

ETIN80 — Algorithms in Signal Processors Projects

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Projects

- ▶ Speech recognition.
- ▶ Speech synthesis.
- ▶ Speech separation.
- ▶ Adaptive line enhancer.
- ▶ Echo cancellation.
- ▶ Beat detection.
- ▶ Beamforming.
- ▶ Or your own project...

Linear Prediction

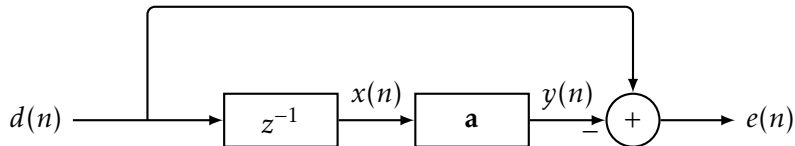
- ▶ Given a finite sequence of samples, can we predict the values of future samples?

$$\hat{x}(n+1) = \sum_{k=0}^{K-1} x(n-k)h(k)$$

- ▶ Correlated components can be predicted.
 - ▶ generally: periodic components
 - ▶ fundamentally: tonal components
- ▶ Stochastic components cannot be predicted.

Linear Prediction

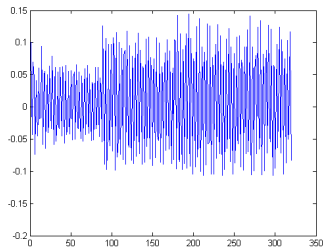
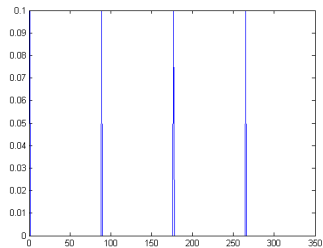
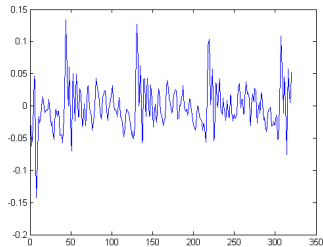
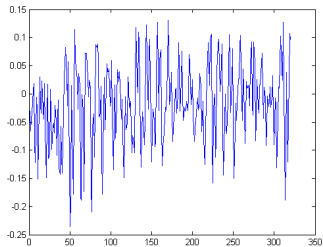
- ▶ The 1-step forward linear prediction filter.
- ▶ Standard Wiener problem:
 - ▶ adaptive solution
 - ▶ analytical solution
- ▶ The filter describes deterministic properties of the signal.



Linear Prediction

- ▶ A linear prediction filter describes formants.
- ▶ A formant is an *acoustic resonance*.
- ▶ The human vocal tract resonates and generates formants.
 - ▶ The vocal cords vibrate at a pitch frequency.
 - ▶ Formants generates overtones at different shapes.
 - ▶ Fricatives generates shaped noise sounds.
 - ▶ A sequence of formants over time describes a “word”.
- ▶ The linear prediction error filter cancels the formants.
- ▶ The inverse filter oscillates at the formants.

Speech

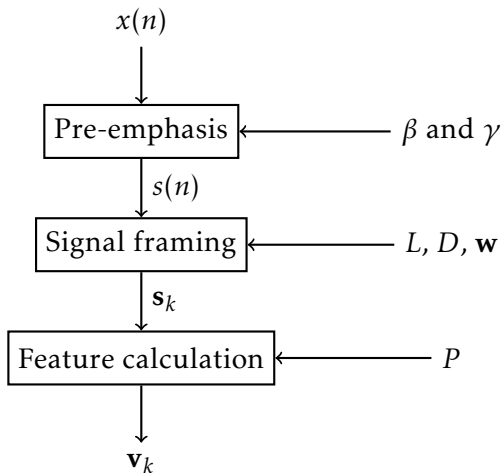


Speech

- ▶ Speech is stationary for roughly 20 ms.
- ▶ Process a speech signal in blocks of 20 ms.
- ▶ The filter **a** is normalized and pitch-independent.
 - ▶ Not dependent on voice amplitude.
 - ▶ Not dependent on voice pitch.
 - ▶ Different voices have similar filter.

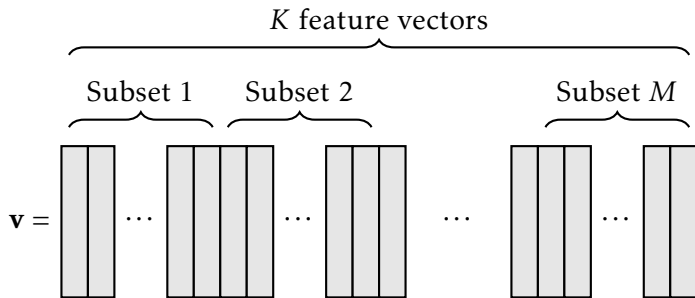
Speech Recognition: Feature Extraction

- ▶ Gather a sequence of feature vectors from the speech.



