



LUND
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EITF35: Introduction to Structured VLSI Design

Part 2.2.1: Sequential circuit

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Lab computer log in

Username: group name (svd01-svd16)

Password: 15Change

You may change your password after first log-in

Come to me if the door access is not working



Outline

- **Sequential vs. Combinational**
- **Synchronous vs. Asynchronous**
- **Basic Storage Elements**
- **Timing**
- **Folding & Pipeline**



Sequential vs. Combinational

□ A combinational circuit:



□ At any time, outputs depend only on present inputs

- Changing inputs changes outputs

□ No regard for previous inputs

- No memory (history)

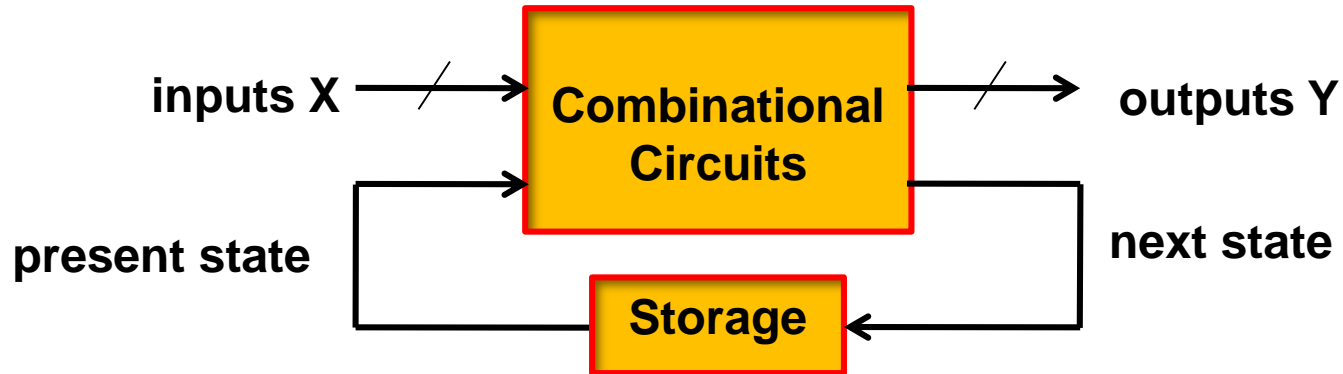
□ Time is “ignored” !

- Time-independent circuit



Sequential vs. Combinational

□ A sequential circuit:



□ Outputs depends on inputs and **past history** of inputs

- Previous inputs can be stored into **storage elements**
- **Input order matters**

