

Källkod

```
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#define red_diode PD6
#define green_diode PD5
#define E PD0
#define RW PD1
#define RS PD4
unsigned int password = 1;
unsigned int count = 0;
unsigned int larm_status = 0;
unsigned int alarmactive = 0;
unsigned int data_available;
unsigned int pinCounter = 0;
unsigned char pinCode[4] = {'1', '2', '3', '4'};
unsigned char pinCodeTry[4];
unsigned char val;
unsigned int charnbr = 0;
unsigned int new_input = 0;
unsigned int sec = 0;
unsigned int min = 15;
unsigned int hour = 10;
unsigned int clock = 49911;
int timevect[8];

char read_keypad(char code){
    if(code == 0b00000000){
        return '0';
    }else if(code==0b00000100){
        return '1';
    }else if(code==0b00001000){
        return '2';
    }else if(code==0b00001100){
        return '3';
    }else if(code==0b00010000){
        return '4';
    }else if(code==0b00010100){
        return '5';
    }else if(code==0b00011000){
        return '6';
    }else if(code==0b00011100){
        return '7';
    }else if(code==0b00100000){
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        return '8';
    }else if(code==0b00100100){
        return '9';
    }else if(code==0b00101000){
        return 'A';
    }else if(code==0b00101100){
        return 'B';
    }else if(code==0b00110000){
        return 'C';
    }else if(code==0b00110100){
        return 'D';
    }else if(code==0b00111000){
        return 'E';
    }else if(code==0b00111100){
        return 'F';
    }
}

int main(void)
{
    INIT();
    _delay_ms(5);
    val=0xff;
    _delay_ms(5);
    start_Display();
    _delay_ms(5);
    set_Display();
    _delay_ms(5);
    clear_display();
    _delay_ms(5);
    write_welcome();

    while (1)
    {

        if(larm_status == 2){
            alarmtriggered();
        }

        while(new_input == 1){
            char input = read_keypad(val);

            if(input == 'A' ){

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int pincount = 0;
while(pincount < 3){
    clear_display();
    write_activatelarm();
    new_input = 0;
    for(int k =0; k<4; k++){

        while(new_input == 0){
            }

            char pin = read_keypad(val);
            pinCodeTry[k] = pin;
            write_char('*');
            new_input = 0;
        }
        int wrong = 0;
        for(int i=0; i<4;i++){
            if(pinCodeTry[i] !=pinCode[i]){
                wrong = 1;
            }
        }
        if(wrong == 0){
            clear_display();
            alarm_ON();
            new_input = 0;
            pincount = 3;
        } else {
            pincount++;
            write_wrongcode();
            if(pincount == 3){
                clear_display();
                larm_status = 2;
                new_input =0;
            }
        }
    }
}
if(input == 'D'){
    int pincount = 0;
    while(pincount < 3){
        clear_display();
        write_deactivatelarm();
        new_input = 0;
        for(int k =0; k<4; k++){

            while(new_input == 0){

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        }

        char pin = read_keypad(val);
        pinCodeTry[k] = pin;
        write_char('*');
        new_input = 0;
    }
    int wrong = 0;
    for(int i=0; i<4;i++){
        if(pinCodeTry[i] !=pinCode[i]){
            wrong = 1;
        }
    }
    if(wrong == 0){
        clear_display();
        alarm_OFF();
        new_input = 0;
        pincount = 3;
    } else {
        pincount++;
        write_wrongcode();
        _delay_ms(5000);
        if(pincount == 3){
            clear_display();
            larm_status = 2;
            new_input =0;
        }
    }
}

if(input == 'C'){
    int pincount = 0;
    while(pincount < 3){
        new_input = 0;
        clear_display();
        write_oldcode();
        for(int k =0; k<4; k++){

            while(new_input == 0){
            }

            char pin = read_keypad(val);
            pinCodeTry[k] = pin;
            write_char('*');
            new_input = 0;

```

```

}
int wrong = 0;

for(int i=0; i<4;i++){
    if(pinCodeTry[i] !=pinCode[i]){
        wrong = 1;
    }
}
if(wrong == 0){
    clear_display();
    write_newcode();
    new_input = 0;
    for(int i=0;i<4;i++){

        while(new_input == 0){

            char newPin = read_keypad(val);
            pinCode[i] = newPin;
            write_char(newPin);
            new_input = 0;

        }
        new_input = 0;
        pincount = 3;
        clear_display();
    } else {
        pincount++;
        write_wrongcode();
        _delay_ms(5000);
        if(pincount == 3){
            clear_display();
            larm_status = 2;
            new_input = 0;
        }
    }
}
}
}
}
}
}
}
}
}

ISR(TIMER1_OVF_vect) {
    sec++;
    if(sec == 60){
        min++;

