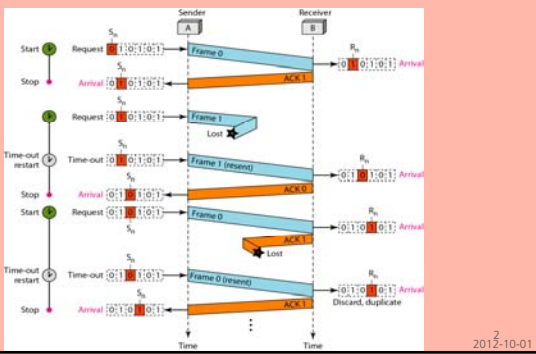


ETSF05:
Network models
Paradigmer
Länkprotokoll: Flödeskontroll vs felhantering
Routingalgoritmer

Jens A Andersson

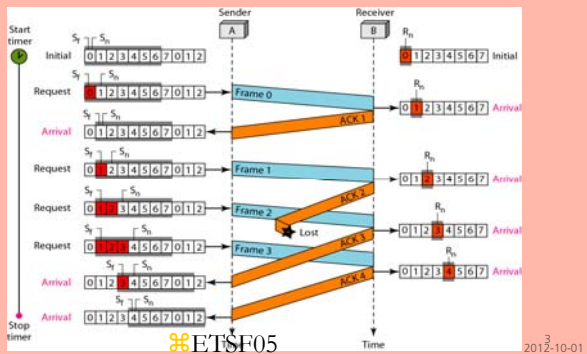


Stop-and-wait ARQ flow diagram



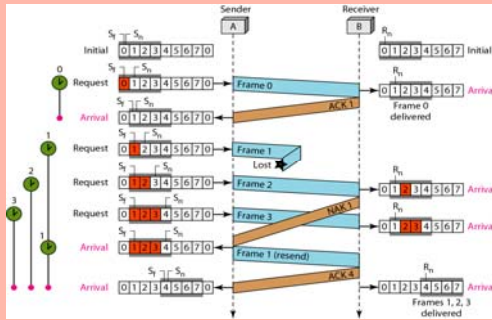
2
2012-10-01

Go-back-N ARQ flow diagram



ETSF05
3
2012-10-01

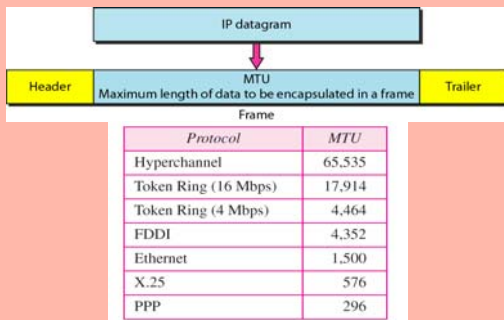
Selective repeat ARQ flow diagram



2012-10-01

BONUS

Maximum datagram size



2012-10-01

Fragmentation

Needed when IP datagram size > MTU

IPv4

- ◆ Performed by the router meeting the problem

IPv6

- ◆ Performed by the source router only

Defragmentation by destination host

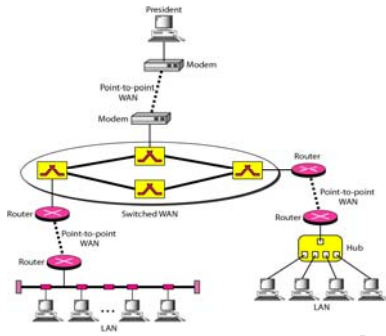


2012-10-01

Network engineering

High performance

- ◆ Reliability
- ◆ Throughput
- ◆ Speed
- ◆ Security



7
2011-09-26

Network models

Too complicated