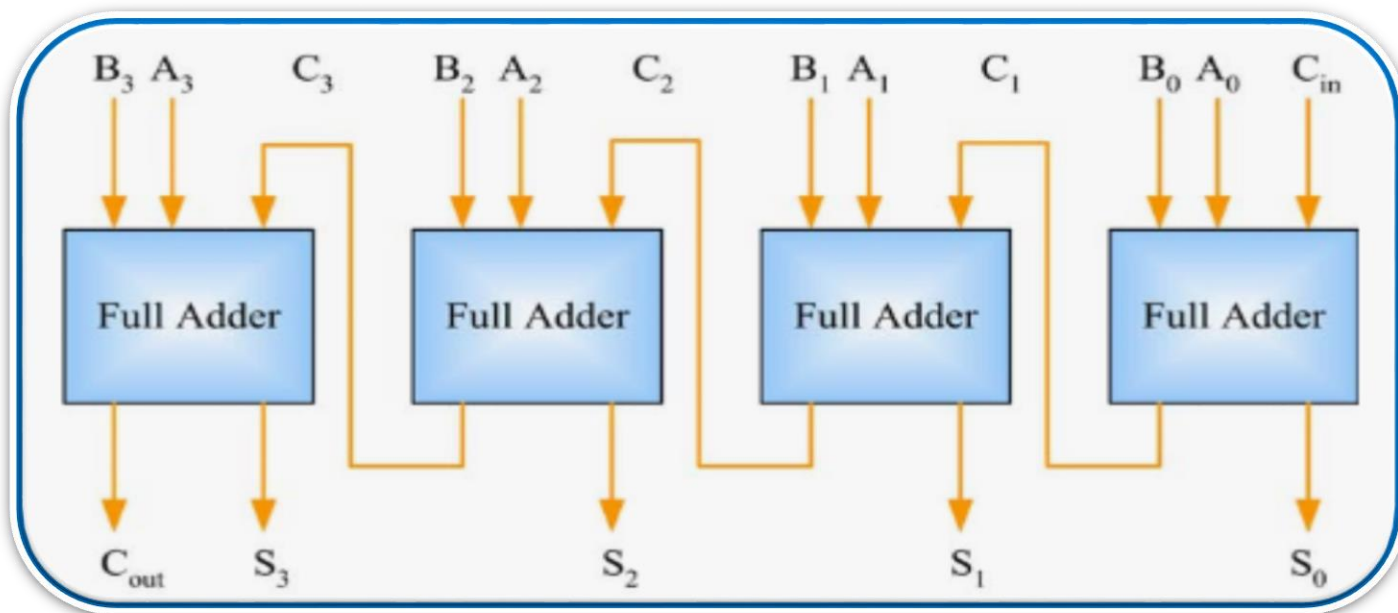


Sequential vs. Combinational: adders

□ Calculate $A_3A_2A_1A_0 + B_3B_2B_1B_0$

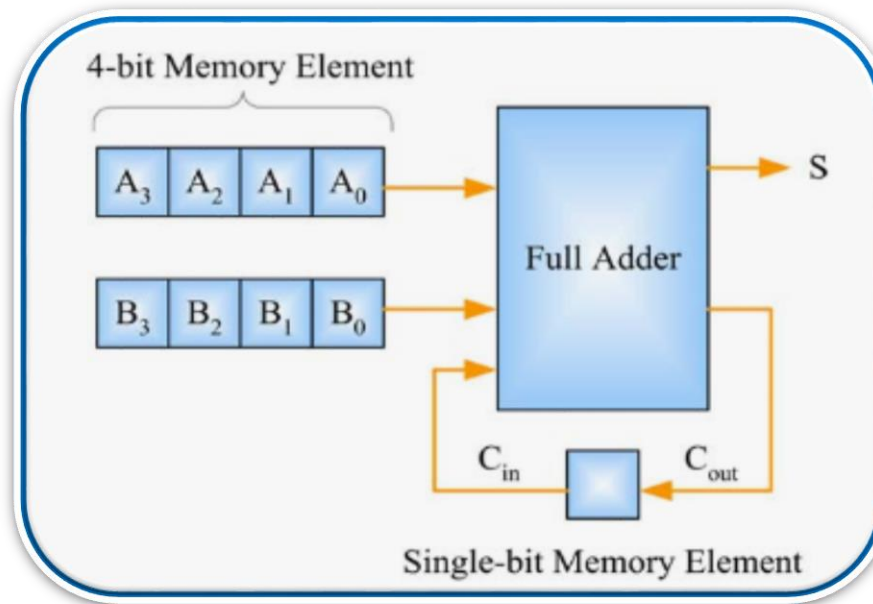
□ Combinational adder

- 4 full adders are required
- One adder is active at a time slot



What we can do with storage elements?

□ Sequential Adder



□ Folding!

- One full adder
- 1-bit memory for carry
- Two 4-bit memory for operators

□ 4 clock cycles to get the output



Outline

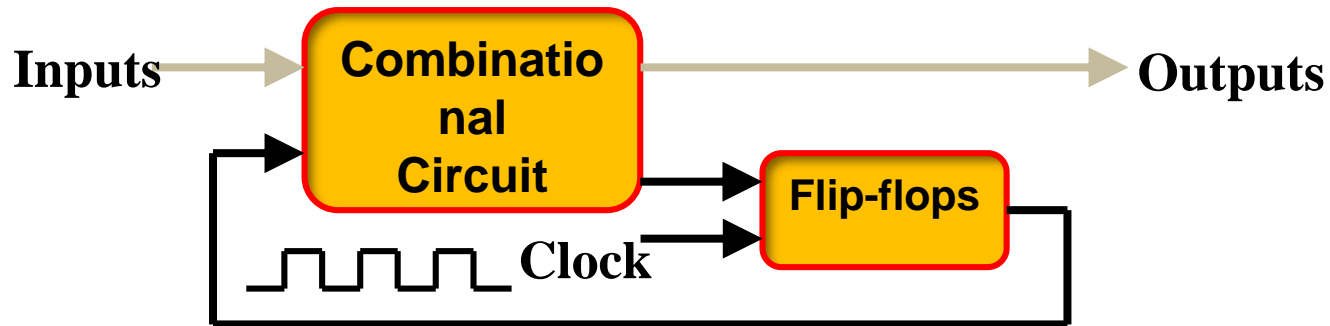
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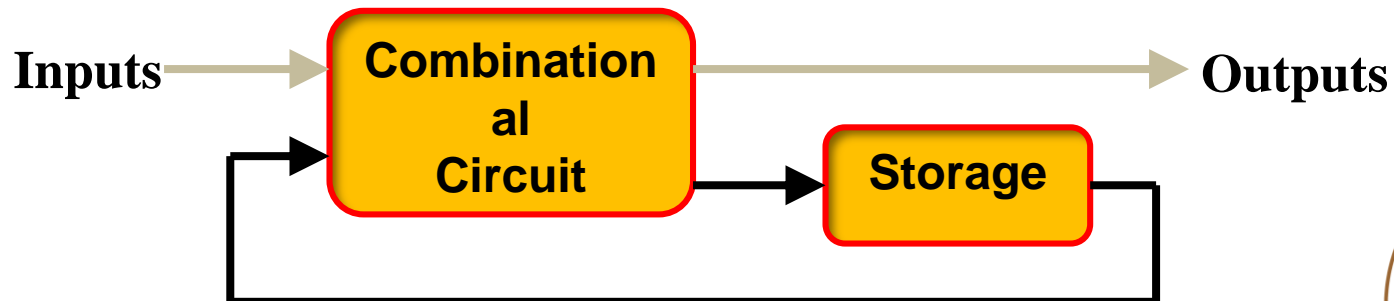
Synchronous vs. Asynchronous

Two types of sequential circuits:

- **Synchronous**: The behavior of the circuit depends on the input signal at discrete instances of time (also called **clocked**)



- **Asynchronous**: The behavior of the circuit depends on the input signals at **any instance of time**



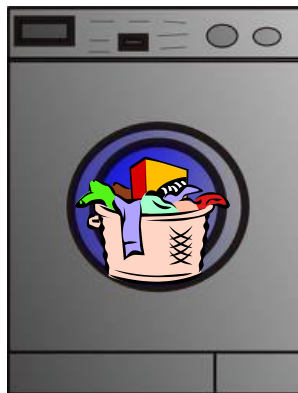
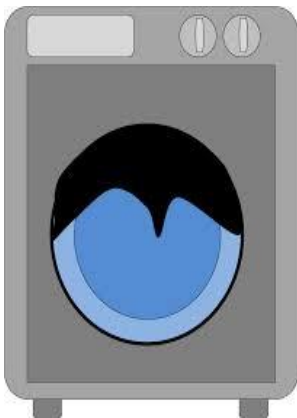
Synchronous vs. Asynchronous

- ❑ When you have a clock
- ❑ You know that washer takes 1 hour
- ❑ You put the laundry in the washer and leave
- ❑ Dry 1 hour later



Synchronous vs. Asynchronous

□ What if you don't have a clock ...



Synchronous or Asynchronous?