```

```

        sec = 0;
        if(min == 60){
            hour++;
            min = 0;
            if(hour == 24){
                hour = 0;
            }
        }
    }
}

```

```

ISR(INT0_vect){
    val = PINA & 0b00111100;
    new_input = 1;
}

```

```

ISR(INT1_vect){
    if(larm_status==1){
        larm_status = 2;
    }
}

```

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void INIT(){ // Sätter initialtillstånden
    DDRB = 0b11111111; //vi sätter databussen ut
    DDRA = 0b00000000; //vi sätter a-porten in
    DDRD = 0b11110011; //vi sätter RS, RW, E ut
    DDRC = 0b00000000; // C-porten in
    PORTD = 0b00001100; //vi sätter RS till 0 och E till 0 även interupt 1
    GICR = 0b11000000;
    MCUCR = 0b0001111;
    TCCR1B = 0b00000101; //inställning för klockan (vet ej om bit 6 ska vara 0

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eller 1)

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    TCNT1 = clock;
    TIMSK = 0b00000100; // Ska sätta hur ofta interuptet skjer, hur??
    sei();

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}

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void display_int(int time){
    int time1 = time/10;
    itoa(time1, timevect, 10);
    write_char(timevect[0]);
}

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        int time2 = time%10;
        time1 = itoa(time2, timevect, 10);
        write_char(timevect[0]);
    }

void showTime(int hour, int min, int sec){
    display_int(hour);
    write_char(':');
    display_int(min);
    write_char(':');
    display_int(sec);
}

void clear_display(){
    _delay_ms(10);

    PORTB = 0b00000001;
    PORTD |= _BV(E);
    PORTD &= ~_BV(E);
    _delay_ms(10);
}

void change_curser(){
    char location = 0x40;
    if(location < 0b01111111){
        PORTB = 0b10000000 | location;
        PORTD |= _BV(E);
        PORTD &= ~_BV(E);
    }
}

void set_Display(){
    PORTB = 0b00111100; // Ska sista två vara nollor? - i datablad
    PORTD |= _BV(E);
    PORTD &= ~_BV(E);
}

void start_Display(){ // Används även denna för off? Behövs off?
    PORTB = 0b00001111;
    PORTD |= _BV(E); // Sätter E till 1
    PORTD &= ~_BV(E); // Sätter E till 0
}

void write_char(char ch){
    _delay_ms(5);
    PORTD |= _BV(RS); // Sätter RS hög
}

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        _delay_ms(5);
        PORTB = ch;
        _delay_ms(5);
        PORTD |= _BV(E); // Sätter E hög
        _delay_ms(5);
        PORTD &= ~_BV(E); // Sätter E låg
        _delay_ms(5);
        PORTD &= ~_BV(RS); // Sätter rs låg
    }

void write_int(int i){
    _delay_ms(5);
    PORTD |= _BV(RS); // Sätter RS hög
    _delay_ms(5);
    PORTB = i;
    _delay_ms(5);
    PORTD |= _BV(E); // Sätter E hög
    _delay_ms(5);
    PORTD &= ~_BV(E); // Sätter E låg
    _delay_ms(5);
    PORTD &= ~_BV(RS); // Sätter rs låg
}

void write_cmd(char cmd){
    _delay_ms(5);
    PORTB = cmd;
    PORTD &= ~_BV(PD4); // Sätter RS låg
    PORTD &= ~_BV(PD0); // Sätter E låg
    PORTD |= _BV(PD4); // Sätter RS hög
    PORTD |= _BV(PD0); // Sätter E hög
}

void write_AlarmON(){
    clear_display();
    _delay_ms(5);
    write_char('A');
    write_char('L');
    write_char('A');
    write_char('R');
    write_char('M');
    write_char(' ');
    write_char('O');
    write_char('N');
}

void write_AlarmOFF(){

```



```
clear_display();
_delay_ms(5);
write_char('A');
write_char('L');
write_char('A');
write_char('R');
write_char('M');
write_char(' ');
write_char('O');
write_char('F');
write_char('F');
}
```