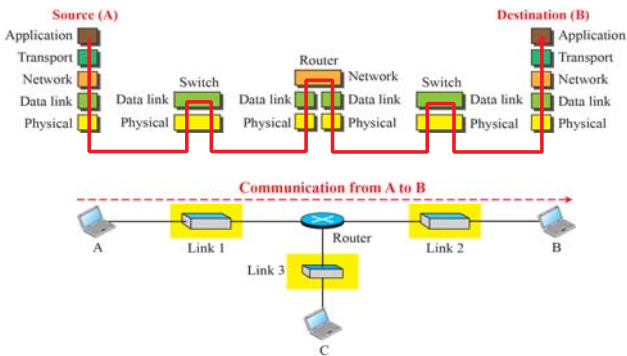
- ◆ Divide and conquer

Layered architecture

- ◆ Hierarchy
- ◆ Specialisation
- ◆ Simplification

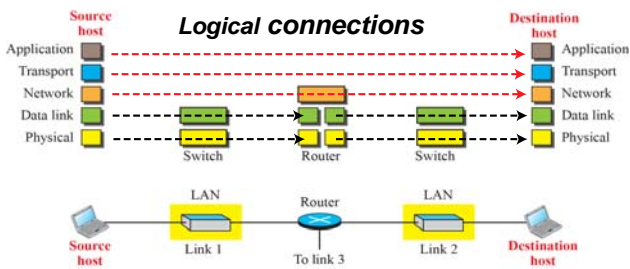
8
2011-09-26

Figure 2.5: Communication through an internet



2.9

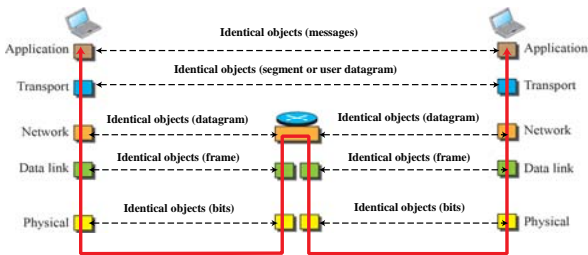
Figure 2.6: Logical connections between layers in TCP/IP



2.10

Figure 2.7: Identical objects in the TCP/IP protocol suite

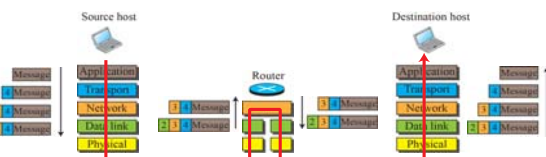
Notes: We have not shown switches because they don't change objects.



2.11

Figure 2.8: Encapsulation / Decapsulation

Legend
 [Blue box] Header at transport layer ↓ Encapsulate
 [Orange box] Header at network layer ↓ Encapsulate
 [Green box] Header at data-link layer ↓ Encapsulate
 ↑ Decapsulate



2.12

Figure 25.2: Example of a client-server paradigm

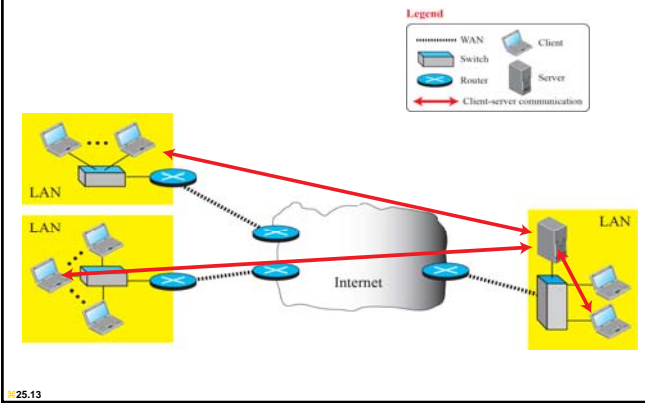
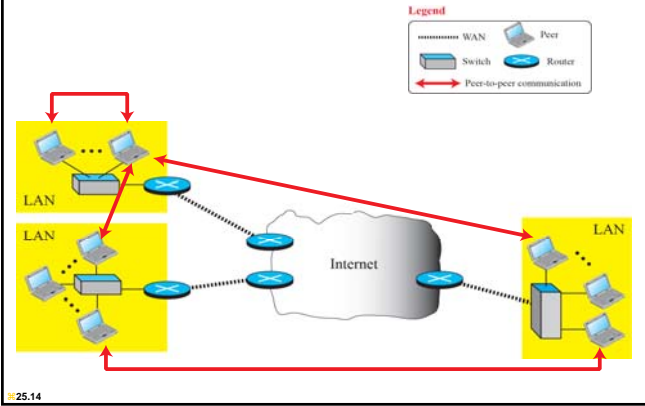


