

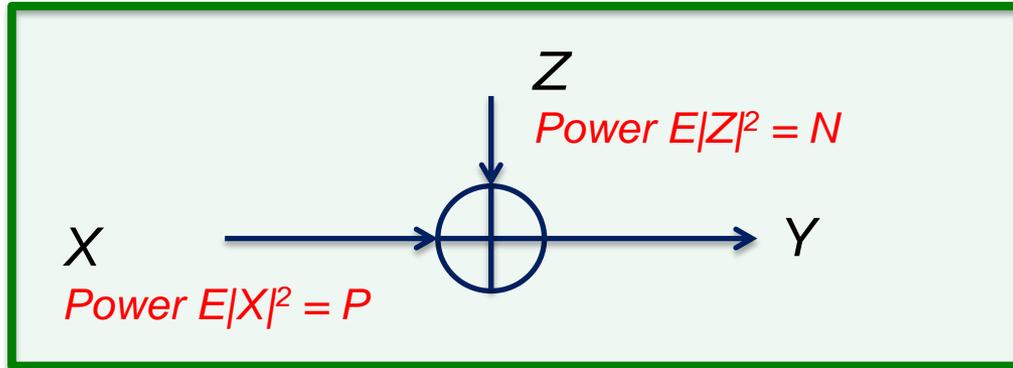
# Digital Communications

**Fredrik Rusek**

Chapter 14,  
Fading Channels II: Capacity (but almost  
no coding)  
Proakis-Salehi

# Brief review of capacity

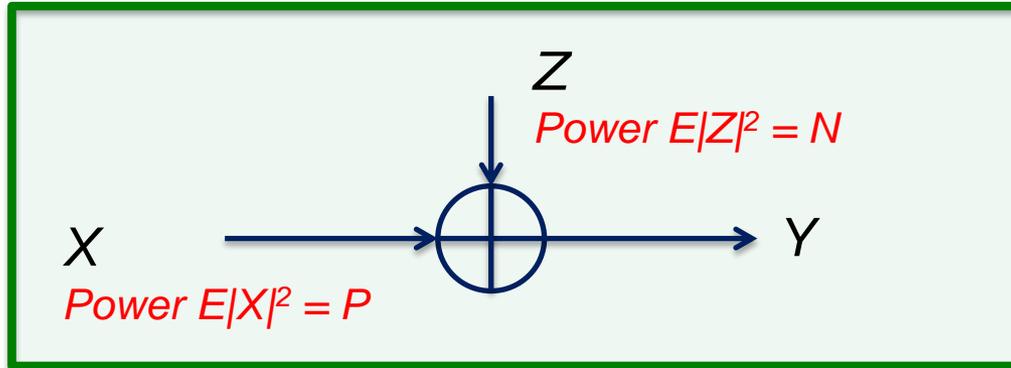
Capacity of AWGN channel (real-valued)



$$C = \frac{1}{2} \log \left( 1 + \frac{P}{N} \right)$$

# Brief review of capacity

Capacity of AWGN channel (real-valued)



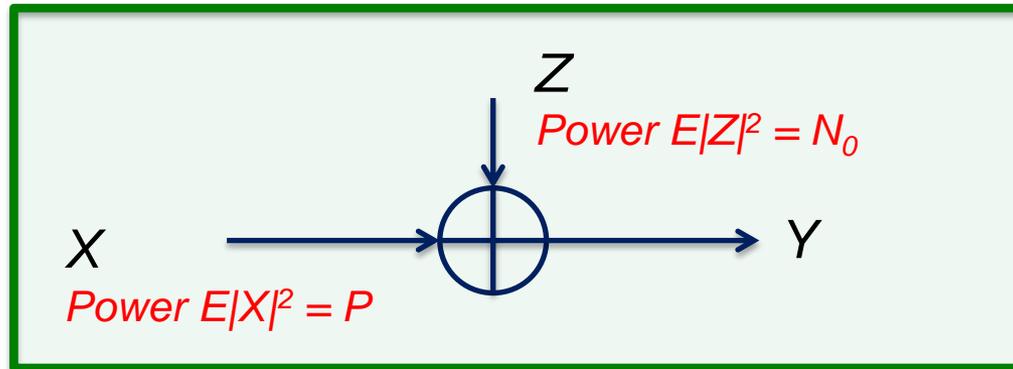
$$C = \frac{1}{2} \log \left( 1 + \frac{P}{N} \right)$$

Let  $N = N_0/2$

$$C = \frac{1}{2} \log \left( 1 + \frac{2P}{N_0} \right)$$

# Brief review of capacity

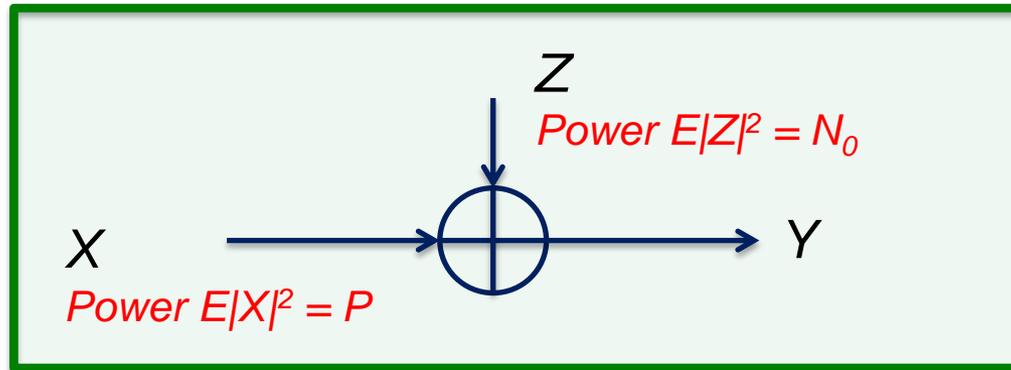
Capacity of AWGN channel (**Complex valued**)



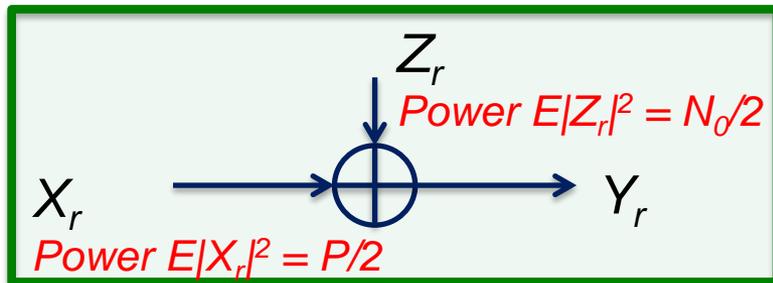
**Note:**  $N_0$  and not  $N_0/2$

# Brief review of capacity

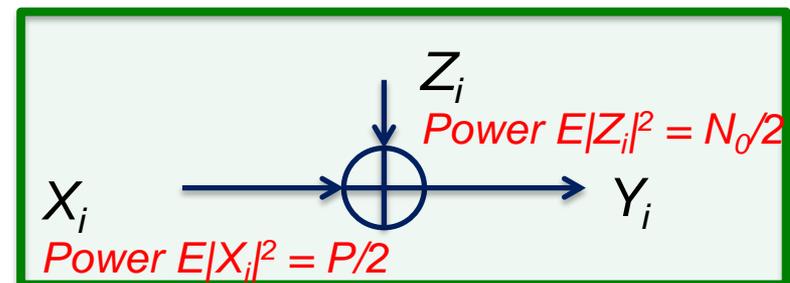
Capacity of AWGN channel (**Complex valued**)



A complex channel is equivalent to two real valued channels.



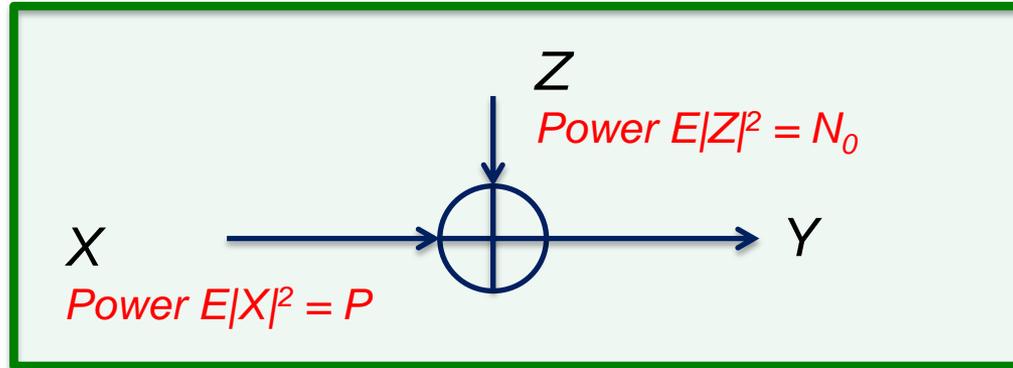
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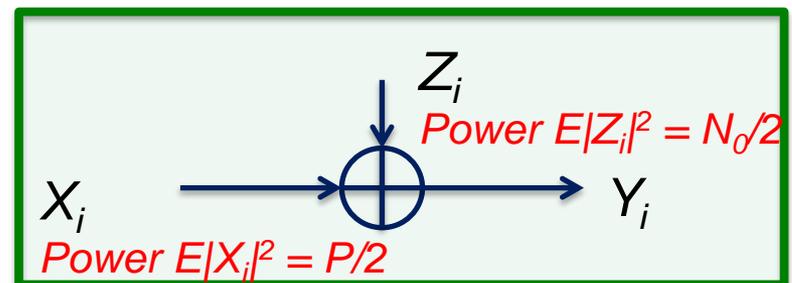
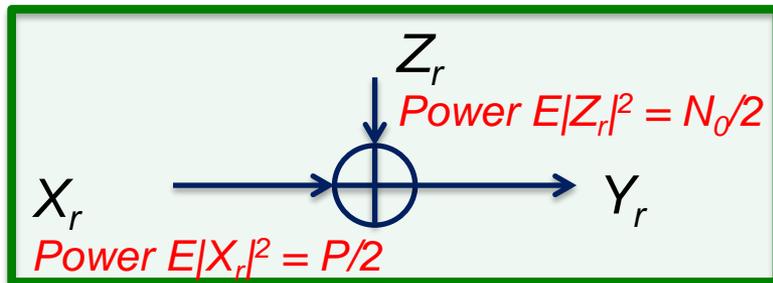
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# Brief review of capacity

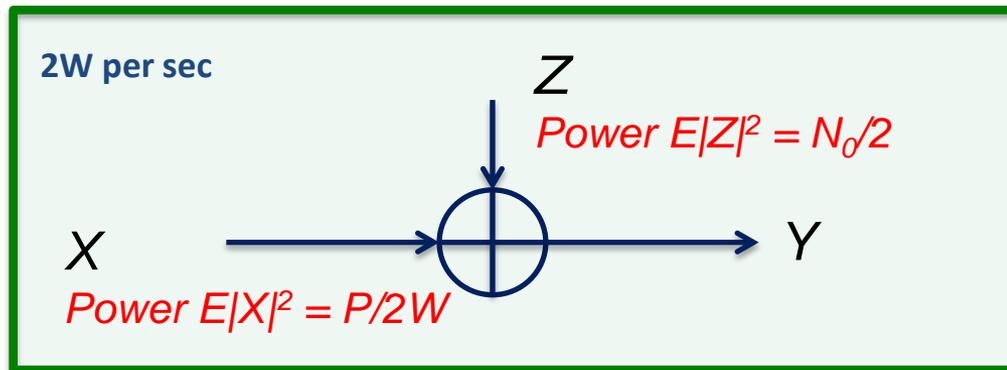
Assume a channel bandlimited to  $W$  positive Hz and input power of  $P$  W

Due to the sampling theorem,  
bandwidth  $W$  specifies  $2W$   
orthonormal dimensions per second.  
Power in each is  $P/2W$