Speech Recognition: Feature Database

- ▶ Create an entry from the sequence for future matching.



- ▶ The database \mathbf{d} is the set of averages of the M subsets.

Speech Recognition: Matching

$$s_0 = 0$$

$$e_0 = 0$$

for each feature vector \mathbf{v}_k in the recorded signal

$$d_{\text{curr}} = |\mathbf{v}_k - \mathbf{d}_s|$$

$$d_{\text{next}} = |\mathbf{v}_k - \mathbf{d}_{s+1}|$$

if $d_{\text{curr}} < d_{\text{next}}$

$$s_k = s_{k-1}$$

else

$$s_k = s_{k-1} + 1$$

end

$$e_k = e_{k-1} + \min(d_{\text{curr}}, d_{\text{next}})$$

end

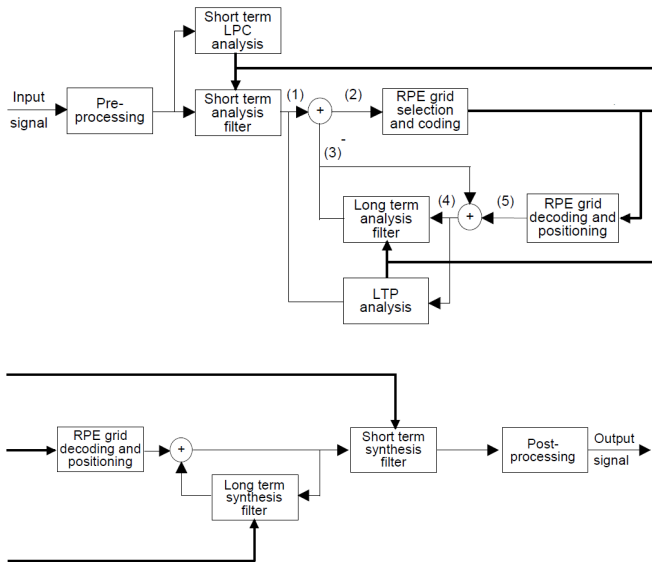
Speech Recognition

- ▶ For single-word verification, detect a match if the error e_k is below a threshold.
- ▶ For multi-word lookup, one state machine for every database entry and choose the one with lowest error.

Speech Synthesis

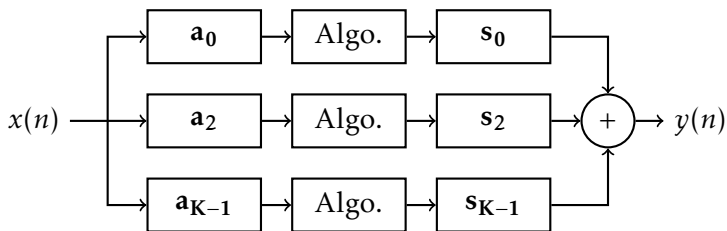
- ▶ For every block of a speech signal:
 - ▶ Calculate the prediction filter.
 - ▶ Calculate the pitch from the error signal.
 - ▶ Alter the pitch for funny effects.
 - ▶ Construct an excitation signal with the pitch frequency.
 - ▶ Filter the excitation signal with the inverse prediction filter.
- ▶ A primitive “Vocoder”.

GSM Full-rate Speech Transcoding



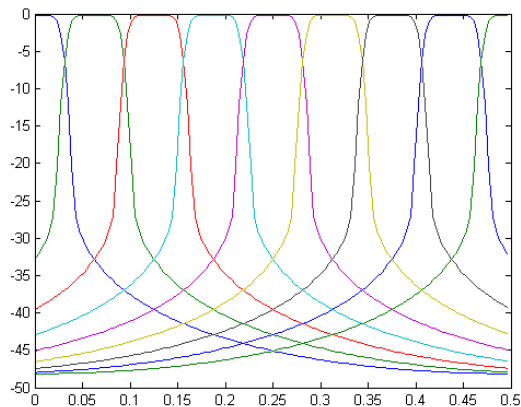
Subband Filtering

- ▶ Not all algorithms are suitable for full-band processing.
 - ▶ narrow-band algorithm
 - ▶ sparse sources and activity detection
- ▶ A filterbank is a set of parallel band-pass filters.
 - ▶ analysis filter to bandwidth limit the signal
 - ▶ subband processing at lower bandwidth
 - ▶ synthesis filter for full-band reconstruction



Subband Filtering

- ▶ Passbands of 16 subband filters.