□ Sync. Advantages: Simplicity to design, debug, and test

- Timing is controlled by one simple clock
- No hand-shake circuits
- Well supported by EDA tools
- Recommended for **VLSI**

□ Sync. Disadvantages:

- Performance constrained by worst-case: critical path
- Overhead for clock network
- Less power efficient

We will focus on synchronous circuits in this course



Power Example

Power Group	Internal Power	Switching Power	Leakage Power	Total Power (%)	Attrs
io_pad	0.0000	0.0000	0.0000	0.0000 (0.00%)	
memory	0.0000	0.0000	0.0000	0.0000 (0.00%)	
black_box	0.0000	0.0000	0.0000	0.0000 (0.00%)	
clock_network	0.0137	4.982e-03	3.116e-05	0.0187 (13.76%)	
register	3.029e-03	1.298e-03	8.082e-04	5.136e-03 (3.79%)	
combinational	0.0518	0.0557	4.337e-03	0.1118 (82.45%)	



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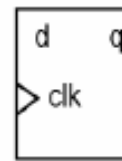
Basic storage element

- D latch: level sensitive
- D flip-flop (D-FF): edge sensitive



c	q*
0	q
1	d

D latch



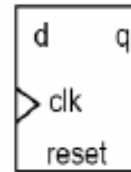
clk	q*
0	q
1	q
\uparrow	d

pos-edge triggered D-FF



clk	q*
0	q
1	q
\downarrow	d

neg-edge triggered D-FF



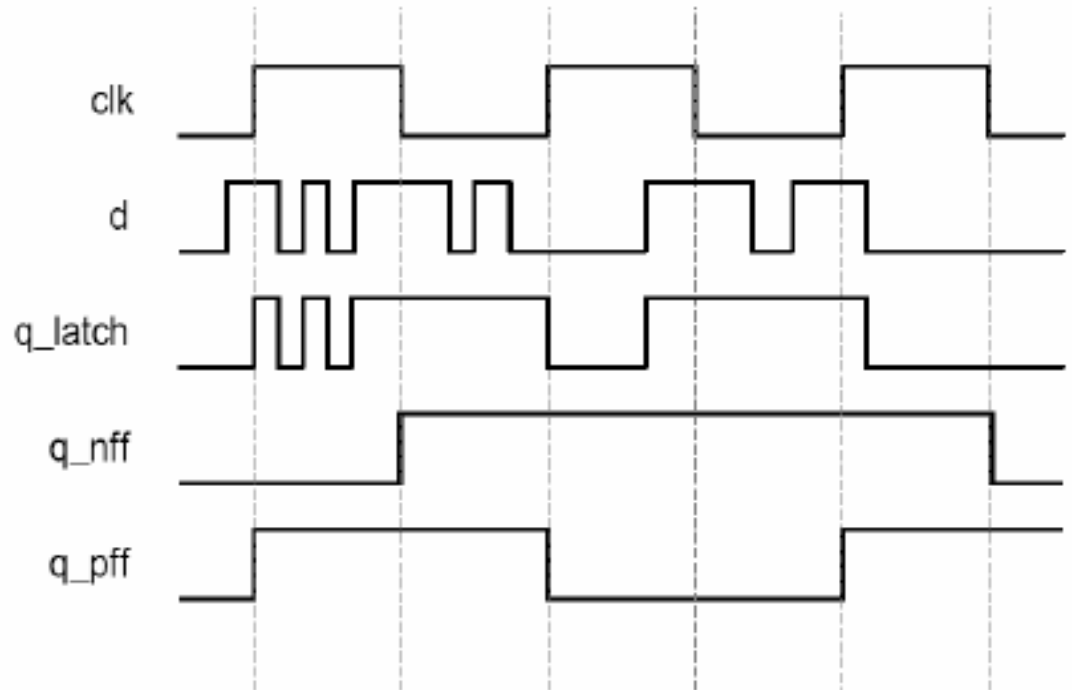
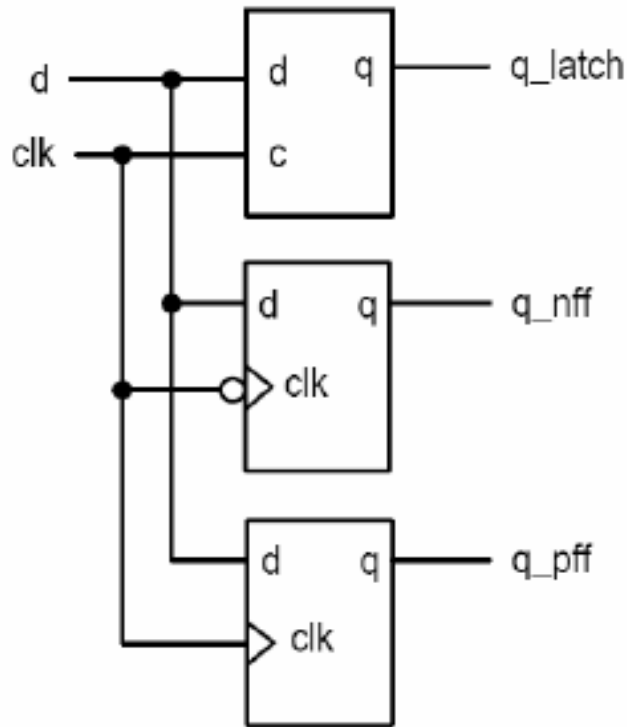
reset	clk	q*
1	-	0
0	0	q
0	1	q
0	\uparrow	d

D-FF with reset



Basic storage element

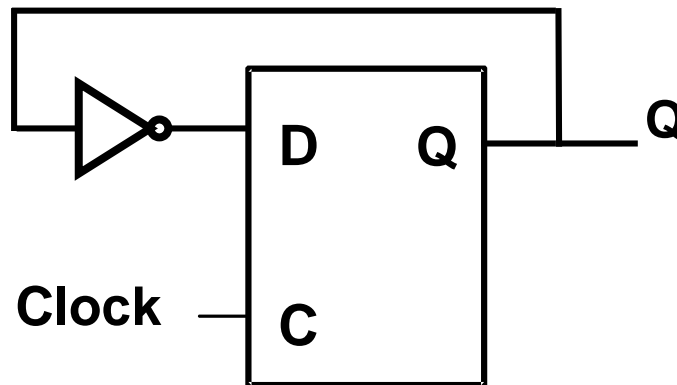
- D latch: level sensitive
- D flip-flop (D-FF): edge sensitive



Problem with Latches

- ❑ Problem: A latch is transparent; state keep changing as long as the clock remains active
- ❑ Due to this uncertainty, latches can not be reliably used as storage elements.
- ❑ What happens if Clock=1? What will be the value of Q when Clock goes to 0?