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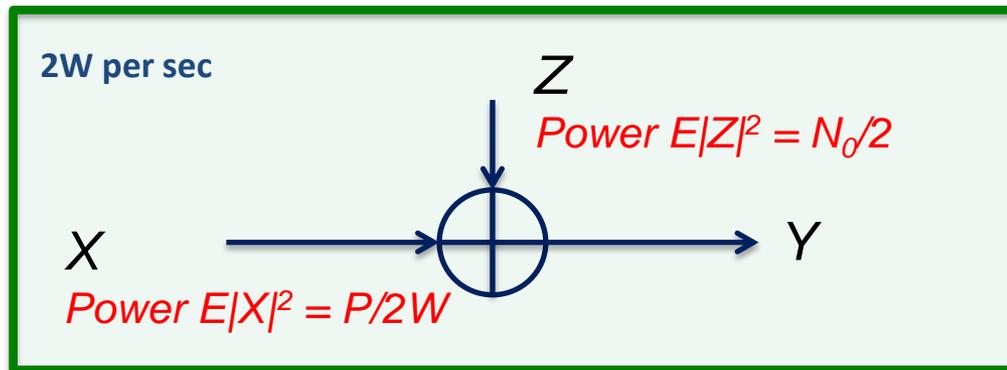
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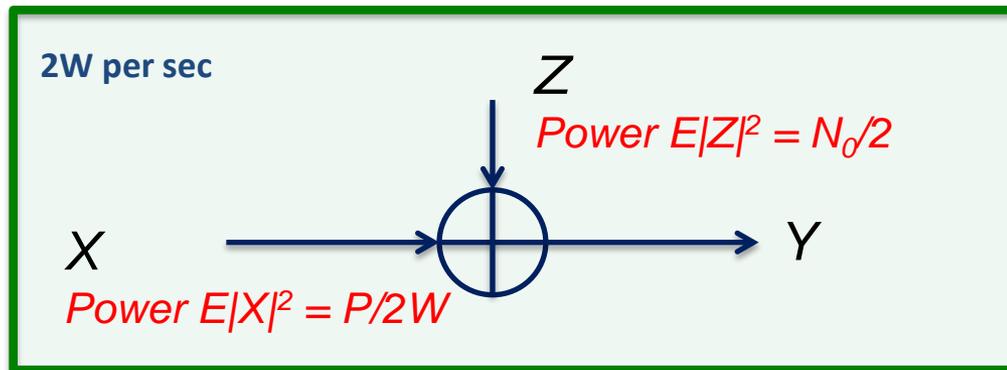
Capacity per channel use

$$C = \frac{1}{2} \log \left( 1 + \frac{P}{N_0 W} \right)$$

# Brief review of capacity

Assume a channel bandlimited to  $W$  positive Hz and input power of  $P$  W

Due to the sampling theorem, bandwidth  $W$  specifies  $2W$  orthonormal dimensions per second. Power in each is  $P/2W$



Capacity per channel use  $C = \frac{1}{2} \log \left( 1 + \frac{P}{N_0 W} \right)$       Capacity per second  $C = W \log \left( 1 + \frac{P}{N_0 W} \right)$

# Brief review of water filling

Now assume a frequency selective channel  $y(t) = x(t) \star c(t) + n(t)$

From chapter  
11 (easy)

$$C = \frac{1}{2} \int_{-\infty}^{\infty} \log \left( 1 + \frac{P(f)|C(f)|^2}{S_n(f)} \right) df$$

**Waterfilling:**  
Graphical  
solution to the  
optimization  
problem

$$\begin{aligned} \max_{P(f)} \quad & C = \frac{1}{2} \int_{-\infty}^{\infty} \log \left( 1 + \frac{P(f)|C(f)|^2}{S_n(f)} \right) df \\ \text{S.t.} \quad & \int_{-\infty}^{\infty} P(f) df = 1 \end{aligned}$$

# Brief review of water filling

Solution.

$$\begin{aligned} \max_{P(f)} \quad & C = \frac{1}{2} \int_{-\infty}^{\infty} \log \left( 1 + \frac{P(f)|C(f)|^2}{S_n(f)} \right) df \\ \text{S.t.} \quad & \int_{-\infty}^{\infty} P(f) df = 1 \end{aligned}$$

Add a Lagrange multiplier to handle the constraint

$$\int_W \left\{ \log_2 \left[ 1 + \frac{P(f)|C(f)|^2}{S_{nn}(f)} \right] + \lambda P(f) \right\} df$$


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Euler - Lagrange equation

With  $S(q) = \int_a^b L(t, q(t), q'(t)) dt$

condition for a stationary point

$$L_q(t, q(t), q'(t)) - \frac{d}{dt} L_{q'}(t, q(t), q'(t)) = 0.$$

$S$  is functional (function from the space of functions to the reals)

$q$  is function of  $t$

$L$  is function of three variables

# Brief review of water filling

Solution.

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In our case:

- $P$  is  $q$ ,  $f$  is  $t$ .
- Derivative of  $L$  with respect to  $q'$  is 0

# Brief review of water filling

Solution.

$$\max_{P(f)} C = \frac{1}{2} \int_{-\infty}^{\infty} \log \left( 1 + \frac{P(f)|C(f)|^2}{S_n(f)} \right) df$$

$$\text{S.t. } \int_{-\infty}^{\infty} P(f) df = 1$$

Add a Lagrange multiplier to handle the constraint

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# Brief review of water filling

This gives

$$\frac{1}{P(f) + S_{nn}(f)/|C(f)|^2} + \lambda = 0$$

$P(f) + S_{nn}(f)/|C(f)|^2$  is a constant adjusted to satisfy the power constraint

$$\begin{aligned} \max_{P(f)} \quad & C = \frac{1}{2} \int_{-\infty}^{\infty} \log \left( 1 + \frac{P(f)|C(f)|^2}{S_n(f)} \right) df \\ \text{S.t.} \quad & \int_{-\infty}^{\infty} P(f) df = 1 \end{aligned}$$

**Waterfilling**

$$P(f) = \left( K - \frac{S_n(f)}{|C(f)|^2} \right)^+$$

$$x^+ = \max\{0, x\}$$

# Brief review of water filling

This gives

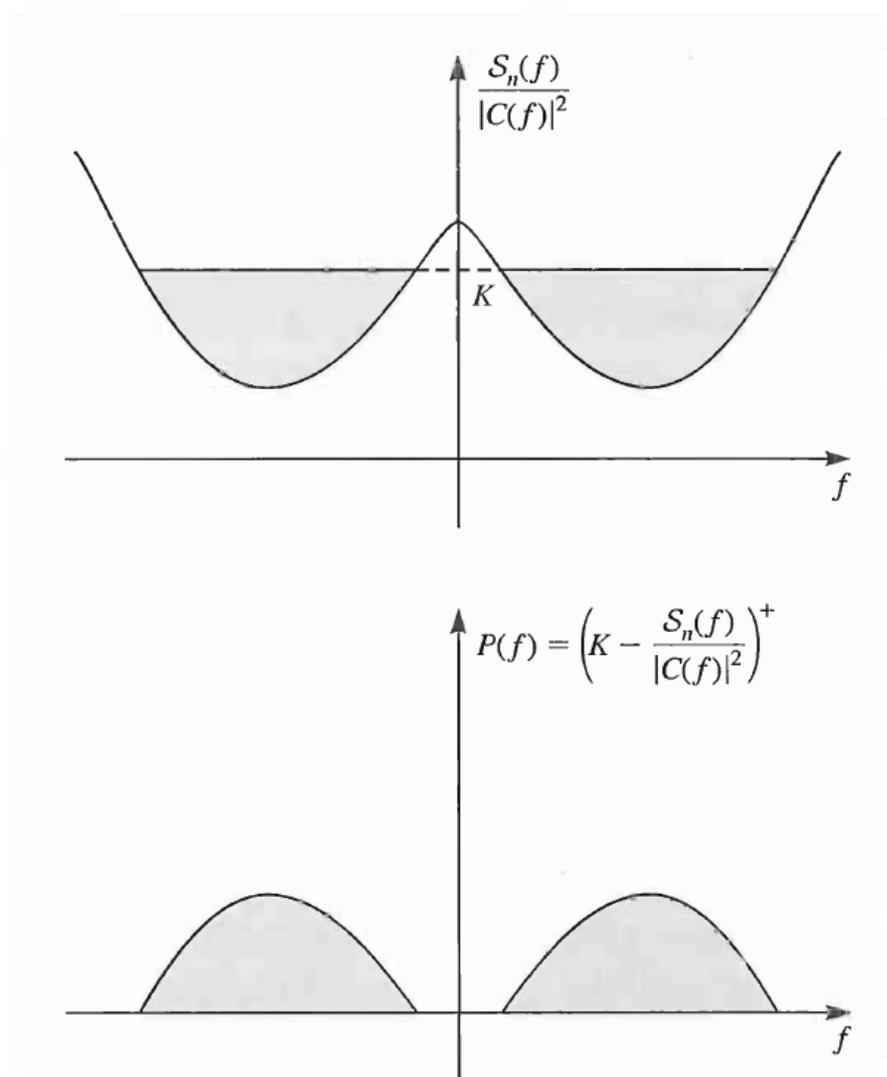
$$\frac{1}{P(f) + \mathcal{S}_{nn}(f)/|C(f)|^2} + \lambda = 0$$

$$P(f) + \mathcal{S}_{nn}(f)|C(f)|^2$$

**Waterfilling**

$$P(f) = \left( K - \frac{\mathcal{S}_n(f)}{|C(f)|^2} \right)^+$$

$$x^+ = \max\{0, x\}$$



# Brief review of water filling

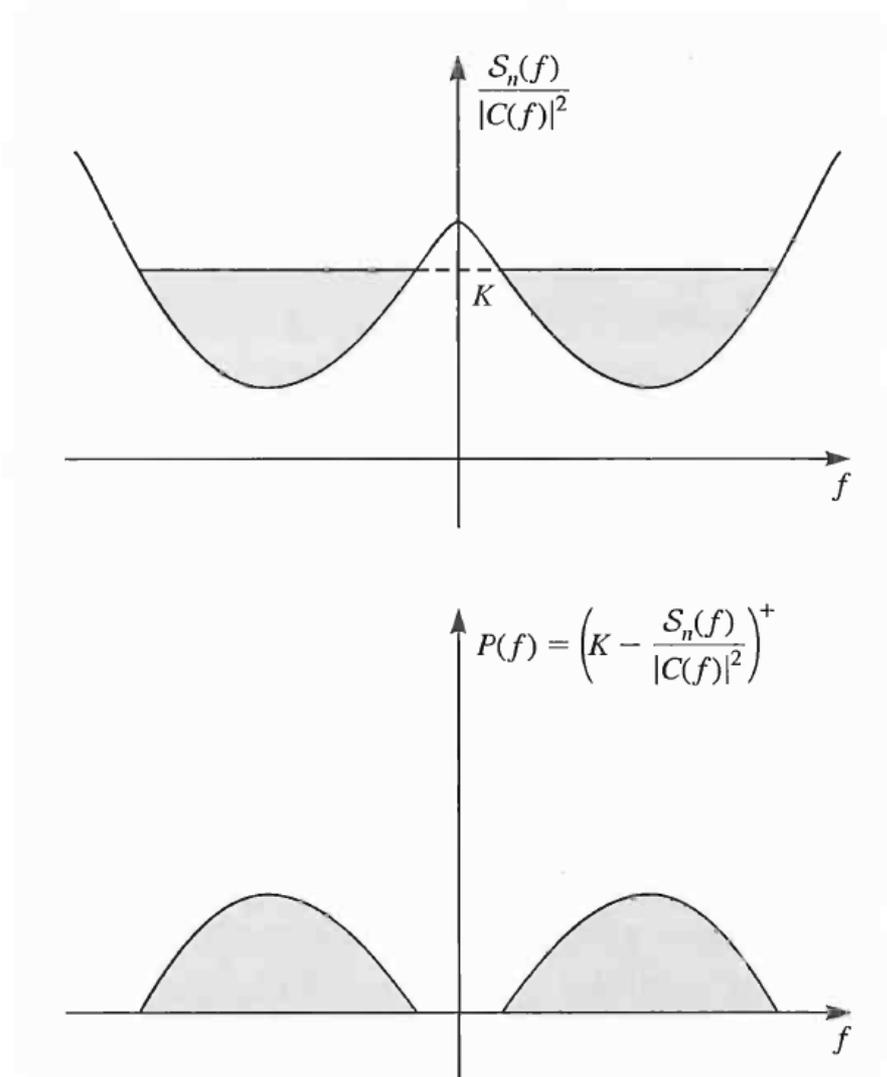
Works also for N discrete parallel channels

$$C = \frac{1}{2} \sum_{i=1}^N \log \left( 1 + \frac{P_i}{N_i} \right)$$

## Waterfilling

$$P_i = (K - N_i)^+$$

$$\sum_{i=1}^N P_i = P$$



# 14.1-1 finite state machines

**Warning: hard to read. (p.904)**

$$C = \max_{p(t)} I(T; Y|V) \quad (14.1-19)$$

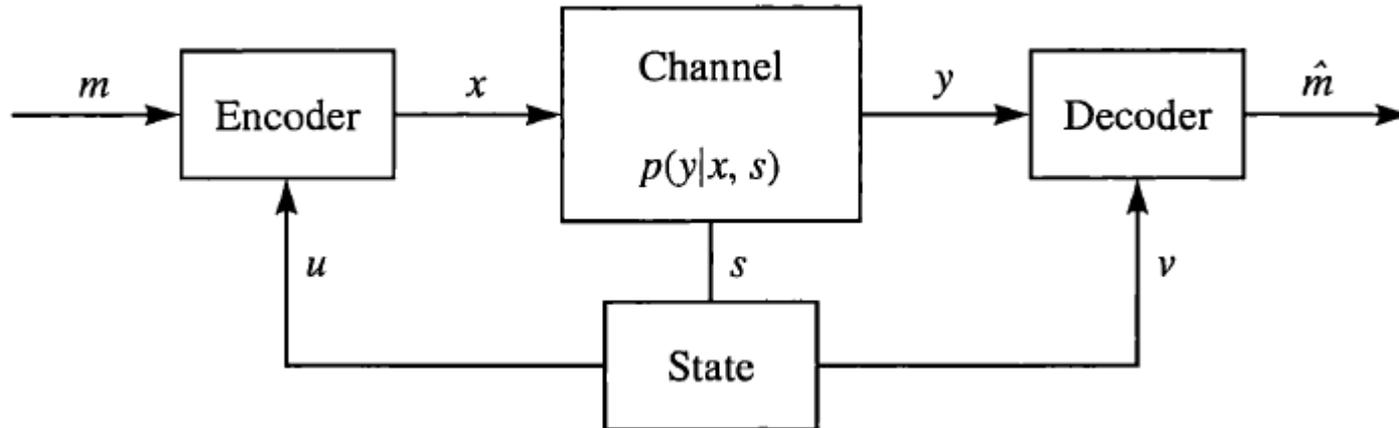
**T** is (at least to me) completely undefined. I don't know what it is.