Figure 25.3: Example of a peer-to-peer paradigm



Data link control protocols

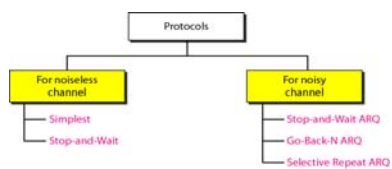
Framing

Flow control

- ◆ Send data
- ◆ Wait for ACK

Error control

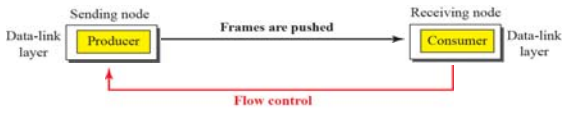
- ◆ Detect error
- ◆ Retransmit



Inte alltid att båda
(flödeskontroll, felhantering)
finns i länklagret!

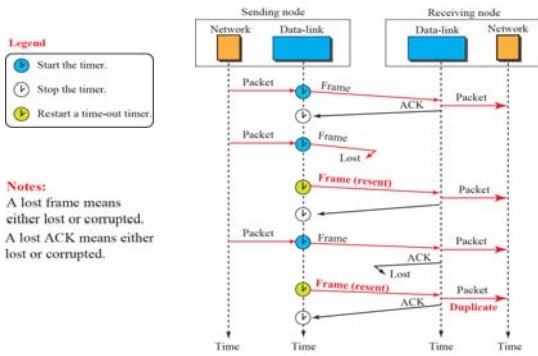
2011-09-26

Figure 111.5: Flow control at the data link layer



11.16

Figure 111.12: Flow diagram for Example 111.3



11.17

Go-Back-N?

- Viktigt inför nästa del och TCP (ETSF10)
- Föreläst i repetitionsföreläsningen
- Kommer på övningen

18

Routing

- Konsten att bygga least-cost trees
 - Från sändare till mottagare
 - Från varje nod till varje annan nod
- Tre principer
 - Distance Vector
 - Link State
 - Path Vector
 - Policy-based routing

19

Distance vector routing

All best known paths **shared to neighbours**

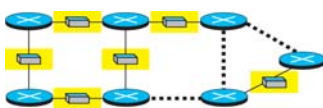
- ◆ Periodically
- ◆ Upon any change

Routing tables **updated** for

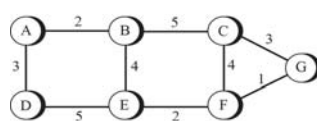
- ◆ New entries
- ◆ Cost changes

”Global knowledge shared locally”

Figure 20.1: An internet and its graphical representation



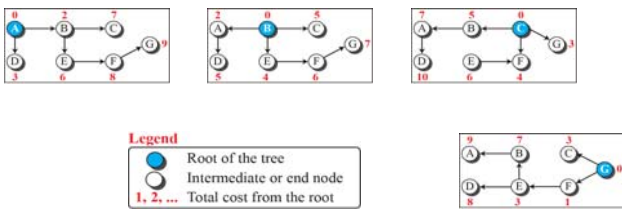
a. An internet



b. The weighted graph

20.21

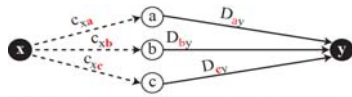
Figure 20.2: Least-cost trees for nodes in the internet of Figure 4.56



Note! This is the final result when the network has converged

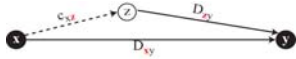
20.22

Figure 20.3: Graphical idea behind Bellman-Ford equation



a. General case with three intermediate nodes

$$D_{xy} = \min\{(c_{xa} + D_{ay}), (c_{xb} + D_{by}), (c_{xc} + D_{cy}) \dots\}$$



b. Updating a path with a new route

$$D_{xy} = \min\{D_{xy}, (c_{xz} + D_{zy})\}$$

20.23

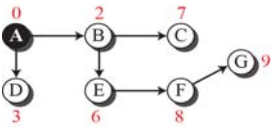
Updating algorithm (Bellman-Ford)

```

if (advertised destination not in table)
{
    add new entry // rule #1
}
else if (adv. next hop = next hop in table)
{
    update cost // rule #2
}
else if (adv. cost < cost in table)
{
    replace old entry // rule #3
}
    
```