Latch Example



Most EDA software tools have difficulty with latches.



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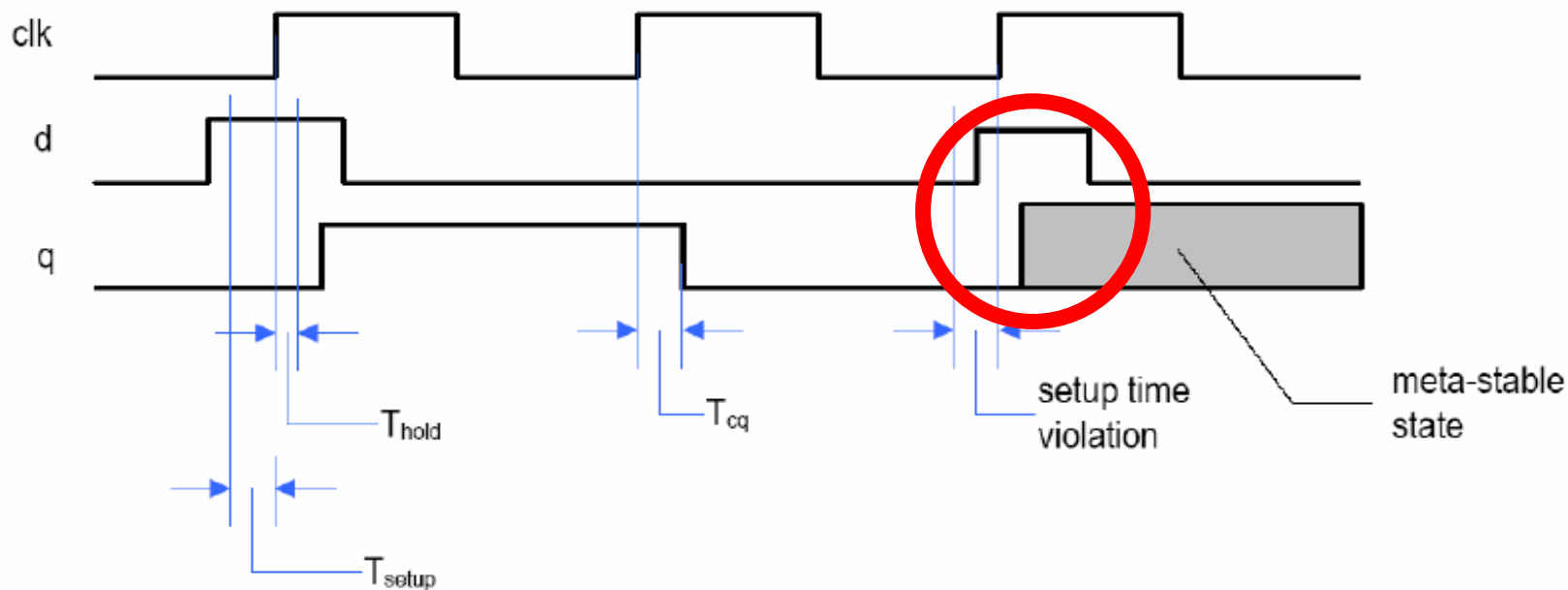


