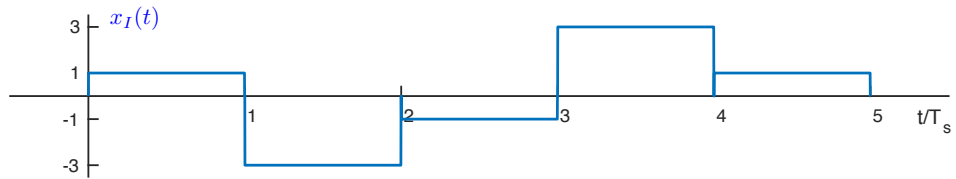
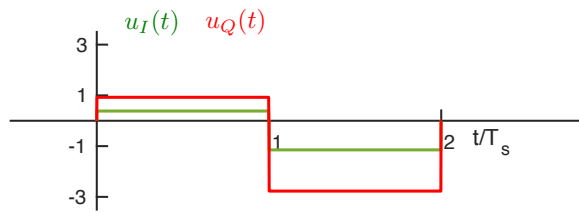


Solutions Week 7

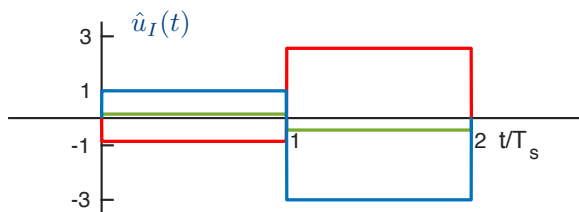
7.1 a.



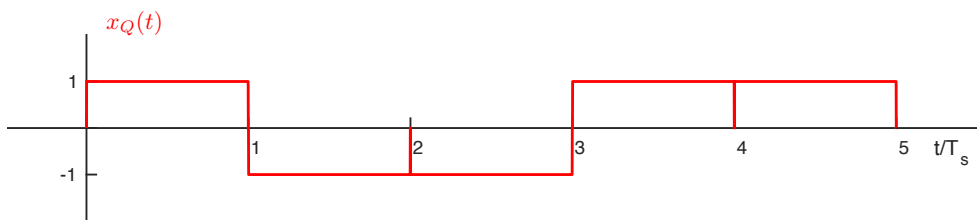
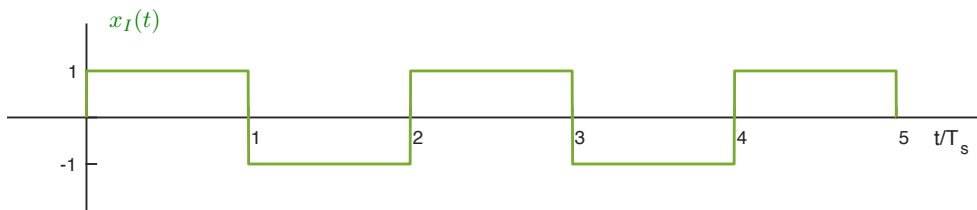
b.



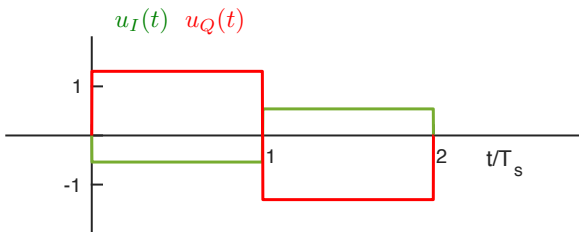
c.



7.2 a.



b.



c. The data is not directly visible in $u_I(t)$ or $u_Q(t)$ due to the crosstalk. For example, the shape of $u_I(t)$ looks different from $x_I(t)$. In general the shape of $u_I(t)$ or $u_Q(t)$ depends on the data and on the amount of phase error $\phi_{err}(t)$.

7.3 a. With

$$u_I(t) \cos(\phi_{err}(t)) = \frac{x_I(t)}{2} A \cos^2(\phi_{err}(t)) + \frac{x_Q(t)}{2} A \sin(\phi_{err}(t)) \cos(\phi_{err}(t))$$

$$u_Q(t) \sin(\phi_{err}(t)) = \frac{x_Q(t)}{2} A \cos(\phi_{err}(t)) \sin(\phi_{err}(t)) - \frac{x_I(t)}{2} A \sin^2(\phi_{err}(t))$$

we get

$$\hat{u}_I(t) = \frac{x_I(t)}{2} A \cos^2(\phi_{err}(t)) + \frac{x_I(t)}{2} A \sin^2(\phi_{err}(t)) = \frac{x_I(t)}{2} A$$

We can conclude that by choosing $A = 2$ the signal $x_I(t)$ can be perfectly recovered despite of the phase error.

b. Using the same concept as above, we can choose

$$\hat{u}_Q(t) = u_I(t) \sin(\phi_{err}(t)) + u_Q(t) \cos(\phi_{err}(t)) = \frac{x_Q(t)}{2} A$$

to cancel out the crosstalk (please verify).

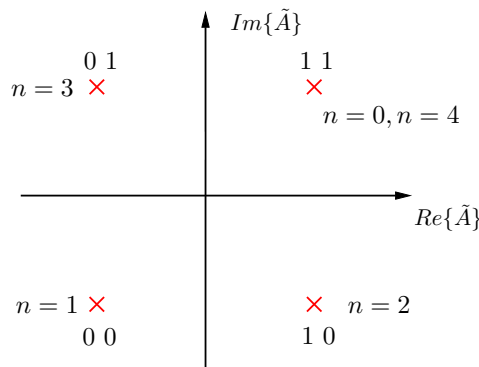
7.4 Let $\phi = \phi_{err}(t)$. Then

$$\begin{aligned} \tilde{u}(t) &= A/2 \tilde{x} e^{-j\phi} = A/2 (x_I(t) + j x_Q(t)) (\cos(\phi) - j \sin(\phi)) \\ &= A/2 (x_I(t) \cos(\phi) + x_Q(t) \sin(\phi)) + j A/2 (x_Q(t) \cos(\phi) - x_I(t) \sin(\phi)) \end{aligned}$$

We can identify $u_I(t) = Re\{\tilde{u}(t)\}$ and $u_Q(t) = Im\{\tilde{u}(t)\}$.

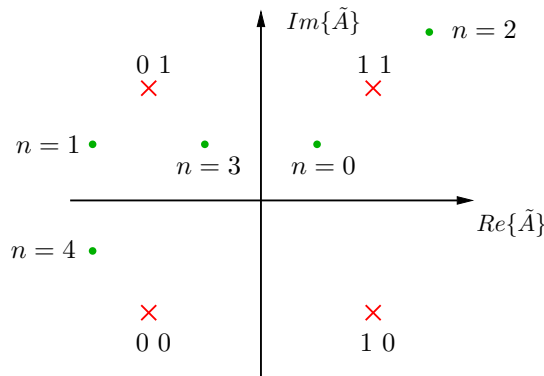
7.5 a. $\tilde{A}_{m[n]} = (1 + j), (-1 - j), (1 - j), (-1 + j), (1 + j)$

b.



c. $\tilde{C} = 1000 e^{j(\phi_a + \phi_{err})} \cdot \frac{1}{T_s}$ with $A = 2$ and $E_g = T_s$

d.



$$\tilde{A}_{m[n]} = (1 + j), (-1 + j), (1 + j), (-1 + j), (-1 - j), \quad \mathbf{b} = 1101110100$$