Switch these two

ular interest. The special case where U = S and V is a degenerate random variable corresponds to the case when complete *channel state information* (CSI) is available at the receiver and no channel state information is available at the transmitter. In this case

# 14.1-1 finite state machines

## System model

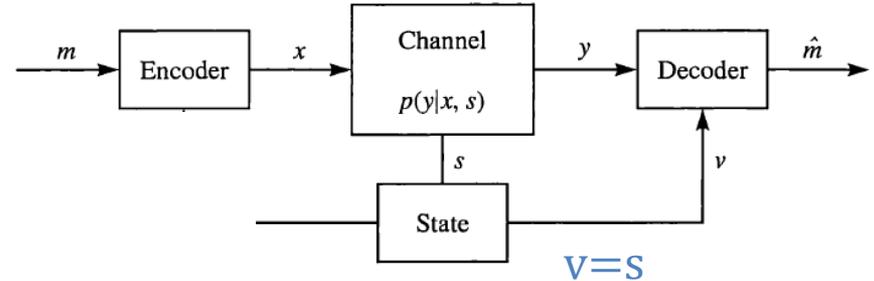


- Channel behavior changes over time. Channel is described by variable  $s$
- A finite number of different  $s$
- Transmitter has some knowledge about the state, represented by  $u$
- Receiver has some knowledge about the state, represented by  $v$
- $u = s = v$  is perfect CSI both at Rx and Tx
- $u = 0, v = s$  is perfect CSI at Rx, no CSI at Tx

**What is the capacity?**

# 14.1-1 finite state machines

Let us start with the case  
of perfect CSI at Rx, no CSI  
at Tx



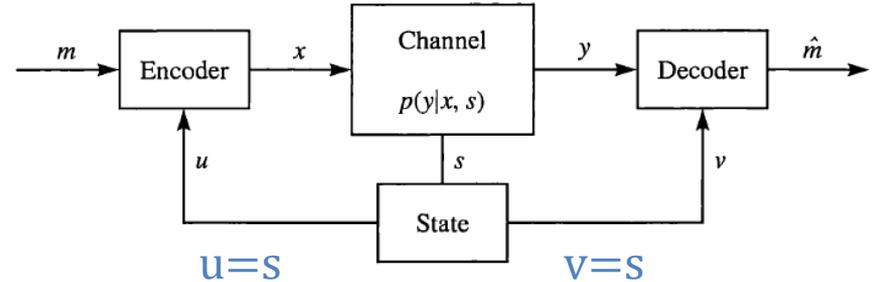
Capacity is [Schlomo Shamai, Guiseppe Caire '1999]

$$C = \max_{p(x)} I(X; Y|S) = \max_{p(x)} \sum_s p(s) I(X; Y|S = s)$$

The task of the Tx is to choose the distribution on  $x$ , that maximizes the averaged mutual information over the channel states.

# 14.1-1 finite state machines

Perfect CSI at Rx and Tx



Capacity is

$$C = \max_{p(x|s)} I(X; Y|S) = \sum_s p(s) \max_{p(x|s)} I(X; Y|S = s)$$

The task of the Tx is to choose the distribution on  $x$ , that maximizes the instantaneous mutual information.

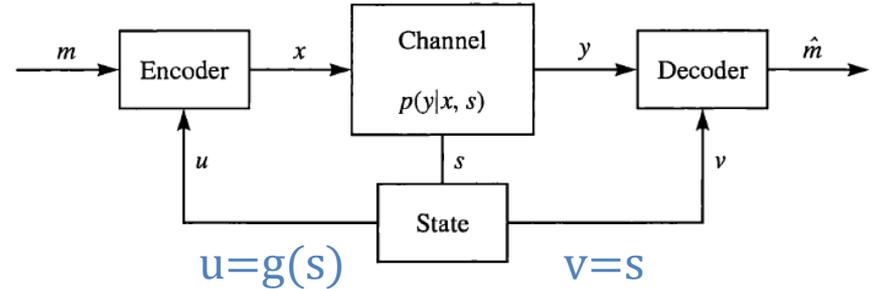
This is the expectation of the channel capacity

# 14.1-1 finite state machines

## Limited feedback

$g(s)$  can be quantization

Capacity is



$$C = \sum_u p(u) \max_{p(x|u)} I(X; Y|S, U = u)$$

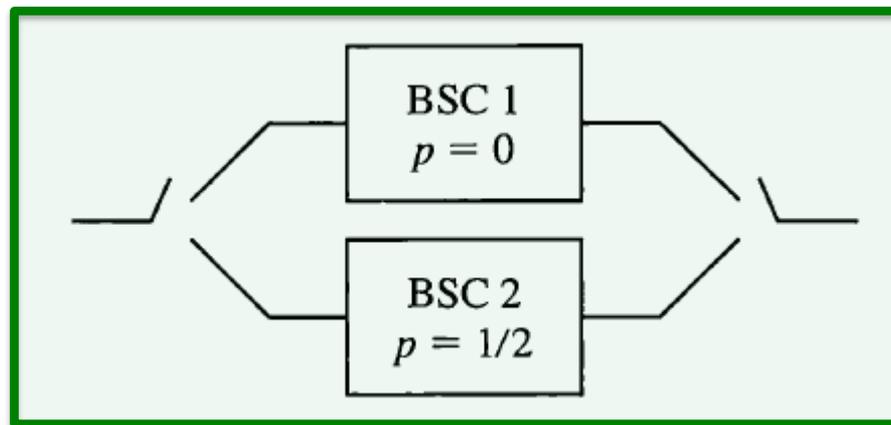
The task of the Tx is to choose the distribution on  $x$ , that maximizes the average of mutual informations over the channels that can be expected to occur around a certain  $u$

# 14.2 Ergodic and outage capacity

## System model

Capacity  $C_1 = 1$

$C_2 = 0$



Either a perfect channel is used (BSC 1), or a useless channel (BSC 2)

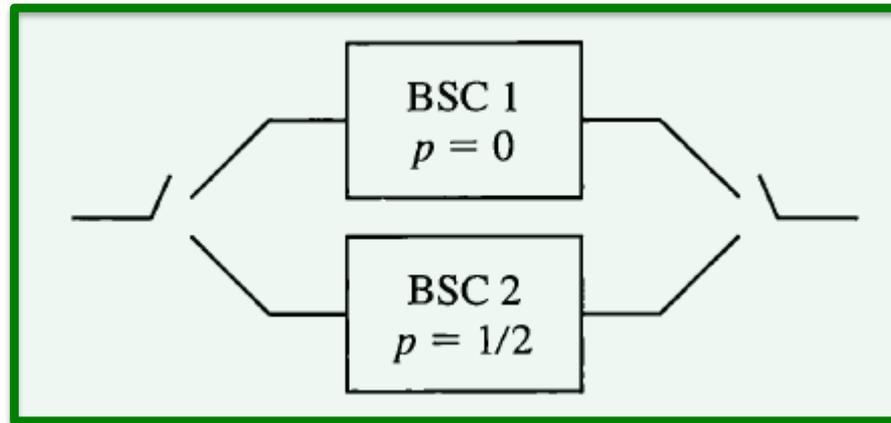
1. In channel model 1 the input and output switches choose the top channel (BSC 1) with probability  $\delta$  and the bottom channel (BSC 2) with probability  $1 - \delta$ , *independently for each transmission*. In this channel model each symbol is transmitted independently of the previous symbols, and the state of the channel is also selected independently for each symbol.
2. In channel model 2 the top and the bottom channels are selected at the beginning of the transmission with probabilities  $\delta$  and  $1 - \delta$ , respectively; but once a channel is selected, it will not change for the entire transmission period.

# 14.2 Ergodic and outage capacity

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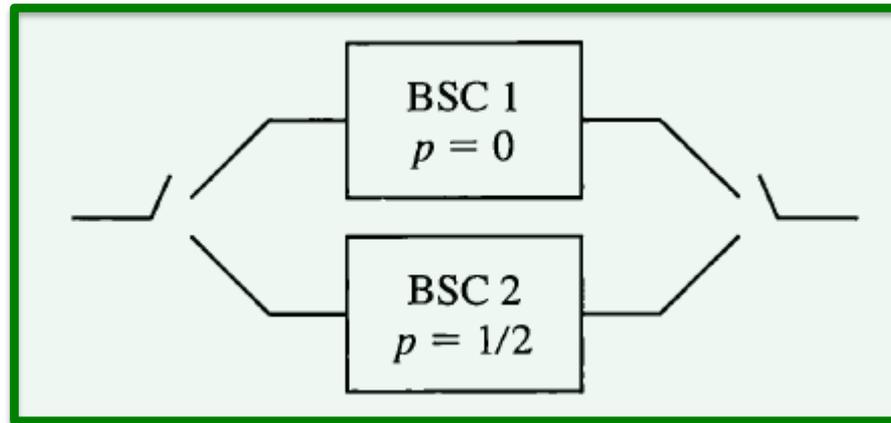
**Ergodic capacity.** In a fraction  $\delta$  of the time, the capacity is 1. In  $(1-\delta)$ , the capacity is 0. The ergodic capacity is the mean capacity that will be experienced over a very long period of time.

This capacity can be reached with a very long codeword spanning all states of the channel.

