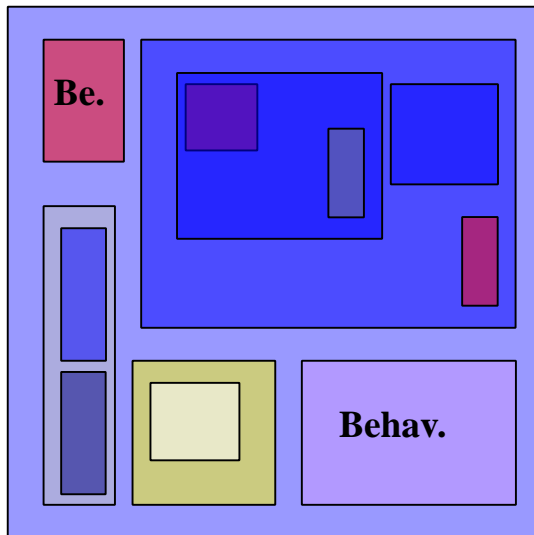
□ Design Independent

- Allows for replacing and testing components without redesigning the circuit



Architecture - Mixing Behavioral and Structural

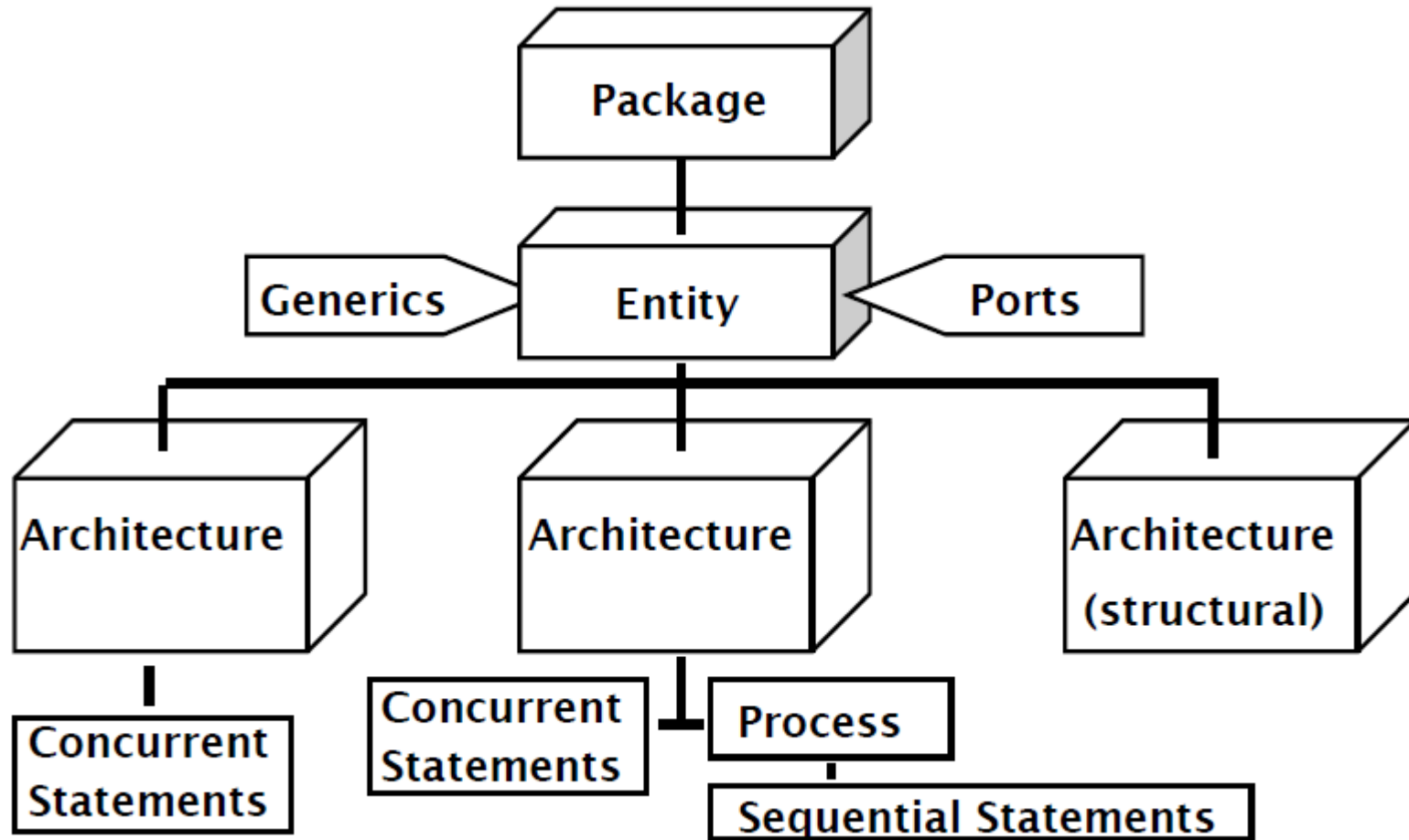
- An architecture may contain both behavioral and structural parts
 - Process statements and component instances
- Example: Register-Transfer-Level (RTL) model
 - **data path** described **structurally** (component)
 - **control section** described **behaviorally**