Flip Flops Timing

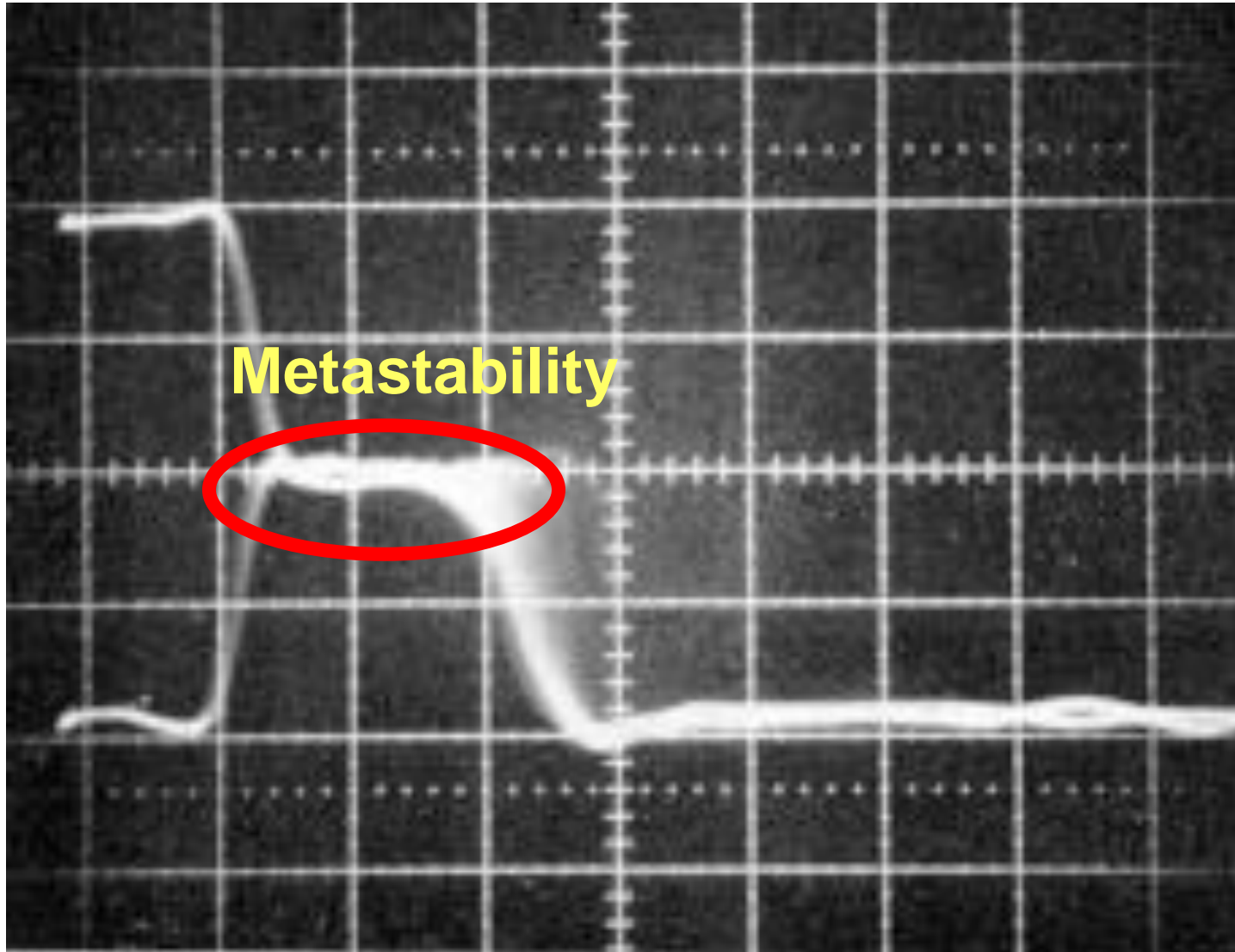
Very Important Timing Considerations!

□ **Setup Time** (T_s): The minimum time during which D input must be maintained **before** the clock transition occurs.

□ **Hold Time** (T_h): The minimum time during which D input must not be changed **after** the clock transition occurs.

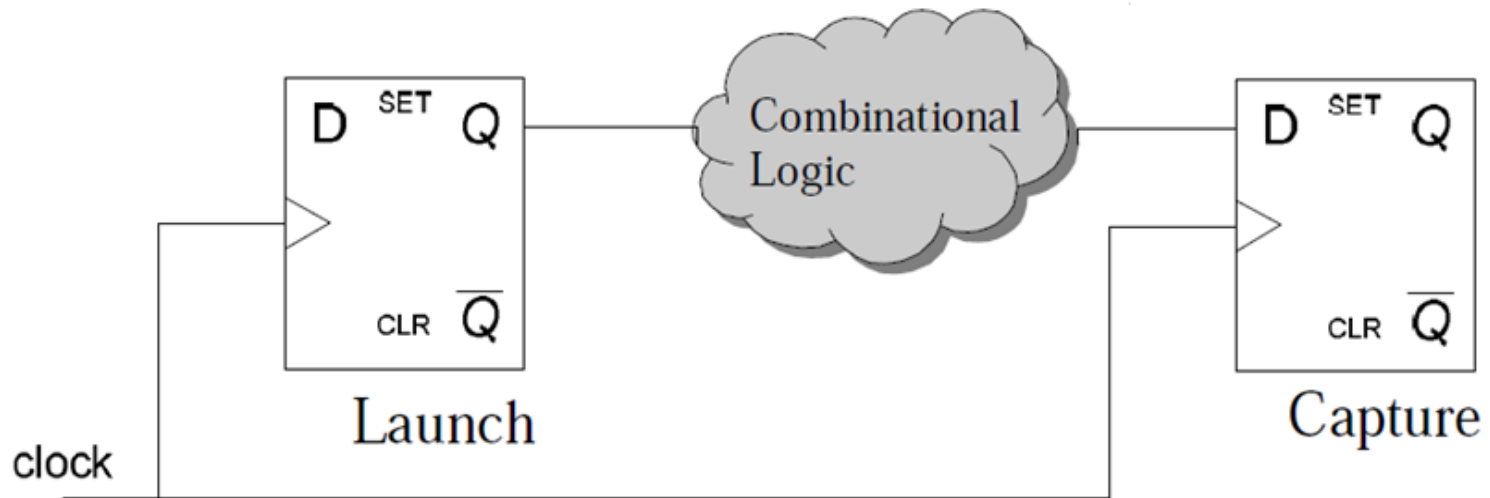


Metastability in Digital Logic



How fast can a synchronous circuit run?

□ RTL (Register Transfer Level)



□ Timing analysis:

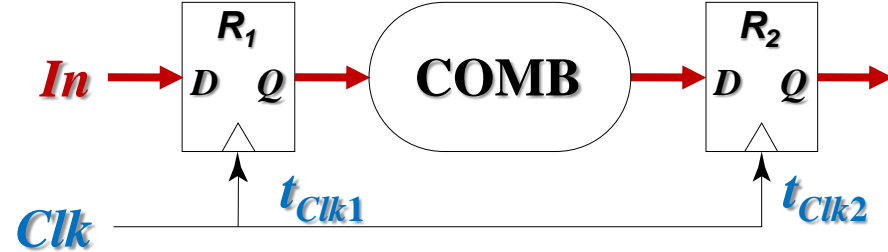
- Starting with the clock rising edge at the launch FF, end with the clock rising edge (**next period or same period**) of the capture FF



Setup Time

Setup Timing analysis:

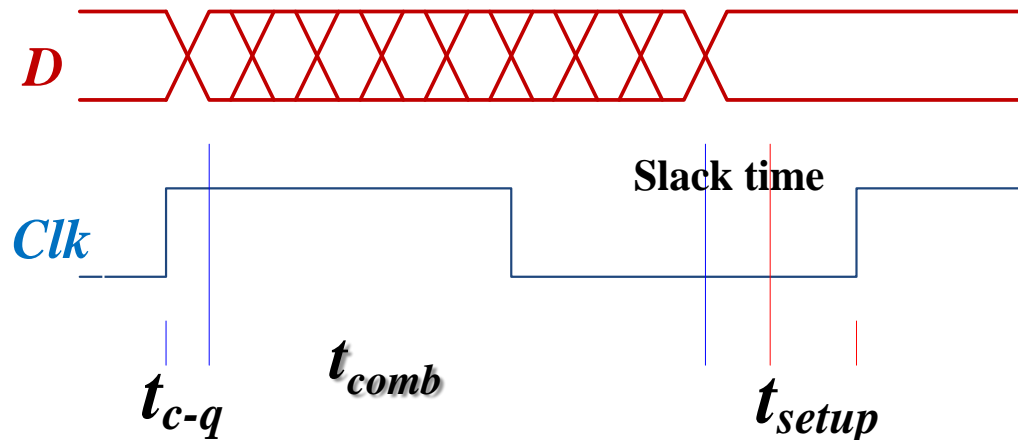
- Starting with the clock rising edge at the launch FF, end with the clock rising edge (**next period**) of the capture FF



Data-Path (arrive time): $T_{\text{Combinational logic}} + FF_{\text{launch}}(\text{clk} \rightarrow Q)$

Clock-Path (required time): Clock Period - $FF_{\text{capture}} t_{\text{Setup}}$

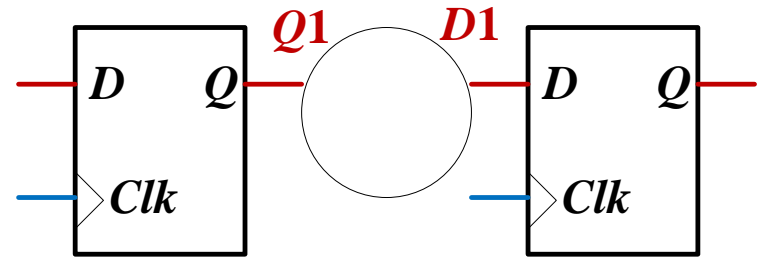
Timing constraint : $T_{\text{Combinational logic}} + FF_{\text{launch}}(\text{clk} \rightarrow Q) < \text{Clock Period} - FF_{\text{capture}} t_{\text{Setup}}$



Hold Time

Hold Timing analysis:

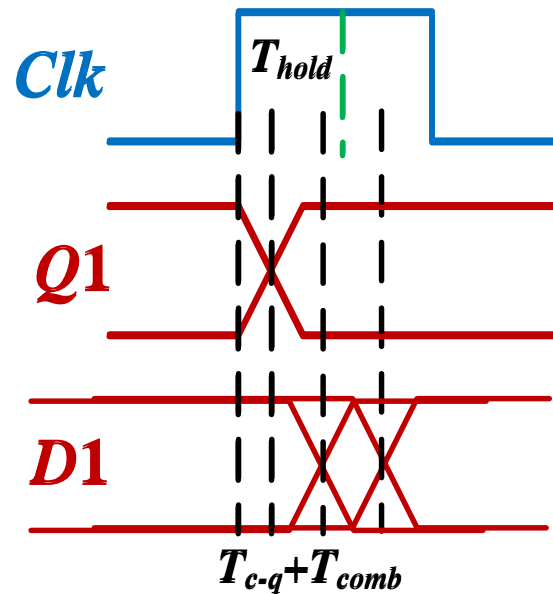
- Starting with the clock rising edge at the launch FF, end with the clock rising edge (same period) of the capture FF



Data-Path (arrive time): $T_{\text{Combinational logic}} + FF_{\text{launch}}(\text{clk} \rightarrow Q)$

Clock-Path (required time): $FF_{t\text{Hold}}$

Timing constraint : $T_{\text{Combinational logic}} + FF_{\text{launch}}(\text{clk} \rightarrow Q) > FF_{t\text{Hold}}$



Clock uncertainty

□ Clock uncertainty = skew ± jitter

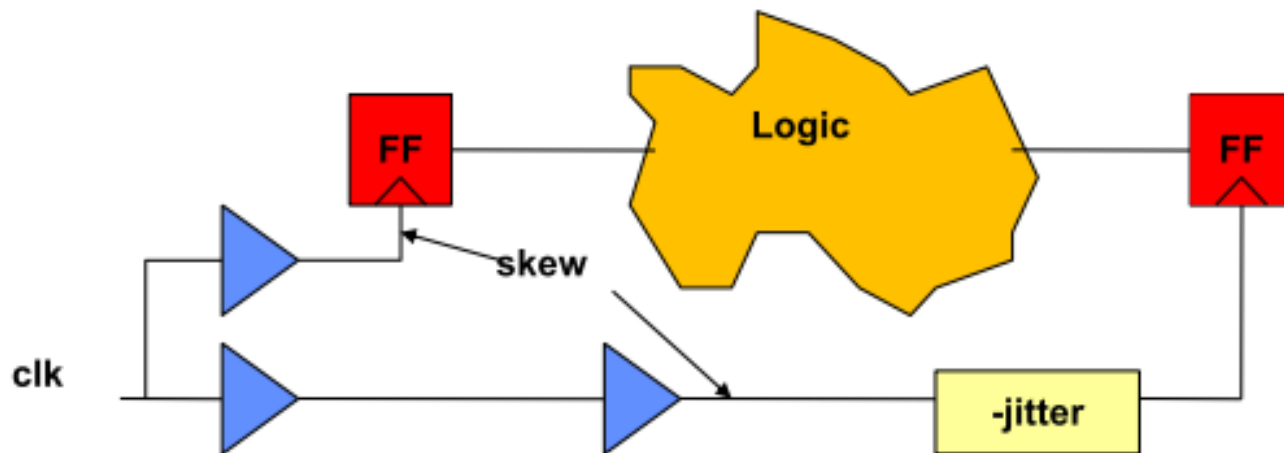
□ Clock skew

- The (knowable) difference in clock arrival times at each flip-flop
- Caused mainly by imperfect balancing of clock tree/mesh