## 14.2 Ergodic and outage capacity

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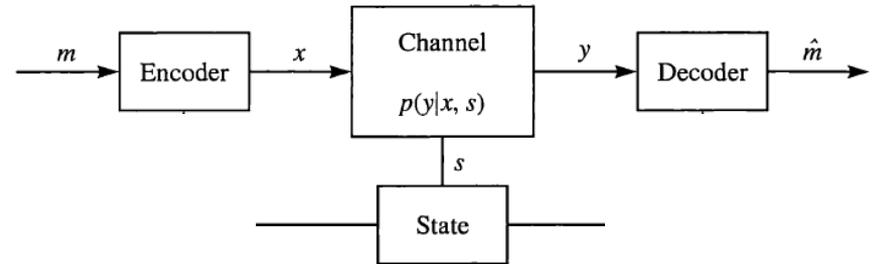


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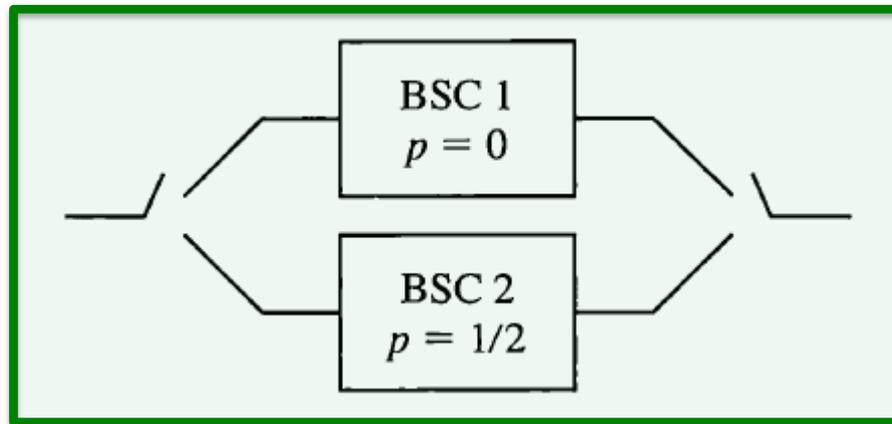
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**Now further break case 1 this into 3 sub-cases**

# 14.2 Ergodic and outage capacity

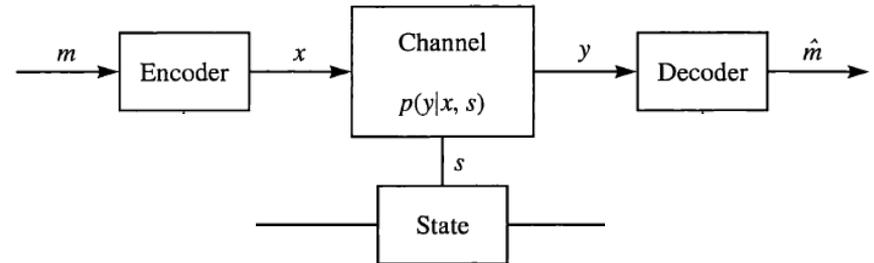


Sub case 1: No CSI at Rx or Tx

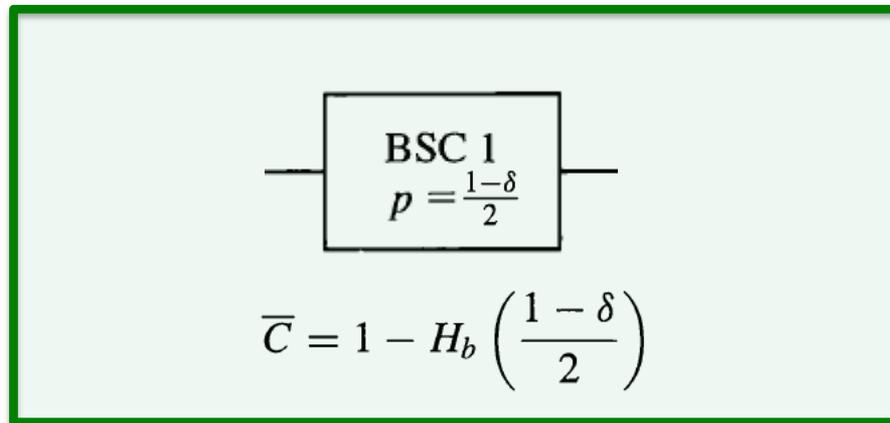


In this case an amount  $(1-\delta)/2$  of the bits are in error, the errors are randomly spread over the block, as the switching between BSC 1 and BSC 2 is random.

# 14.2 Ergodic and outage capacity



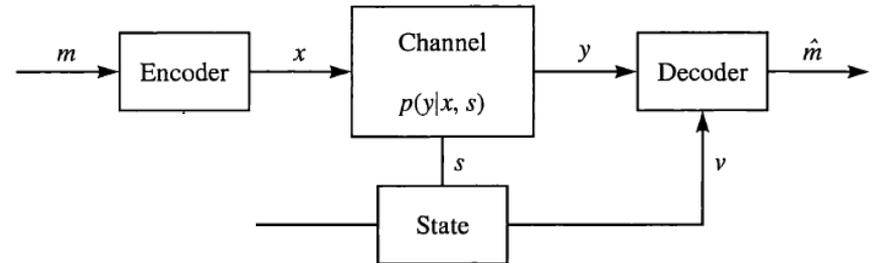
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In this case an amount  $(1-\delta)/2$  of the bits are in error, the errors are randomly spread over the block, as the switching between BSC 1 and BSC 2 is random.

Scenario is indistinguishable from a single BSC

# 14.2 Ergodic and outage capacity

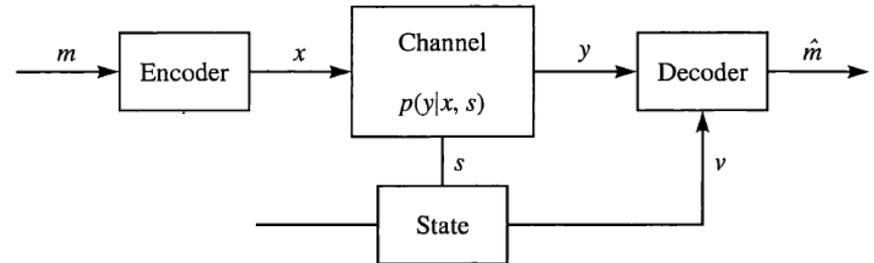


Sub case 2: CSI at Rx

$$C = \max_{p(x)} I(X; Y|S) = \max_{p(x)} \sum_s p(s) I(X; Y|S = s)$$

Find the input distribution that maximizes the average of the capacities.

# 14.2 Ergodic and outage capacity



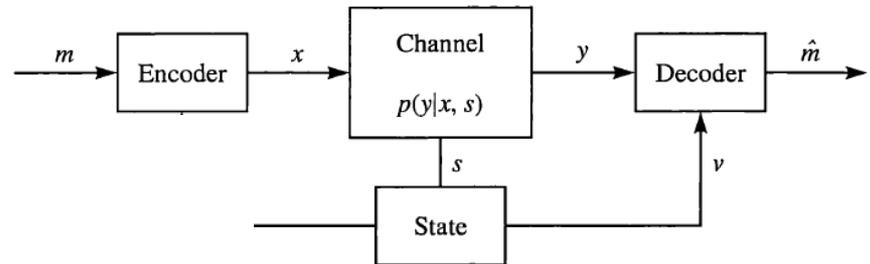
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Find the input distribution that maximizes the average of the capacities.

However, the capacity of a BSC channel is maximized by a uniform input distribution. That is,  $p(x=1)=p(x=0)=0.5$

## 14.2 Ergodic and outage capacity



Sub case 2: CSI at Rx

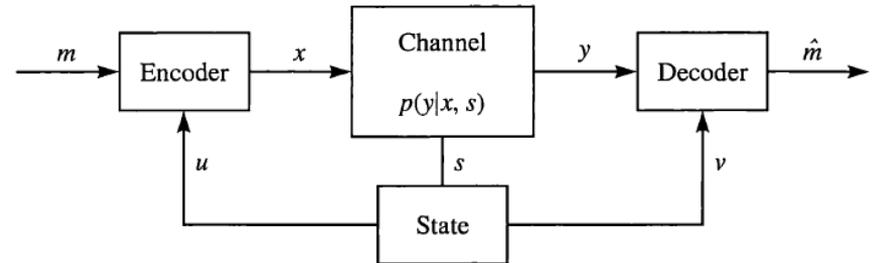
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However, the capacity of a BSC channel is maximized by a uniform input distribution. That is,  $p(x=1)=p(x=0)=0.5$

$$\bar{C} = \delta C_1 + (1 - \delta) C_2 = \delta$$

# 14.2 Ergodic and outage capacity

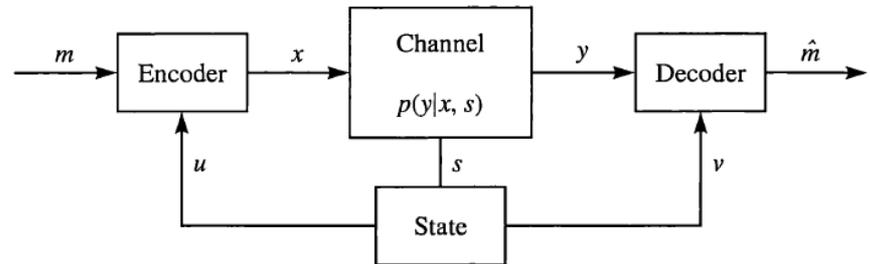


Sub case 3: CSI at Rx and Tx

$$C = \max_{p(x|s)} I(X; Y|S) = \sum_s p(s) \max_{p(x|s)} I(X; Y|S = s)$$

Find the input distributions that maximize the capacities of the two channels individually.

## 14.2 Ergodic and outage capacity



Sub case 3: CSI at Rx and Tx

$$C = \max_{p(x|s)} I(X; Y|S) = \sum_s p(s) \max_{p(x|s)} I(X; Y|S = s)$$

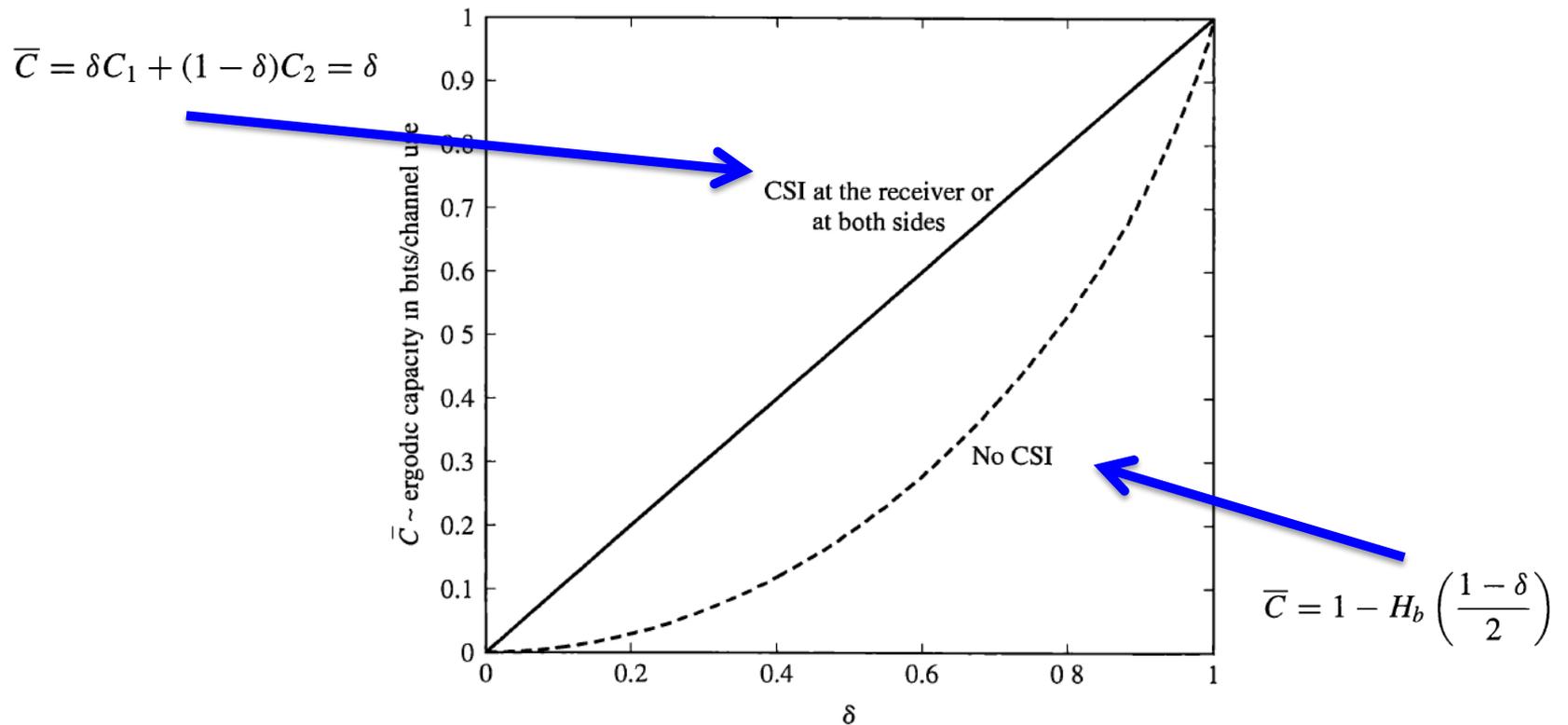
Find the input distributions that maximize the capacities of the two channels individually.

In both cases, this is the uniform distribution, so Tx feedback does not help in this case

$$\bar{C} = \delta C_1 + (1 - \delta) C_2 = \delta$$

# 14.2 Ergodic and outage capacity

## Comparison of sub case 1 and 2/3



# 14.2 Ergodic and outage capacity

## Case 2

2. In channel model 2 the top and the bottom channels are selected at the beginning of the transmission with probabilities  $\delta$  and  $1 - \delta$ , respectively; but once a channel is selected, it will not change for the entire transmission period.