Partially behavioral.
& structural.



Summary



VHDL Process

- ❑ Contains a set of sequential statements to be executed sequentially
- ❑ Can be interpreted as a circuit part enclosed inside a black box
 - Model a circuit's **abstract behavior**
 - **Not ALL process can be mapped to hardware**
- ❑ Process statements:

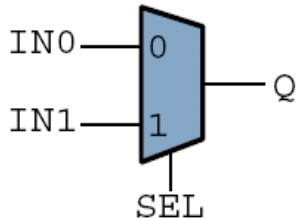
```
name_label: process (sensitivity list)
    variable declarations...
begin
    sequential statements...
- if ... then ... [else | elsif ...] end if;
- for n in 0 to 7 loop...
- case b is ...
- i := a + b; --variable assignment, only in processes
- c <= i; --signal assignment!
end process namelabel;
```



VHDL Process: Example 1

- A process is activated when a signal in the sensitivity list changes its value

Writing **combinational** components:



architecture BEHAV of MUX2 is

begin

```
process (INO, IN1, SEL);
```

sensitivity list

```
begin
```

```
Q <= IN0;
```

default assignment

```
if( SEL = '0' ) then
```

```
Q <= IN0;
```

```
elsif( SEL = '1' ) then
```

```
Q <= IN1;
```

```
end if;
```

```
end process;
```

```
end BEHAV;
```

For a component to be combinational:

1. All inputs **MUST** be present in the sensitivity list!
2. All outputs **MUST** be assigned on every run!

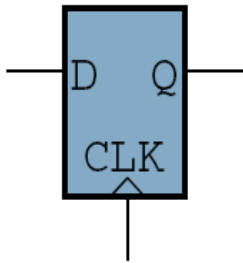
If conditions 1 and 2 above are not fulfilled,
THE SYNTHESIZED DESIGN WILL NOT WORK!



VHDL Process: Example 2

```
if rising_edge(clk) then  
if falling_edge(clk) then
```

Writing **sequential** (clocked) components:



Enable register with synchronous reset

```
process (clk)  
begin  
    if (clk'event and clk='1')  
    then  
        if (Reset = '0') then  
            Q <= '0';  
        elseif enable='1' then  
            Q <= D;  
        end if;  
    end if;  
end process ;
```

```
architecture GOOSE of FLIPFLOP is  
begin
```

```
    process ( CLK )  
    begin  
        if (CLK = '1') and (CLK'event) then  
            Q<=D;  
        end if;  
    end process;
```

```
end GOOSE;
```

the SENSITIVITY LIST

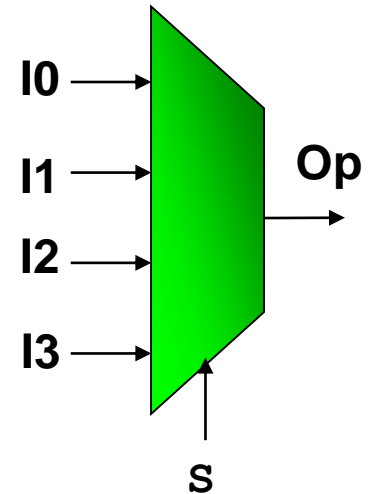
When a signal present in the sensitivity list changes, the process is run once, top to bottom.



Case Statement

□ Example: Multiplexer

```
architecture behv1 of Mux is
begin
process (I3, I2, I1, I0, S)  --inputs to process
begin -- use case statement
  case S is
    when "00" => Op <= I0;  --sequential statements
    when "01" => Op <= I1;
    when "10" => Op <= I2;
    when "11" => Op <= I3;
    when others => Op <= I0;
  end case;
end process;
end behv1;
```



Sequential Signal Assignment

□ Signal assignment in process

- Actual value of an expression will **NOT** be assigned to a signal until the **END** of the process
- No intermediate value

```
process (a, b, c, d)
begin
  y <= a or c;
  y <= a and b;
  y <= c and d;
end process;
```

```
process (a, b, c, d)
begin
  y <= c and d;
end process;
```

Avoid assigning a signal multiple times!