□ Clock jitter

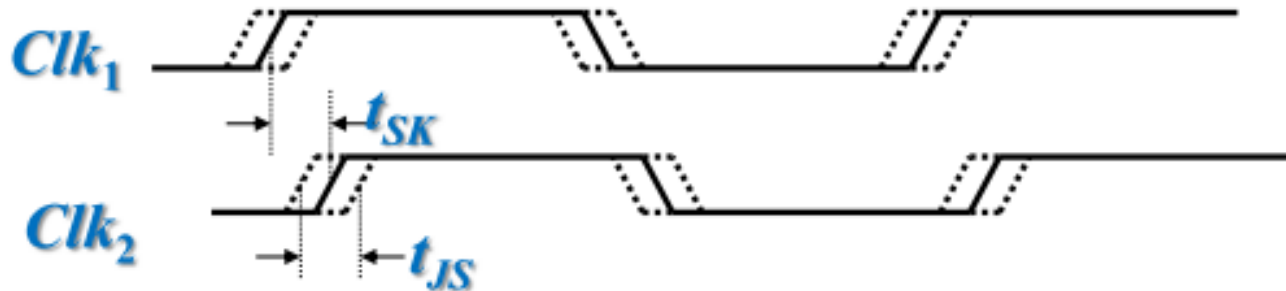
- The random (unknowable) difference in clock arrival times at each flip-flop
- Caused by on-die process, V_{dd} , temperature variation, PLL jitter, crosstalk.

□ Clock tree to minimize clock uncertainty

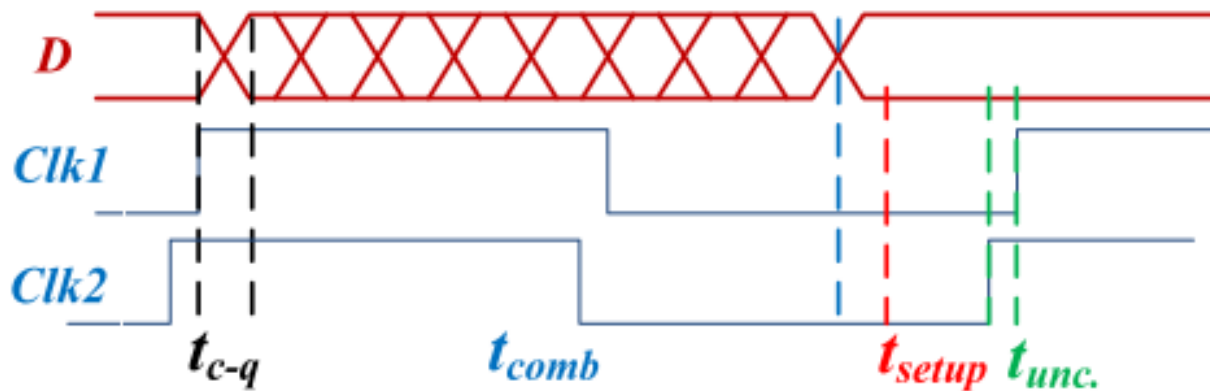


Clock uncertainty

□ Clock uncertainty = skew \pm jitter



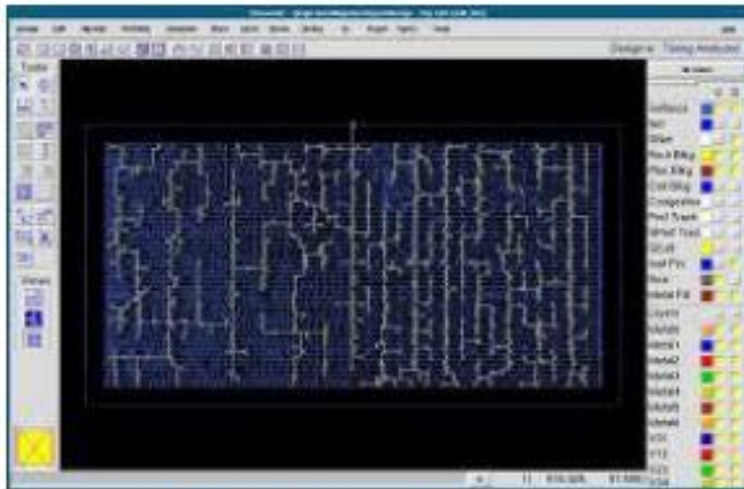
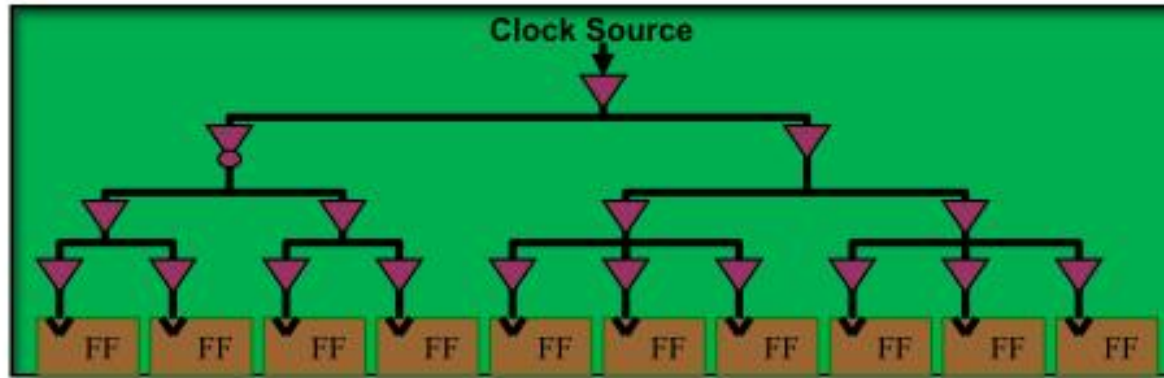
□ Timing analysis with clock uncertainty