Suppose that we select a transmission rate  $R > 0$

# 14.2 Ergodic and outage capacity

## Case 2

2. In channel model 2 the top and the bottom channels are selected at the beginning of the transmission with probabilities  $\delta$  and  $1 - \delta$ , respectively; but once a channel is selected, it will not change for the entire transmission period.

Suppose that we select a transmission rate  $R > 0$

Now suppose that BSC 2 is selected

Capacity  $C_2 = 0 < R$

## 14.2 Ergodic and outage capacity

### Case 2

2. In channel model 2 the top and the bottom channels are selected at the beginning of the transmission with probabilities  $\delta$  and  $1 - \delta$ , respectively; but once a channel is selected, it will not change for the entire transmission period.

Suppose that we select a transmission rate  $R > 0$

Now suppose that BSC 2 is selected (happens with non-zero probability)

Capacity  $C_2 = 0 < R$

Hence, reliable communication at any nonzero rate is not possible

*Shannon capacity of the channel is 0*

# 14.2 Ergodic and outage capacity

## Case 2

2. In channel model 2 the top and the bottom channels are selected at the beginning of the transmission with probabilities  $\delta$  and  $1 - \delta$ , respectively; but once a channel is selected, it will not change for the entire transmission period.

In case 2, the channel capacity is a random function (0 or 1).

*The notion of ergodic capacity is not applicable*

*This calls for the concept of **outage capacity***

# 14.2 Ergodic and outage capacity

## Case 2

If we transmit at a rate  $R > 0$ , there is a probability that the channel capacity  $C$  is less than  $R$ , and then the channel is in *outage*.

*Probability of this is called outage probability*

$$P_{\text{out}}(R) = P[C < R] = F_C(R^-)$$

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CDF of C

Limit of approaching  
R from the left

## 14.2 Ergodic and outage capacity

### Case 2

If we transmit at a rate  $R > 0$ , there is a probability that the channel capacity  $C$  is less than  $R$ , and then the channel is in *outage*.

*Probability of this is called outage probability*

$$P_{\text{out}}(R) = P[C < R] = F_C(R^-)$$

*$\epsilon$ -outage-capacity: Highest rate that keeps the outage probability below  $\epsilon$*

$$C_\epsilon = \max \{R : P_{\text{out}}(R) \leq \epsilon\}$$

## 14.2 Ergodic and outage capacity

In the previous 2-BSC example, we get the following outage capacity

$$C_\epsilon = \begin{cases} 0 & \text{for } 0 \leq \epsilon < 1 - \delta \\ 1 & \text{for } 1 - \delta \leq \epsilon < 1 \end{cases}$$

$$C_\epsilon = \max \{R : P_{\text{out}}(R) \leq \epsilon\}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

$$y_i = R_i x_i + n_i$$

$\mathcal{CN}(\bar{0}, N_0)$



All variables are complex.

$R_i$  has Rayleigh distributed amplitude, and uniform phase

$$p(r) = \begin{cases} \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} & r > 0 \\ 0 & r \leq 0 \end{cases}$$

$$E[R^2] = 2\sigma^2 \quad \rho = |R_i|^2$$

$$p(\rho) = \begin{cases} \frac{1}{2\sigma^2} e^{-\frac{\rho}{2\sigma^2}} & \rho > 0 \\ 0 & \rho \leq 0 \end{cases}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

$$y_i = R_i x_i + n_i$$

$$\mathcal{CN}(\bar{0}, N_0)$$


All variables are complex.

$R_i$  has Rayleigh distributed amplitude, and uniform phase

$$p(r) = \begin{cases} \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} & r > 0 \\ 0 & r \leq 0 \end{cases}$$

Means that  $R_i$  is  $A_i + iB_i$ , where  $A_i$  and  $B_i$  are independent normal variables with variance  $\sigma^2$



$$E[R^2] = 2\sigma^2$$

$$\rho = |R_i|^2$$


$$p(\rho) = \begin{cases} \frac{1}{2\sigma^2} e^{-\frac{\rho}{2\sigma^2}} & \rho > 0 \\ 0 & \rho \leq 0 \end{cases}$$

Means that  $\rho$  is chi-2 with 2 degrees of freedom

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$$y_i = R_i x_i + n_i$$

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$$p(r) = \begin{cases} \frac{r}{\sigma^2} e^{-\frac{r^2}{2\sigma^2}} & r > 0 \\ 0 & r \leq 0 \end{cases}$$

Received power

$$P_r = 2\sigma^2 P_t$$

$$E[R^2] = 2\sigma^2 \quad \rho = |R_i|^2$$

Assume

$$2\sigma^2 = 1$$

$$p(\rho) = \begin{cases} \frac{1}{2\sigma^2} e^{-\frac{\rho}{2\sigma^2}} & \rho > 0 \\ 0 & \rho \leq 0 \end{cases}$$

Thus

$$P_t = P_r = P$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

In this case, we can drop the sub-index "i" on the signals, as the channel is totally random identically distributed from one time instant to the other.

$$y = Rx + n$$

$\mathcal{CN}(0, 2\sigma^2)$        $\mathcal{CN}(0, N_0)$

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

In this case, we can drop the sub-index "i" on the signals, as the channel is totally random identically distributed from one time instant to the other.

$$y = Rx + n$$

Phase of R is unknown and uniform  $\rightarrow$  phase of x cannot carry information.

(Given the phase of x, the phase of y is still uniformly distributed over  $[0, 2\pi]$ )

To compute capacity, we need  $p(y|x)$

$$p(y|x) = \frac{1}{2\pi} \int_0^{2\pi} \int_0^{\infty} p(y|x, r, \theta) p(r) dr d\theta$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

In this case, we can drop the sub-index "i" on the signals, as the channel is totally random identically distributed from one time instant to the other.

$$y = Rx + n$$

Phase of R is unknown and uniform  $\rightarrow$  phase of x cannot carry information.

(Given the phase of x, the phase of y is still uniformly distributed over  $[0, 2\pi]$ )

To compute capacity, we need  $p(y|x)$

$$p(y|x) = \frac{1}{\pi (N_0 + |x|^2)} e^{-\frac{|y|^2}{N_0 + |x|^2}}$$

**Clearly seen that all phase information in x has been lost**

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

To find capacity entails the expectations

**Entropy of y:**  $H(y) = - E_y \log_2 [p(y)]$

**Entropy of y|x:**  $H(y|x) = - E_y \log_2 [p(y|x)]$

Then, one should optimize over the distribution of x

**This optimization does not allow for a closed-form solution**

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

To find capacity entails the expectations

**Entropy of y:**  $H(y) = - E_y \log_2 [p(y)]$

**Entropy of y|x:**  $H(y|x) = - E_y \log_2 [p(y|x)]$

Then, one should optimize over the distribution of x

**This optimization does not allow for a closed-form solution**

### Facts about it

- Gaussian inputs are not optimal (they are with Rx CSI)
- Optimal distribution is discrete
- At low SNR, on-off keying is optimal
- At low SNR, ergodic capacity is

$$\bar{C} = \frac{1}{\ln 2} \frac{P}{N_0} \approx 1.44 \frac{P}{N_0}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## No CSI at Rx or Tx

With full CSI at the Rx, we get

$$C = \log \left( 1 + \frac{P}{N_0} \right)$$

With small P, we get

$$C = \frac{1}{\ln 2} \frac{P}{N_0} \approx 1.44 \frac{P}{N_0}$$

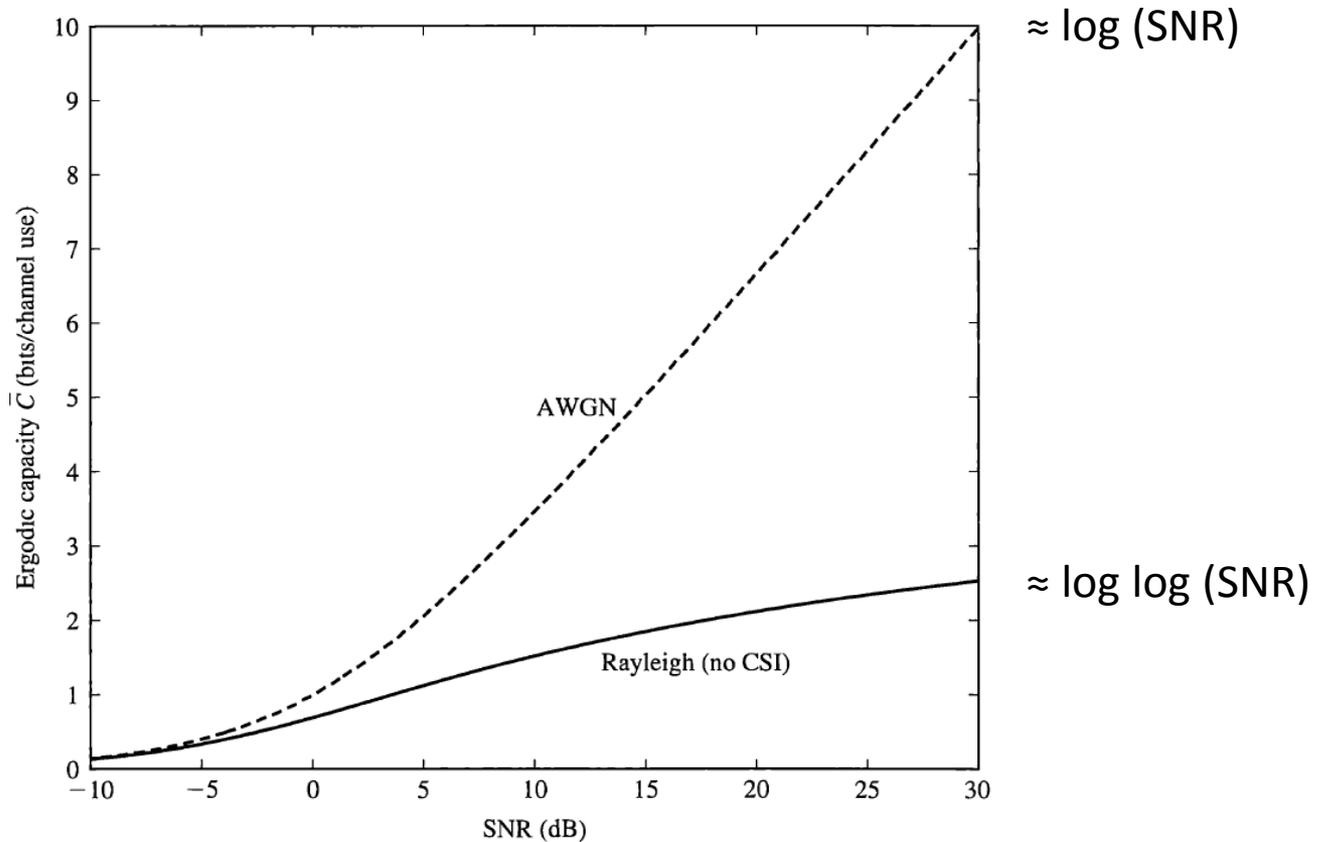
Hence, at low SNR, the loss of having no CSI at Rx vanishes

- At low SNR, ergodic capacity is

$$\bar{C} = \frac{1}{\ln 2} \frac{P}{N_0} \approx 1.44 \frac{P}{N_0}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

No CSI at Rx or Tx



# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

With Rx CSI, the receiver can compensate for the phase of the channel

We can wlog assume the channel  $R$  to be real

The effect is a scaling of the SNR by an amount  $\rho$

**Ergodic capacity is the expectation of**

$$C = \log \left( 1 + \rho \frac{P}{N_0} \right)$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

Log is a concave function -> Jensen's inequality applies:

$$\begin{aligned}\bar{C} &= \mathbb{E} \left[ \log \left( 1 + \rho \frac{P}{N_0} \right) \right] \\ &\leq \log \left( 1 + \mathbb{E}[\rho] \frac{P}{N_0} \right) \\ &= \log \left( 1 + \frac{P}{N_0} \right)\end{aligned}$$

**Ergodic capacity of time-varying channel is never better than the capacity of a static channel with the same SNR**

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

Exact computation of ergodic capacity

$$p(\rho) = \begin{cases} \frac{1}{2\sigma^2} e^{-\frac{\rho}{2\sigma^2}} & \rho > 0 \\ 0 & \rho \leq 0 \end{cases}$$

$$2\sigma^2 = 1$$

$$p(\rho) = \begin{cases} e^{-\rho} & \rho > 0 \\ 0 & \rho \leq 0 \end{cases}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