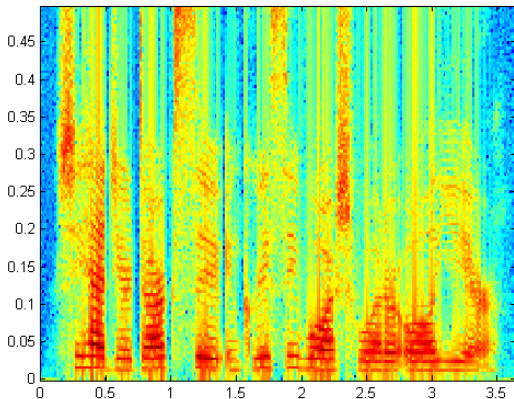
Speech Separation

- ▶ Speech excite narrow frequency bands at short times.
- ▶ Different speech sources rarely overlap.
- ▶ Separate different sources with selective masking.

$$Y_n(\omega, \tau) = \begin{cases} X(\omega, \tau) & \text{If source } n \text{ in } (\omega, \tau). \\ 0 & \text{Otherwise.} \end{cases}$$

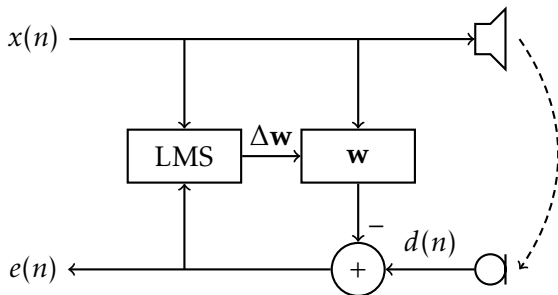
Speech Separation

- ▶ Time and frequency sparsity of speech.



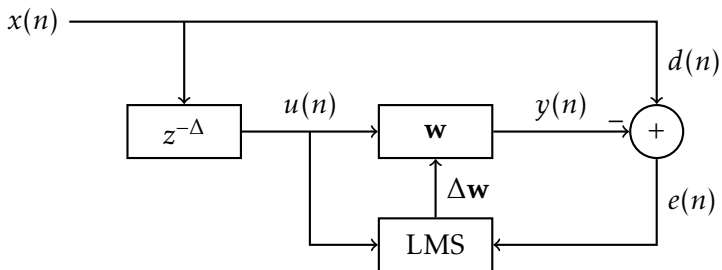
Echo Cancellation

- ▶ Cancel the feedback from a speaker into a microphone.
- ▶ Adaptive filter for continuous tracking.
- ▶ Subband filtering.



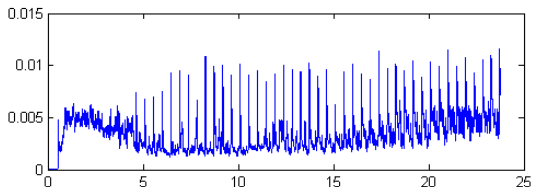
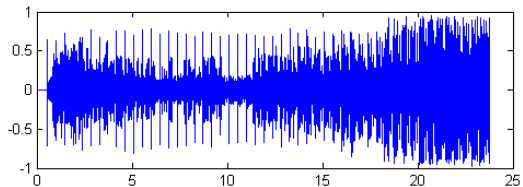
Adaptive Line Enhancer

- ▶ Delays a signal by Δ samples and attempts to predict it.
- ▶ Cancels uncorrelated components, such as noise.
- ▶ Cancels correlated components, such as feedback howling.



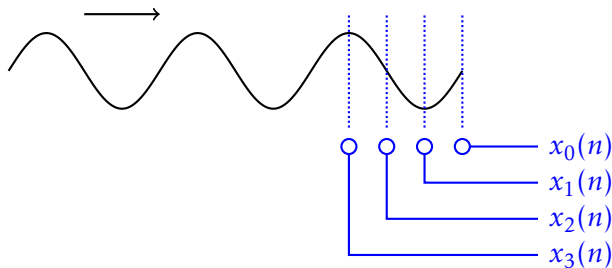
Beat Detection

- ▶ The beats in a music dictates its rhythm.
- ▶ Mixing of music relies of beat matching.



Beamforming

- ▶ Temporal correlation matrix correlates samples in time.
- ▶ Spatial correlation matrix correlates samples in space.
- ▶ Sampling in time and space are equivalent.

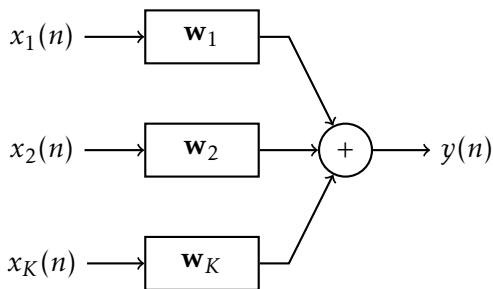


$$\mathbf{x}(n) = [x_0(n) \quad x_0(n-1) \quad x_0(n-2) \quad x_0(n-3)] \Rightarrow \mathbf{R}_{\mathbf{xx}} = \mathbf{x}^T \mathbf{x}$$

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Beamforming

- ▶ Filtering in both temporal and spatial domain.
- ▶ Listening to or cancel a spatially located source.
- ▶ Standard methods such as $\mathbf{w}_{\text{opt}} = \mathbf{R}_{\mathbf{xx}}^{-1} \mathbf{r}_{d\mathbf{x}}$ still applies.



Choose your own project

Or, choose your own project...