Outline

□ VHDL Background

- What is VHDL?
- Why VHDL?

□ Basic VHDL Component

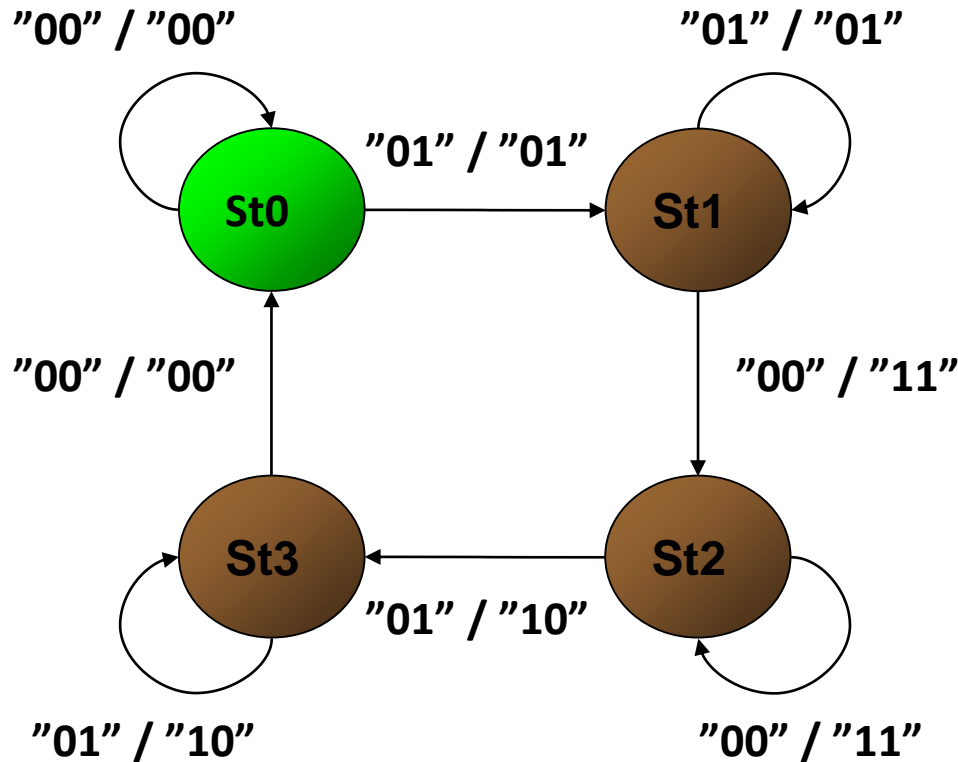
- A example

□ **FSM Design with VHDL**

□ Simulation & TestBench



Finite State Machine (FSM)