Exact computation of ergodic capacity

$$\begin{aligned}\bar{C} &= \int_0^{\infty} \log \left( 1 + \rho \frac{P}{N_0} \right) e^{-\rho} d\rho \\ &= \frac{1}{\ln 2} e^{\frac{N_0}{P}} \Gamma \left( 0, \frac{N_0}{P} \right) \\ &= \frac{1}{\ln 2} e^{\frac{1}{\text{SNR}}} \Gamma \left( 0, \frac{1}{\text{SNR}} \right)\end{aligned}$$

$$\Gamma(a, z) = \int_z^{\infty} t^{a-1} e^{-t} dt$$

*complementary gamma function*

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

Exact computation of ergodic capacity

$$\begin{aligned}\bar{C} &= \int_0^{\infty} \log \left( 1 + \rho \frac{P}{N_0} \right) e^{-\rho} d\rho \\ &= \frac{1}{\ln 2} e^{\frac{N_0}{P}} \Gamma \left( 0, \frac{N_0}{P} \right) \\ &= \frac{1}{\ln 2} e^{\frac{1}{\text{SNR}}} \Gamma \left( 0, \frac{1}{\text{SNR}} \right)\end{aligned}$$

$$\Gamma(a, z) = \int_z^{\infty} t^{a-1} e^{-t} dt$$

*complementary gamma function*

## Low SNR

Cannot be worse than no Rx CSI  
Cannot be better than AWGN  
due to Jensen's

$$\bar{C} = 1.44 \text{ SNR}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

Exact computation of ergodic capacity

$$\begin{aligned}\bar{C} &= \int_0^{\infty} \log \left( 1 + \rho \frac{P}{N_0} \right) e^{-\rho} d\rho \\ &= \frac{1}{\ln 2} e^{\frac{N_0}{P}} \Gamma \left( 0, \frac{N_0}{P} \right) \\ &= \frac{1}{\ln 2} e^{\frac{1}{\text{SNR}}} \Gamma \left( 0, \frac{1}{\text{SNR}} \right)\end{aligned}$$

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## Low SNR

Cannot be worse than no Rx CSI  
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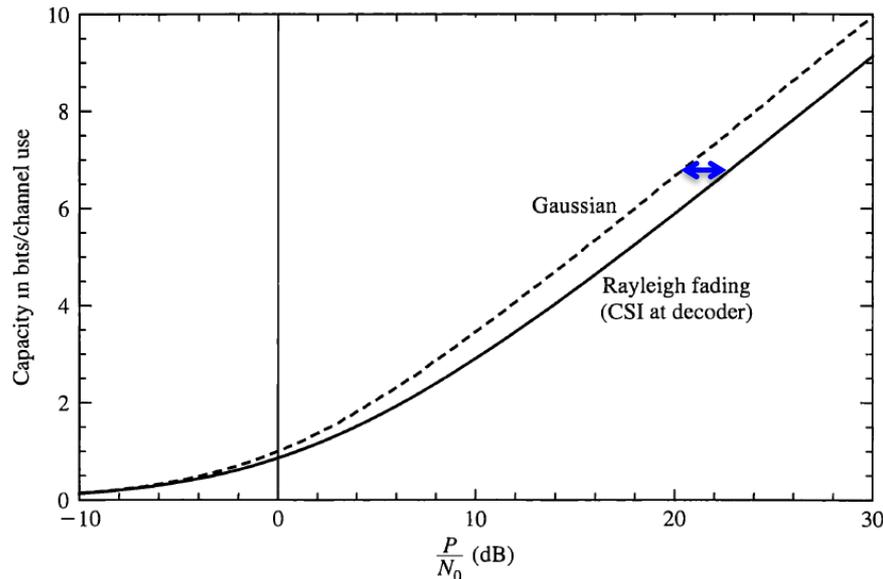
$$\bar{C} = 1.44 \text{ SNR}$$

## High SNR

$$\begin{aligned}\log \left( 1 + \rho \frac{P}{N_0} \right) &\approx \log \left( \rho \frac{P}{N_0} \right) \\ \bar{C} &\approx \frac{1}{\ln 2} \int_0^{\infty} \log \left( \rho \frac{P}{N_0} \right) e^{-\rho} d\rho \\ &= \log \text{SNR} + \frac{1}{\ln 2} \int_0^{\infty} (\ln \rho) e^{-\rho} d\rho \\ &= \log \text{SNR} - 0.8327\end{aligned}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx



At high SNR, there is about 2.5 dB SNR loss from having a Rayleigh fading channel compared with an AWGN channel

### Low SNR

Cannot be worse than no Rx CSI  
Cannot be better than AWGN  
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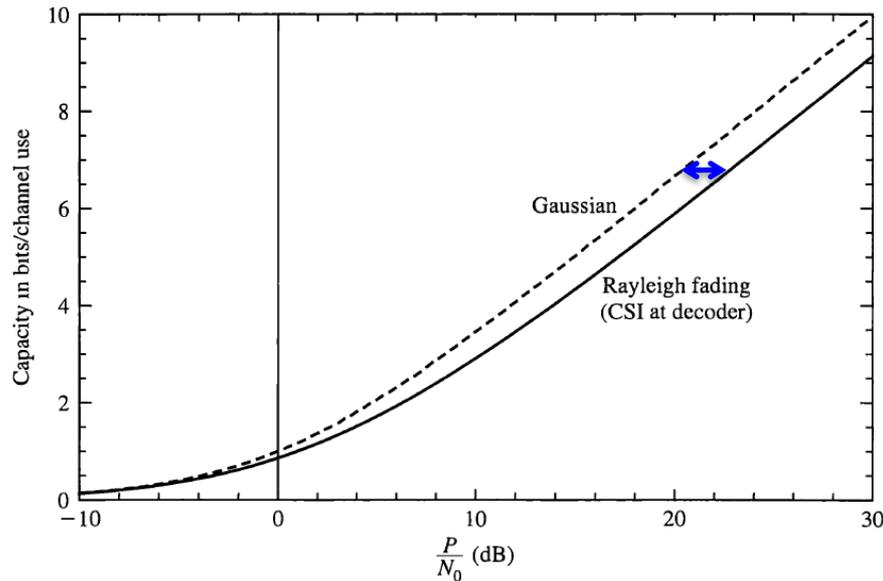
$$\bar{C} = 1.44 \text{ SNR}$$

### High SNR

$$\begin{aligned} \log \left( 1 + \rho \frac{P}{N_0} \right) &\approx \log \left( \rho \frac{P}{N_0} \right) \\ \bar{C} &\approx \frac{1}{\ln 2} \int_0^{\infty} \log \left( \rho \frac{P}{N_0} \right) e^{-\rho} d\rho \\ &= \log \text{SNR} + \frac{1}{\ln 2} \int_0^{\infty} (\ln \rho) e^{-\rho} d\rho \\ &= \log \text{SNR} - 0.8327 \end{aligned}$$

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx

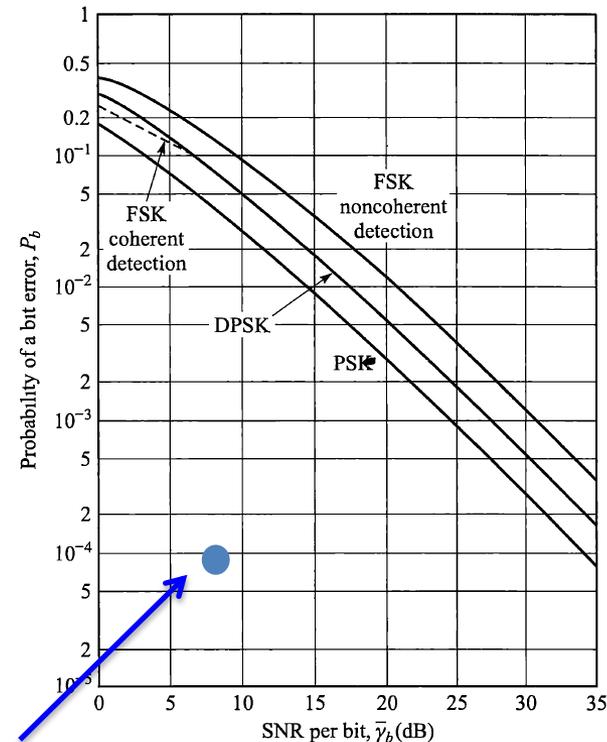


At high SNR, there is about 2.5 dB SNR loss from having a Rayleigh fading channel compared with an AWGN channel

## Comparison with BER

See 13.3-13 for eqs

$$P_b \approx 1/4\bar{\gamma}_b \quad \text{for coherent PSK}$$

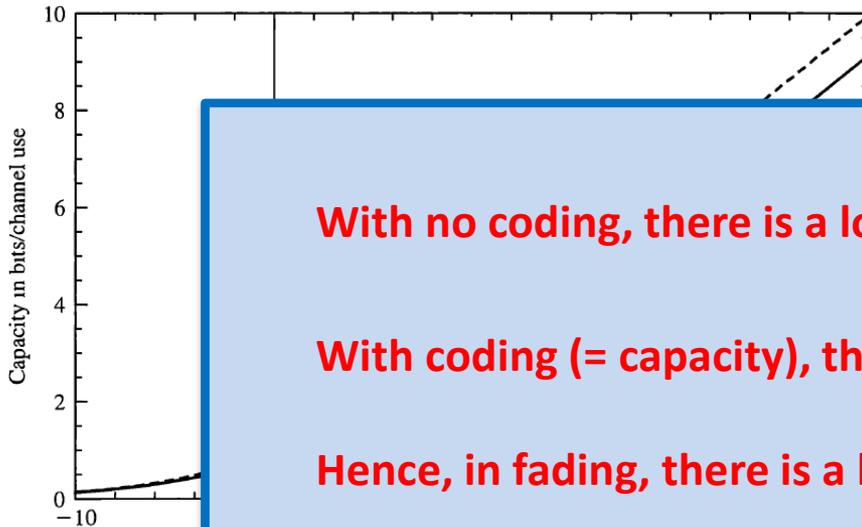


**AWGN is here**

30 dB  
difference in  
BER

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx



## Comparison with BER

See 13.3.13 for eqs

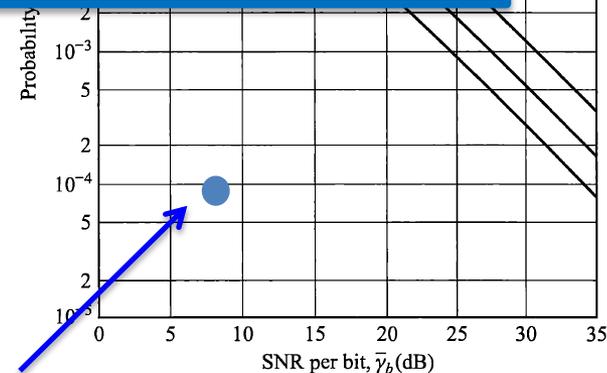
ent PSK

**With no coding, there is a loss of 30 dB in BER at  $10^{-4}$**

**With coding (= capacity), the loss is only 2.5 dB**

**Hence, in fading, there is a huge potential of coding**

At high SNR, there is about 2.5 dB SNR loss from having a Rayleigh fading channel compared with an AWGN channel



30 dB  
difference in  
BER

**AWGN is here**

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx and Tx

Transmit power is a function of the channel gain

$$\bar{C} = \int_0^{\infty} \log \left( 1 + \rho \frac{P(\rho)}{N_0} \right) e^{-\rho} d\rho$$


# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx and Tx

Transmit power is a function of the channel gain

$$\bar{C} = \int_0^{\infty} \log \left( 1 + \rho \frac{P(\rho)}{N_0} \right) e^{-\rho} d\rho$$


We can now apply the waterfilling principle in the time domain

$$\frac{P(\rho)}{N_0} = \left( \frac{1}{\rho_0} - \frac{1}{\rho} \right)^+$$

Waterfilling

$$\int_0^{\infty} \left( \frac{1}{\rho_0} - \frac{1}{\rho} \right)^+ e^{-\rho} d\rho = \frac{P}{N_0}$$

Satisfy average power constraint

# 14.2-1 Ergodic capacity of Rayleigh fading

## CSI at Rx and Tx

Transmit power is a function of the channel gain

$$\bar{C} = \int_0^{\infty} \log \left( 1 + \rho \frac{P(\rho)}{N_0} \right) e^{-\rho} d\rho$$


Parametric solution exists

$$\frac{P(\rho)}{N_0} = \left( \frac{1}{\rho_0} - \frac{1}{\rho} \right)^+$$

$$\int_0^{\infty} \left( \frac{1}{\rho_0} - \frac{1}{\rho} \right)^+ e^{-\rho} d\rho = \frac{P}{N_0}$$