2012-10-01

Figure 20.4: The distance vector corresponding to a tree



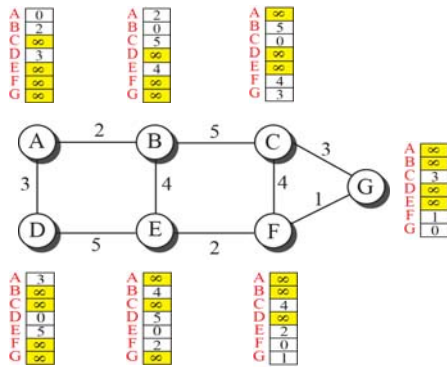
a. Tree for node A

A	
A	0
B	2
C	7
D	3
E	6
F	8
G	9

b. Distance vector for node A

20.25

Figure 20.5: The first distance vector for an internet



20.26

Figure 20.6: Updating distance vectors

New B		Old B		A	
A	2	A	2	A	0
B	0	B	0	B	2
C	5	C	5	C	∞
D	5	D	∞	D	3
E	4	E	4	E	∞
F	∞	F	∞	F	∞
G	∞	G	∞	G	∞

$B[x] = \min(B[x], 2 + A[x])$

a. First event: B receives a copy of A's vector.

Note:
X[]: the whole vector

New B		Old B		E	
A	2	A	2	A	∞
B	0	B	0	B	4
C	5	C	5	C	∞
D	5	D	5	D	5
E	4	E	4	E	0
F	6	F	∞	F	2
G	∞	G	∞	G	∞

$B[x] = \min(B[x], 4 + E[x])$

b. Second event: B receives a copy of E's vector.

20.27

- Periodiska uppdateringar!?
- Problem med länkar och noder som försvinner.

Mer om distance vector

I ETSF10:

- Count to infinity
- Two, three node instability
- Split Horizon
- Poison Reverse
- Routingprotokoll RIP

28

Link state routing

Local topology info **flooded** globally

- ◆ Periodically (very seldom in practise)
- ◆ Upon any change

Create database with link states in each node

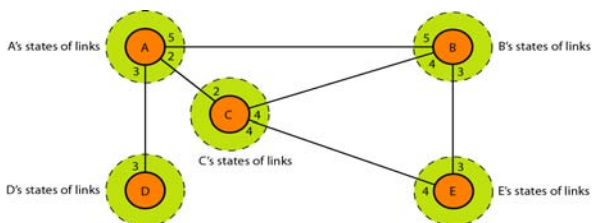
Routing tables updated for

- ◆ New entries
- ◆ Cost changes

”Local knowledge shared globally”

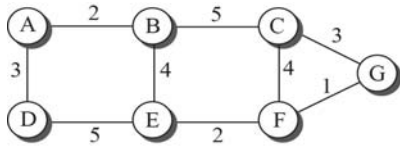
29
2011-10-03

Initial link state knowledge



30
2011-10-03

Figure 20.8: Example of a link-state database



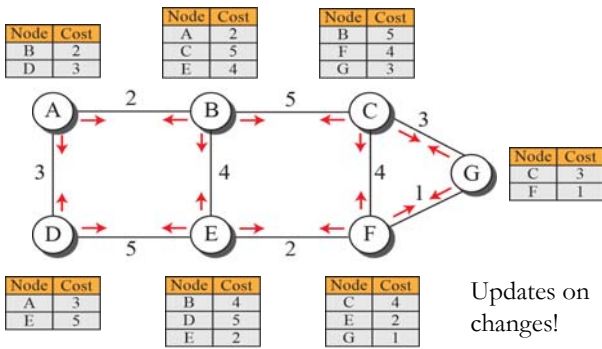
a. The weighted graph

	A	B	C	D	E	F	G
A	0	2	∞	3	∞	∞	∞
B	2	0	5	∞	4	∞	∞
C	∞	5	0	∞	∞	4	3
D	3	∞	∞	0	5	∞	∞
E	∞	4	∞	5	0	2	∞
F	∞	∞	4	∞	2	0	1
G	∞	∞	3	∞	∞	1	0

b. Link state database

20.31

Figure 20.9: LSPs created and sent out by each node to build LSDB



Updates on changes!