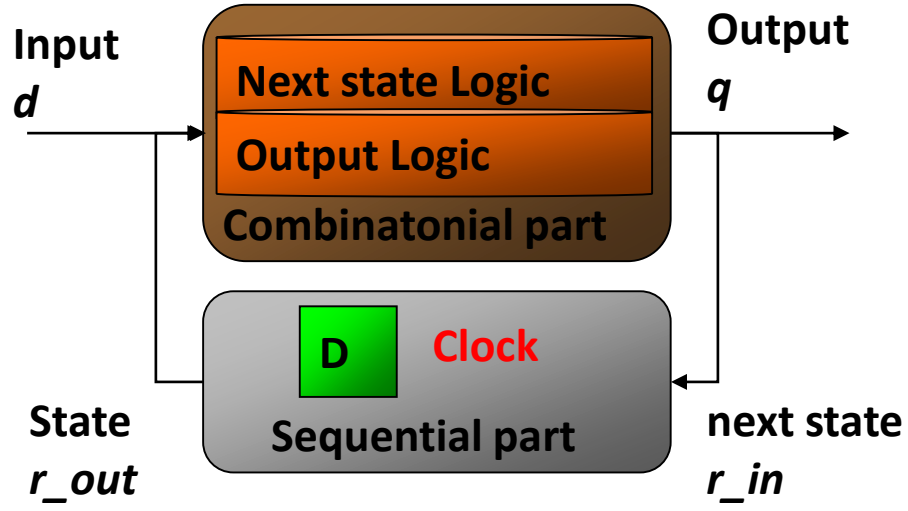
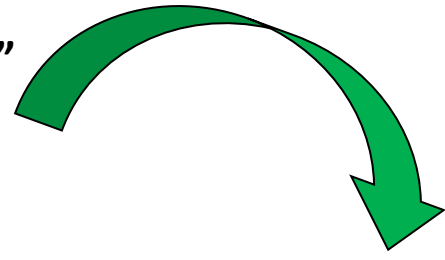
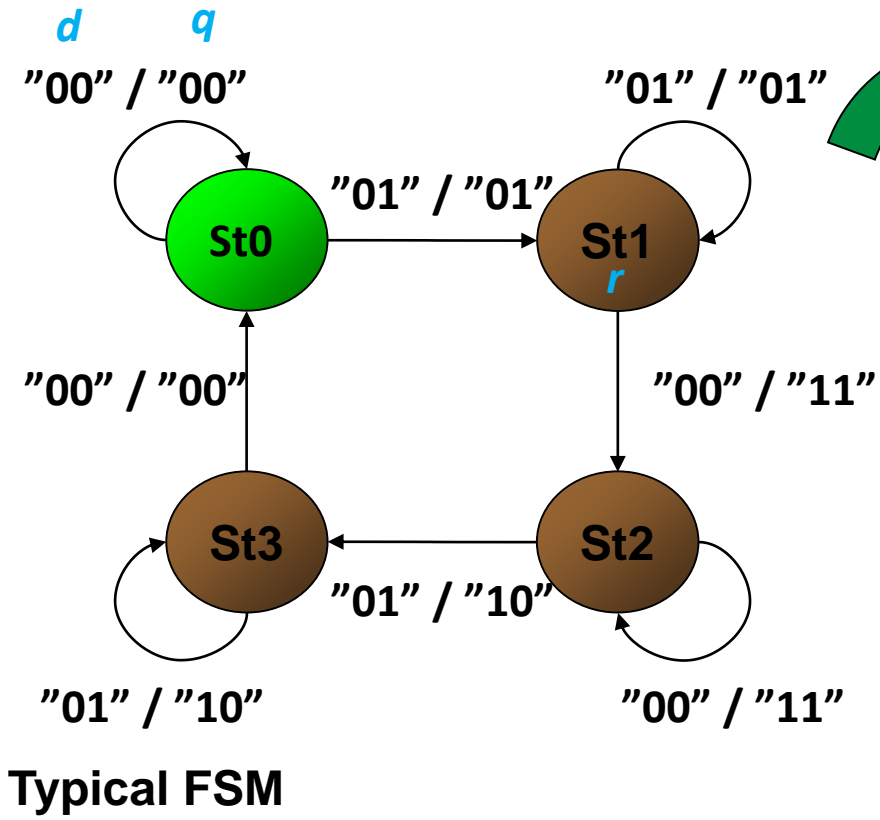


Output of a Mealy machine is **state** and **input** dependent

A Typical state machine



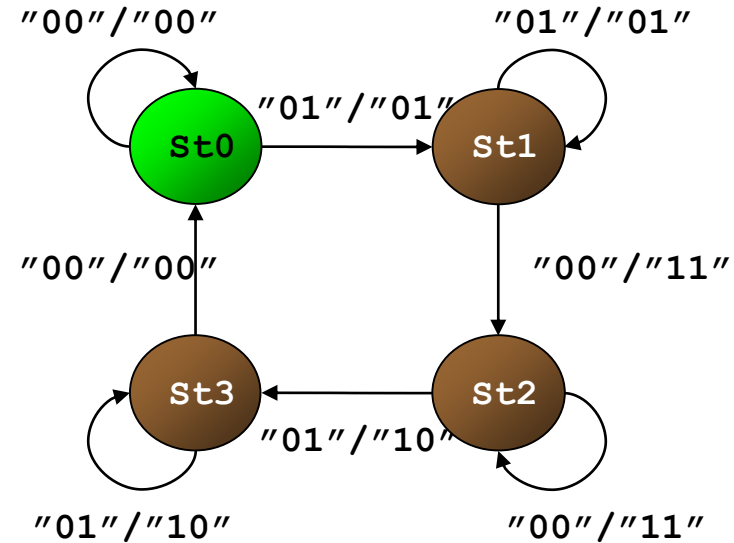
Transforming a State Diagram into HW



VHDL Realization of FSMs

Entity declaration

```
library IEEE;  
use IEEE.STD_LOGIC_1164.all;  
entity state_machine is  
    port (clk : in STD_LOGIC;  
          reset : in STD_LOGIC;  
          input : in STD_LOGIC_VECTOR(1 downto 0);  
          output : out STD_LOGIC_VECTOR(1 downto 0)  
          );  
end state_machine;
```