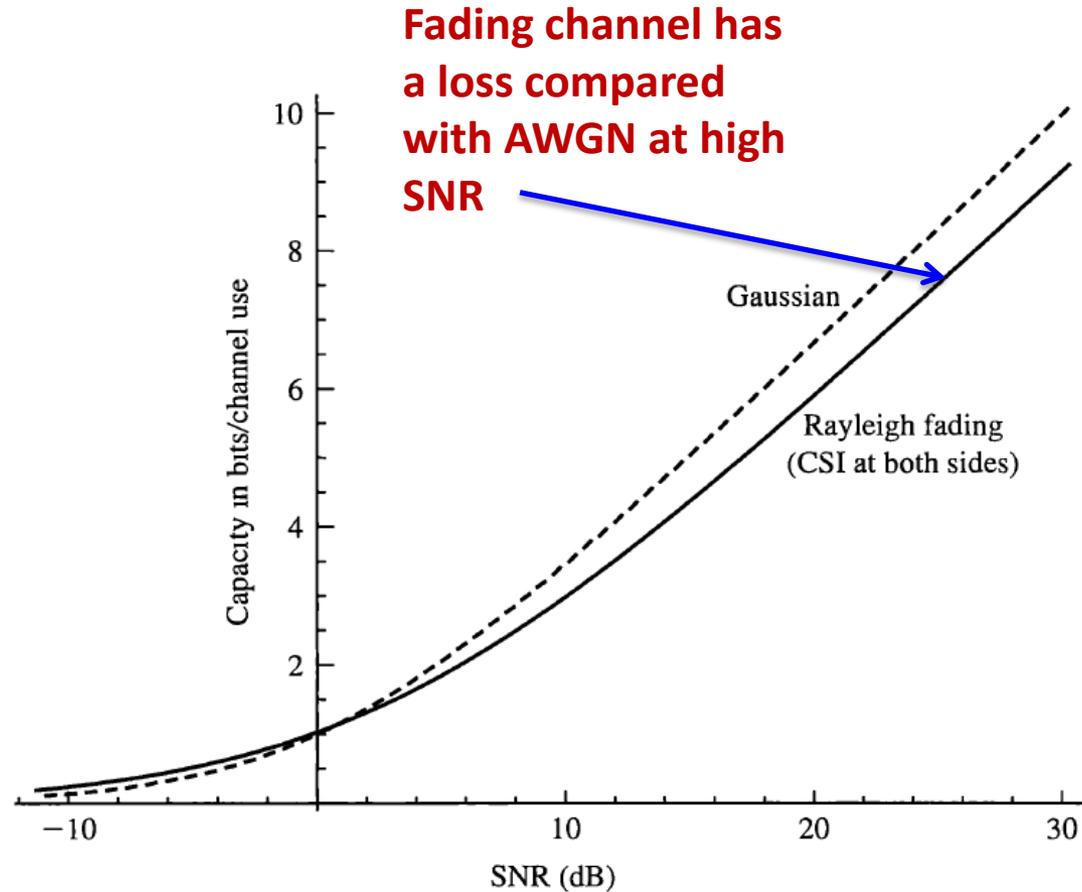
$$\frac{e^{-\rho_0}}{\rho_0} - \Gamma(0, \rho_0) = \frac{P}{N_0}$$

$$\bar{C} = \frac{1}{\ln 2} \Gamma(0, \rho_0)$$

# 14.2-1 Ergodic capacity of Rayleigh fading

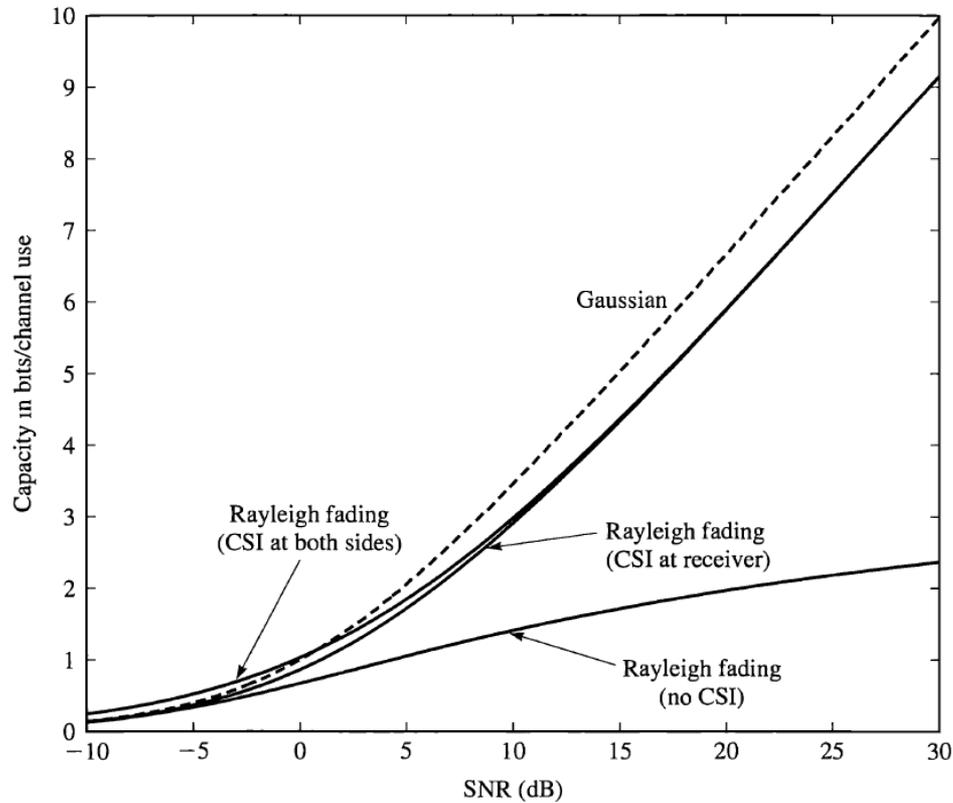
CSI at Rx and Tx

Fading channel can outperform AWGN at low SNR



# 14.2-1 Ergodic capacity of Rayleigh fading

## Comparisons



# Extension

*Consider a channel model*

$$Y_i = R_i X_i + N_i$$

Where neither the receiver or the transmitter has CSI.

Assume that  $R_i$  fades continuously according to a known channel transition law

$$\Pr(R_i | R_{i-1}, R_{i-2}, \dots, R_1)$$

The capacity of this is a wide open problem, and not much is known

**Excellent research topic**

## **14.2-2 Outage capacity of Rayleigh fading**

**Applies when, due to latency etc, one cannot afford to interleave the data across a long codeword, so that one can average over all channel realizations.**

## 14.2-2 Outage capacity of Rayleigh fading

$$\begin{aligned}C_\epsilon &= \max\{R : P_{\text{out}}(R) \leq \epsilon\} \\ &= \max\{R : F_C(R^-) = \epsilon\} \\ &= F_C^{-1}(\epsilon)\end{aligned}$$

$$C = \log(1 + \rho \text{ SNR})$$

**Perfect CSI at Rx assumed  
By definition, no CSI at Tx**

$$P_{\text{out}}(R) = P[C < R]$$

**Probability of outage event  
for a given rate R**

## 14.2-2 Outage capacity of Rayleigh fading

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$$P_{\text{out}}(R) = P[C < R]$$

Probability of outage event  
for a given rate R

$$P_{\text{out}}(R) = P\left[\rho < \frac{2^R - 1}{\text{SNR}}\right]$$

Can be expressed as

$$= 1 - e^{-\frac{2^R - 1}{\text{SNR}}}$$

Using the cdf of  $\rho$

## 14.2-2 Outage capacity of Rayleigh fading

Solving for R yields

$$R = \log [1 - \text{SNR} \ln(1 - P_{\text{out}})]$$

**Confusing typo in book:**  
Between eq (14.2-36) and  
(14.2-37), Proakis refers to  
eq (14.2-36), but this  
should be (14.2-35)

$$\begin{aligned} P_{\text{out}}(R) &= P \left[ \rho < \frac{2^R - 1}{\text{SNR}} \right] \\ &= 1 - e^{-\frac{2^R - 1}{\text{SNR}}} \end{aligned}$$

# 14.2-2 Outage capacity of Rayleigh fading

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Signaling at this rate gives  
an outage capacity of

$$C_{\epsilon} = \log [1 - \text{SNR} \ln(1 - \epsilon)]$$

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Low SNR

$$C_{\epsilon} \approx \frac{\text{SNR}}{\ln 2} \ln \frac{1}{1 - \epsilon}$$

$$\log(1+x) \approx x, \text{ for } x \approx 0$$

# 14.2-2 Outage capacity of Rayleigh fading

Solving for R yields

$$R = \log [1 - \text{SNR} \ln(1 - P_{\text{out}})]$$

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=  $C_{\text{AWGN}}$  at low SNR

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At very small  $\epsilon$

$$C_{\epsilon} \approx \epsilon C_{\text{AWGN}}$$

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Solving for R yields

$$R = \log [1 - \text{SNR} \ln(1 - P_{\text{out}})]$$

Signaling at this rate gives  
an outage capacity of

$$C_{\epsilon} = \log [1 - \text{SNR} \ln(1 - \epsilon)]$$

Bring "-" inside log,  
and ignore "1+"

Low SNR

$$C_{\epsilon} \approx \frac{\text{SNR}}{\ln 2} \ln \frac{1}{1 - \epsilon}$$

=  $C_{\text{AWGN}}$  at low SNR

High SNR

$$C_{\epsilon} \approx \log \left[ \text{SNR} \ln \frac{1}{1 - \epsilon} \right]$$
$$= \log \text{SNR} + \log \left( \ln \frac{1}{1 - \epsilon} \right)$$

At very small  $\epsilon$

$$C_{\epsilon} \approx \epsilon C_{\text{AWGN}}$$

# 14.2-2 Outage capacity of Rayleigh fading

Solving for R yields

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$$C_{\epsilon} \approx \epsilon C_{\text{AWGN}}$$

High SNR

$$C_{\epsilon} \approx \log \left[ \text{SNR} \ln \frac{1}{1 - \epsilon} \right]$$
$$= \log \text{SNR} + \log \left( \ln \frac{1}{1 - \epsilon} \right)$$

For  $\epsilon=0.1$ ,

$$\log \left( \ln \frac{1}{1 - \epsilon} \right) = -3.25$$

# 14.2-2 Outage capacity of Rayleigh fading

Solving for R yields

$$R = \log [1 - \text{SNR} \ln(1 - P_{\text{out}})]$$

Signaling at this rate gives  
an outage capacity of

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Low SNR

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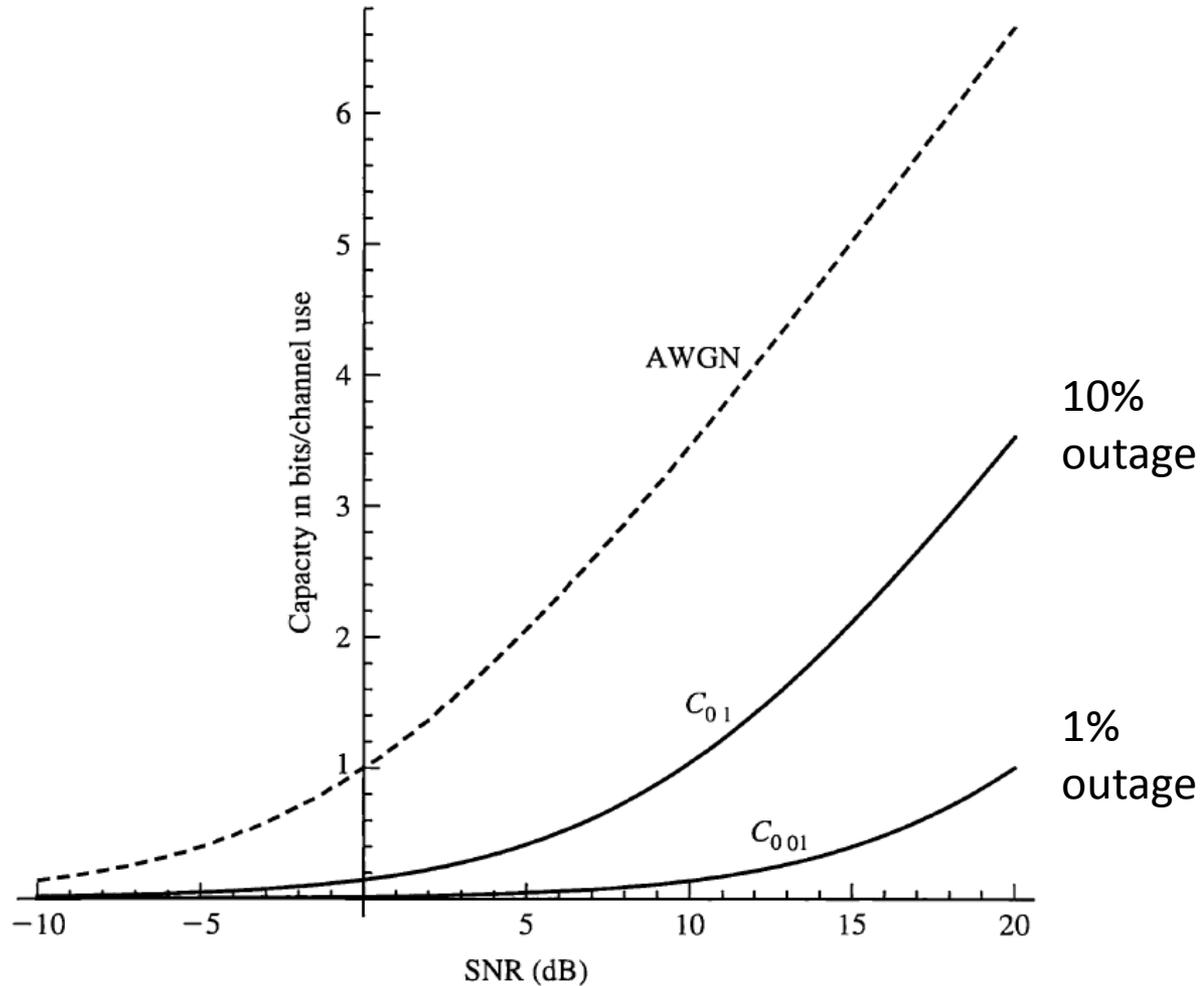
High SNR