20.32

Tree generation algorithm (Dijkstra)

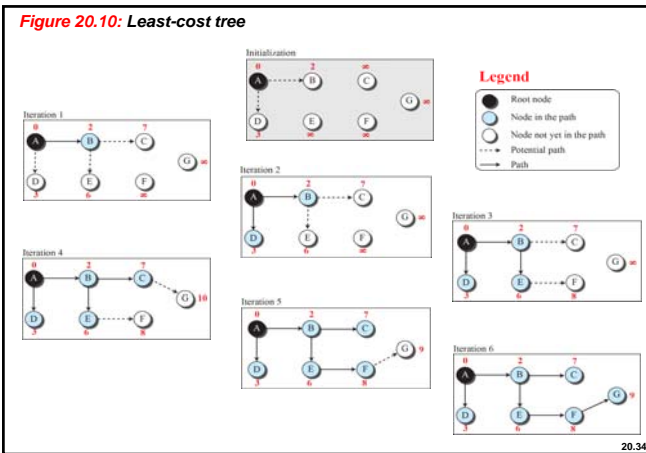
```

put yourself to tentative list
while tentative list not empty
{
    pick node which can be reached
        with least cumulative cost
    add it to your tree*
    put its neighbours to tentative list**
        with cumulative costs to reach them
}
    
```

* (a. k. a. permanent list)
 ** (if not already there with lower cost)

33

Figure 20.10: Least-cost tree



Mer om link state

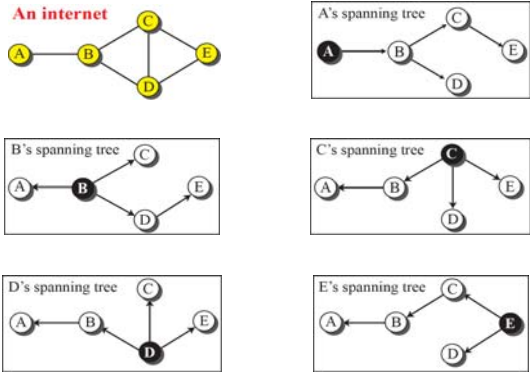
I ETSF10:

- Routingprotokoll OSPF
- Konceptet Areor eller hur man minskar flooding

Path Vector Routing

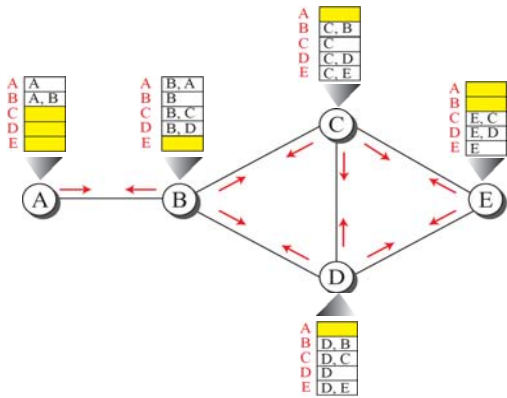
- Policy Based Routing
- Select *best path* of multiple paths
- Similar to Distance Vector
- Add path vector for each destination
- Add only paths that passes through accepted nodes
- Do not add paths where own node is element
- Path Vector length is only/major discriminator

Figure 20.11: Spanning trees in path-vector routing



20.37

Figure 20.12: Path vectors made at booting time



20.38

Figure 20.13: Updating path vectors

	New C	Old C	B
A	C, B, A	A	B, A
B	C, B	B	B
C	C	C	B, C
D	C, D	D	B, D
E	C, E	E	

Note:
X []: vector X
Y: node Y

$$C[] = \text{best}(C[], C + B[])$$

Event 1: C receives a copy of B's vector

”best” är implementerinen g av policyn

	New C	Old C	D
A	C, B, A	A	D, B
B	C, B	B	D, C
C	C	C	D
D	C, D	D	D, E
E	C, E	E	

$$C[] = \text{best}(C[], C + D[])$$

Event 2: C receives a copy of D's vector

20.39

Mer om path vector

I ETSF10:

- Autonoma system, AS
- Routing mellan domäner
- Policy routing
- Routingprotokoll BGP

40