```
void write_wrongcode(){
clear_display();
_delay_ms(5);
write_char('W');
write_char('R');
write_char('O');
write_char('N');
write_char('G');
write_char(' ');
write_char('C');
write_char('O');
write_char('D');
write_char('E');
}
```

```
void write_oldcode(){
clear_display();
_delay_ms(5);
write_char('O');
write_char('L');
write_char('D');
write_char(' ');
write_char('C');
write_char('O');
write_char('D');
write_char('E');
write_char(':');
change_cursor();
}
```

```
void write_newcode(){
clear_display();
```

```

        _delay_ms(5);
        write_char('N');
        write_char('E');
        write_char('W');
        write_char(' ');
        write_char('C');
        write_char('O');
        write_char('D');
        write_char('E');
        write_char(':');
        change_curser();
    }
void write_welcome(){
    clear_display();
    _delay_ms(5);
    write_char('W');
    write_char('E');
    write_char('L');
    write_char('C');
    write_char('O');
    write_char('M');
    write_char('E');
    write_char(' ');
    write_char('T');
    write_char('O');
    change_curser();
    write_char('L');
    write_char('A');
    write_char('R');
    write_char('M');
    write_char(' ');
    write_char('M');
    write_char('A');
    write_char('S');
    write_char('T');
    write_char('E');
    write_char('R');
}
void write_activatelarm(){
    clear_display();
    _delay_ms(5);
    write_char('A');
    write_char('C');
    write_char('T');
    write_char('I');
    write_char('V');
}

```

```

        write_char('A');
        write_char('T');
        write_char('E');
        write_char(' ');
        write_char('L');
        write_char('A');
        write_char('R');
        write_char('M');
        write_char(':');
        change_curser();
    }
void write_deactivatelarm(){
    clear_display();
    _delay_ms(5);
    write_char('D');
    write_char('E');
    write_char('A');
    write_char('C');
    write_char('T');
    write_char('I');
    write_char('V');
    write_char('A');
    write_char('T');
    write_char('E');
    write_char(' ');
    write_char('L');
    write_char('A');
    write_char('R');
    write_char('M');
    write_char(':');
    change_curser();
}

void triggered_at(){
    clear_display();
    _delay_ms(5);
    write_char('T');
    write_char('R');
    write_char('I');
    write_char('G');
    write_char('G');
    write_char('E');
    write_char('R');
    write_char('E');
    write_char('D');
    write_char(' ');

```

```

        write_char('A');
        write_char('T');
        write_char(':');
        change_curser();
        _delay_ms(5);
    }

// LED
void greenDiode_ON(){
    PORTD |= _BV(green_diode);
    PORTD &= ~_BV(PD0);
    PORTD |= _BV(PD0);
}

void redDiode_ON(){
    PORTD |= _BV(red_diode);
    PORTD &= ~_BV(PD0);
    PORTD |= _BV(PD0);
}

void greenDiode_OFF(){
    PORTD &= ~_BV(green_diode);
    PORTD &= ~_BV(PD0);
    PORTD |= _BV(PD0);
}

void redDiode_OFF(){
    PORTD &= ~_BV(red_diode);
    PORTD &= ~_BV(PD0);
    PORTD |= _BV(PD0);
}

void summer_ON(){
    PORTD |= _BV(PD7);
    PORTD &= ~_BV(E);
    PORTD |= _BV(E);
}

void summer_OFF(){
    PORTD &= ~_BV(PD7);
    PORTD &= ~_BV(PD0);
    PORTD |= _BV(PD0);
}

void alarm_ON(){
    larm_status = 1;
    greenDiode_OFF();
    redDiode_ON();
}

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```

        write_AlarmON();
    }

void alarm_OFF(){
    redDiode_OFF();
    greenDiode_ON();

    larm_status = 0;
    summer_OFF();
    write_AlarmOFF();
}

void alarmtriggered(){
    clear_display();
    triggered_at();
    showTime(hour, min,sec);
while(read_keypad(val) != 'D'){
    summer_ON();
        redDiode_ON();
        _delay_ms(1000);
        summer_OFF();
    redDiode_OFF();
        _delay_ms(1000);
    }
    if(larm_status == 2){
        summer_ON();
        redDiode_ON();
    }
}
}

```