$$C_{\epsilon} \approx \log \left[ \text{SNR} \ln \frac{1}{1 - \epsilon} \right]$$
$$= \log \text{SNR} + \log \left( \ln \frac{1}{1 - \epsilon} \right)$$

For  $\epsilon \approx 0$

$$\ln \frac{1}{1 - \epsilon} \approx \epsilon \quad \text{Loss is } \log_2 \epsilon$$

# 14.2-2 Outage capacity of Rayleigh fading



# 14.2-2 Outage capacity of Rayleigh fading

What we did so far was for Rayleigh fading

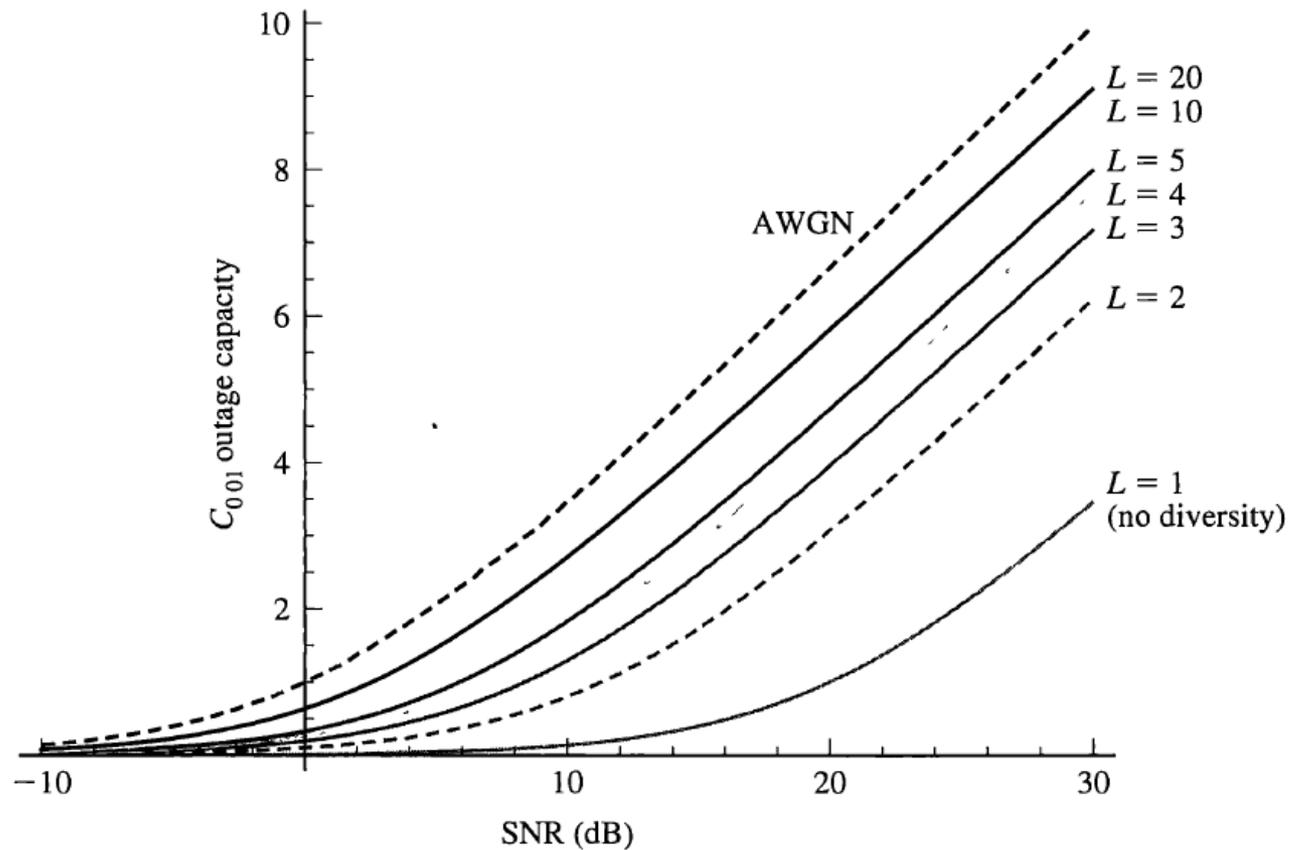
Rayleigh fading is a diversity  $L = 1$  scheme

The variable  $\rho$  has a chi-2 distribution with 2 degrees of freedom

Now assume an order  $L$  diversity scheme, so that  $\rho$  is a chi-2 with  $2L$  DoF

Repeat outage computations!

# 14.2-2 Outage capacity of Rayleigh fading



**Diversity has huge impact on outage capacity!**

# 14.3 – 14.7 Coding

**Too many details...Read if you are interested**  
**Much more time would be needed to cover this in lectures**

**One thing is very important**

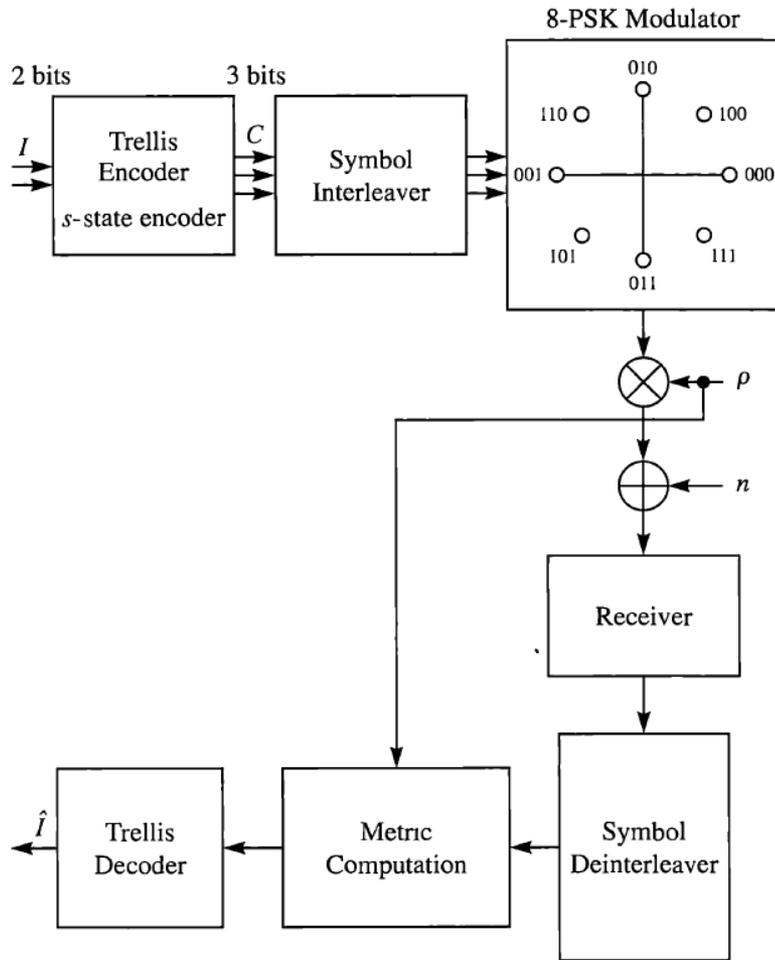
**In AWGN, a good code is designed by maximizing the Euclidean distance between pairs of transmitted signals**

**In fading, it is the Hamming distance of the code itself that should be optimized (loosely speaking)**

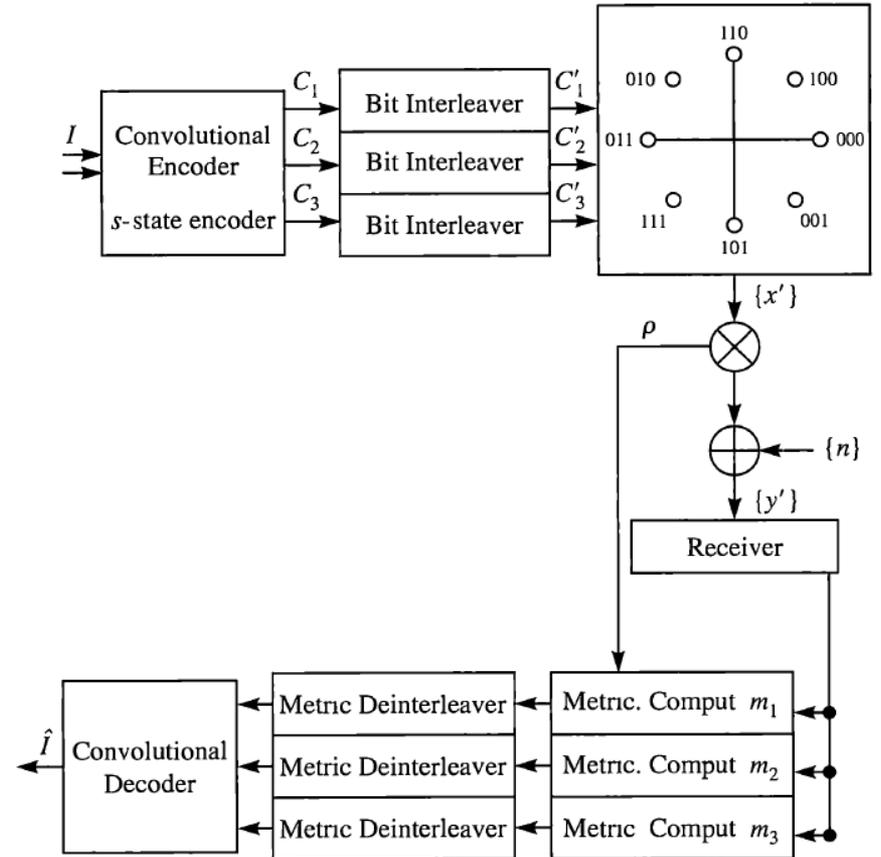
**For BPSK, these Euclidean distance and Hamming distance is the same (except for scaling), but not for higher order constellations.**

**One way to do this is via BICM**

# BICM



**Trellis coded modulation (TCM)**



**Bit-iterleaved coded modulation (BICM)**

# BICM

**TABLE 14.6–1**  
**Upper Bounds to Minimum Euclidean Distance**  
**and Diversity Order for TCM and BICM for**  
**16-QAM Signaling. Average Energy is**  
**Normalized to 1 and Transmission Rate is 3 Bits**  
**per Complex Dimension.**

Encoder memory	BICM		TCM	
	$d_E^2$	$d_{2(C)}$	$d_E^2$	$d_{M(C)}$
2	1.2	3	2	1
3	1.6	4	2.4	2
4	1.6	4	2.8	2
5	2.4	6	3.2	2
6	2.4	6	3.6	3
7	3.2	8	3.6	3
8	3.2	8	4	3

*Source: From Caire et al. (1998), copyright IEEE*

**BICM has worse Euclidean distance, but superior Hamming distance. This is more important in fading channels**

**BICM is worse on AWGN channels due to reduced Euclidean distance**