VHDL Realization of FSMs (cont'd)

Architecture declaration (combinational part)

```
architecture implementation of state machine is
```

```
type state_type is (st0,st1,st2,st3); -- Defines states;  
signal state, next_state : state_type;
```

```
begin
```

```
combinational : process (input,state)
```

```
begin
```

```
case (state) is -- Current state and input dependent
```

```
when st0 => if (input = "01") then  
             next_state <= st1;  
             output <= "01"
```

```
           else ...  
           end if;
```

```
when ....
```

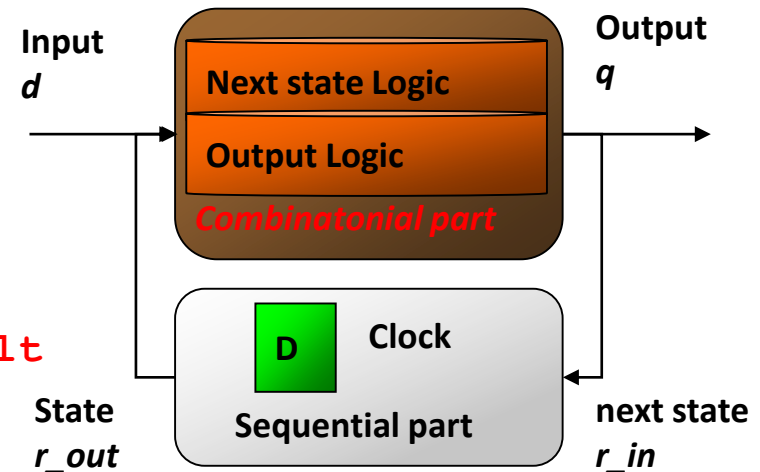
```
when others =>
```

```
    next_state <= st0; -- Default  
    output <= "00";
```

```
end case;
```

```
end process;
```

```
end implementation;
```



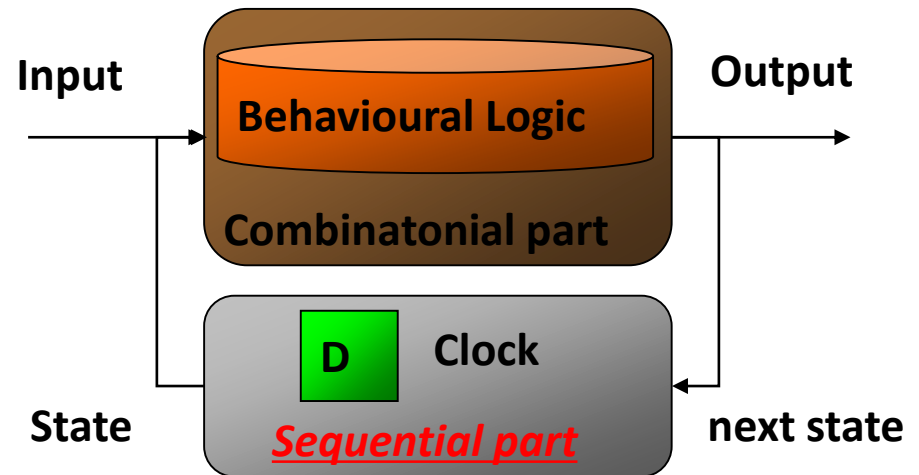
Suggestion: Use enumerate data type for states



VHDL Realization of FSMs (cont'd)

□ Architecture declaration (sequential part)

```
synchronous : process (clk)
begin
  if (clk'event and clk = '1') then
    if reset = '1' then
      state <= st0;
    else
      state <= next_state;
    end if;
  end if;
end process;
end architecture;
```



Generic Architecture for FSMs

Suggestion: Separate the processes of Comb. And Seq.



Outline

□ VHDL Background

- What is VHDL?
- Why VHDL?
- How to code VHDL?

□ Basic VHDL Component

- A example

□ FSM Design with VHDL

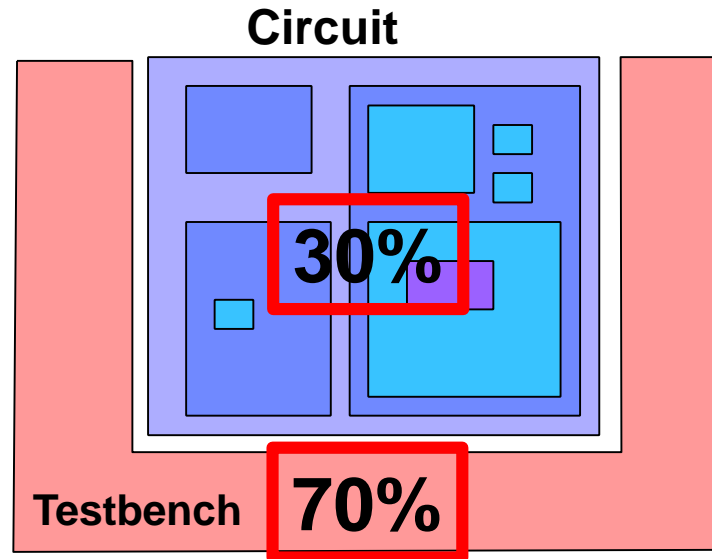
□ Simulation & TestBench



Testbench and Simulation

□ Testing: Testbench and Circuit

- The testbench models the environment our circuit is situated in.
- Provides stimuli (input to circuit) during simulation.
- May verify the output of our circuit against test vectors.
- Verification should be conducted at **ALL** design levels.



Testbench Example

Top level entity connecting the circuit to the testbench

```
entity testbench is
end testbench;
architecture test of testbench is
```

Component declaration of the circuit being tested

```
component circuit is
port (clk, reset, inputs, outputs);
end circuit;
signal inputs, outputs, clk, reset : type;
```

Clock generator

```
begin
clk_gen: process
begin
    if clk='1' then clk<='0';
    else clk<='1'; end if;
    wait for clk_period/2;
```

Reset signal generator

```
end process;
reset <= '1', '0' after 57 ns;
```

Component instantiation of the circuit being tested

```
device: circuit
    port map (clk, reset, inputs, outputs);
```

The tester, which generates stimuli (inputs) and verifies the response (outputs)

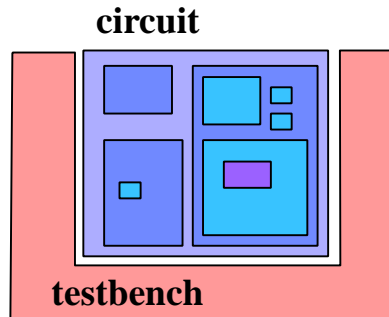
- The tester could also be a separate component.

```
tester: process (clk, reset)
begin
    ...
end process;
end testbench;
```



Testbench and Simulation: Testing larger circuits

□ Divide and conquer

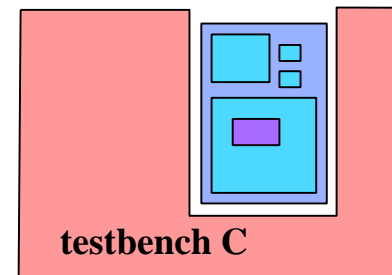
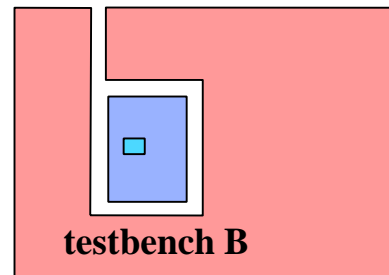
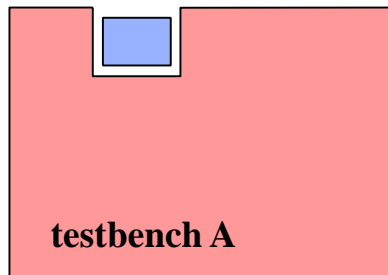


Test (simulation) fails !

What then ?

How can I find the bug ?

□ 3 subcomponents -> 3 subtests:



This will localize the problem or problems! Repeat the procedure if a faulty component consists of subcomponents, etc.

Overall Test is still needed!!!



Recommendation Readings

□ Mujtaba Hamid, “Writing Efficient Testbenches”, Xilinx Application Note

http://www.xilinx.com/support/documentation/application_notes/xapp199.pdf

□ “VHDL Test Bench Tutorial”, University of Pennsylvania

<http://www.seas.upenn.edu/~ese171/vhdl/VHDLTestbench.pdf>



Questions?