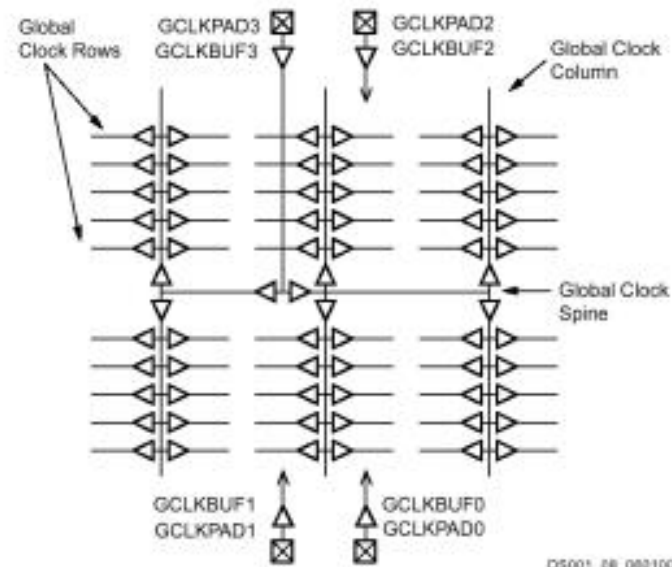
$$T_{\text{Combinational logic}} + FF_{\text{launch}}(\text{clk} \rightarrow \text{Q}) < \text{Clock Period} - FF_{\text{tSetup}} - \text{Clock Uncertainty}$$



Clock tree



Clock-tree Asic

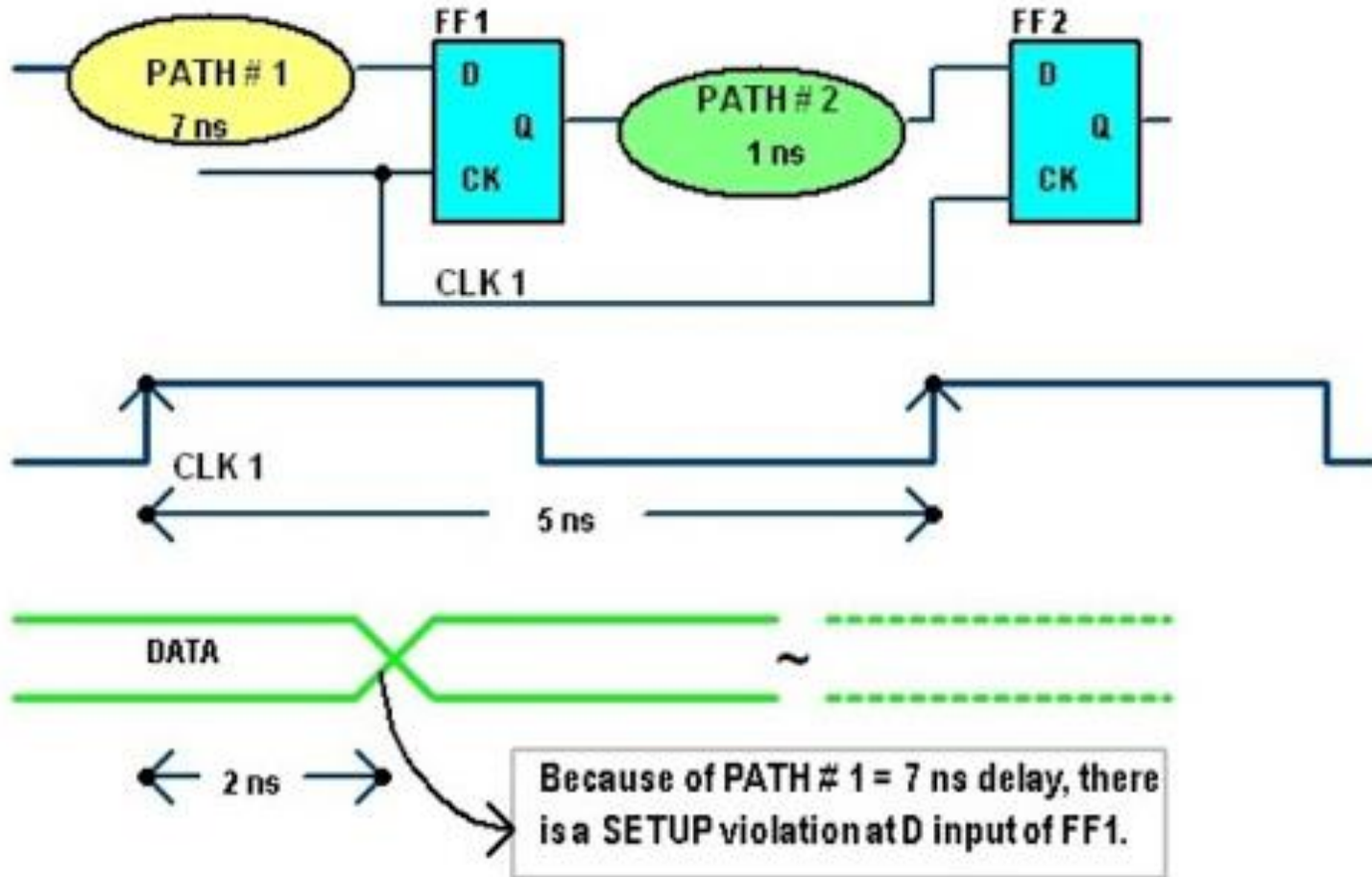


Global clock network in Xilinx FPGA

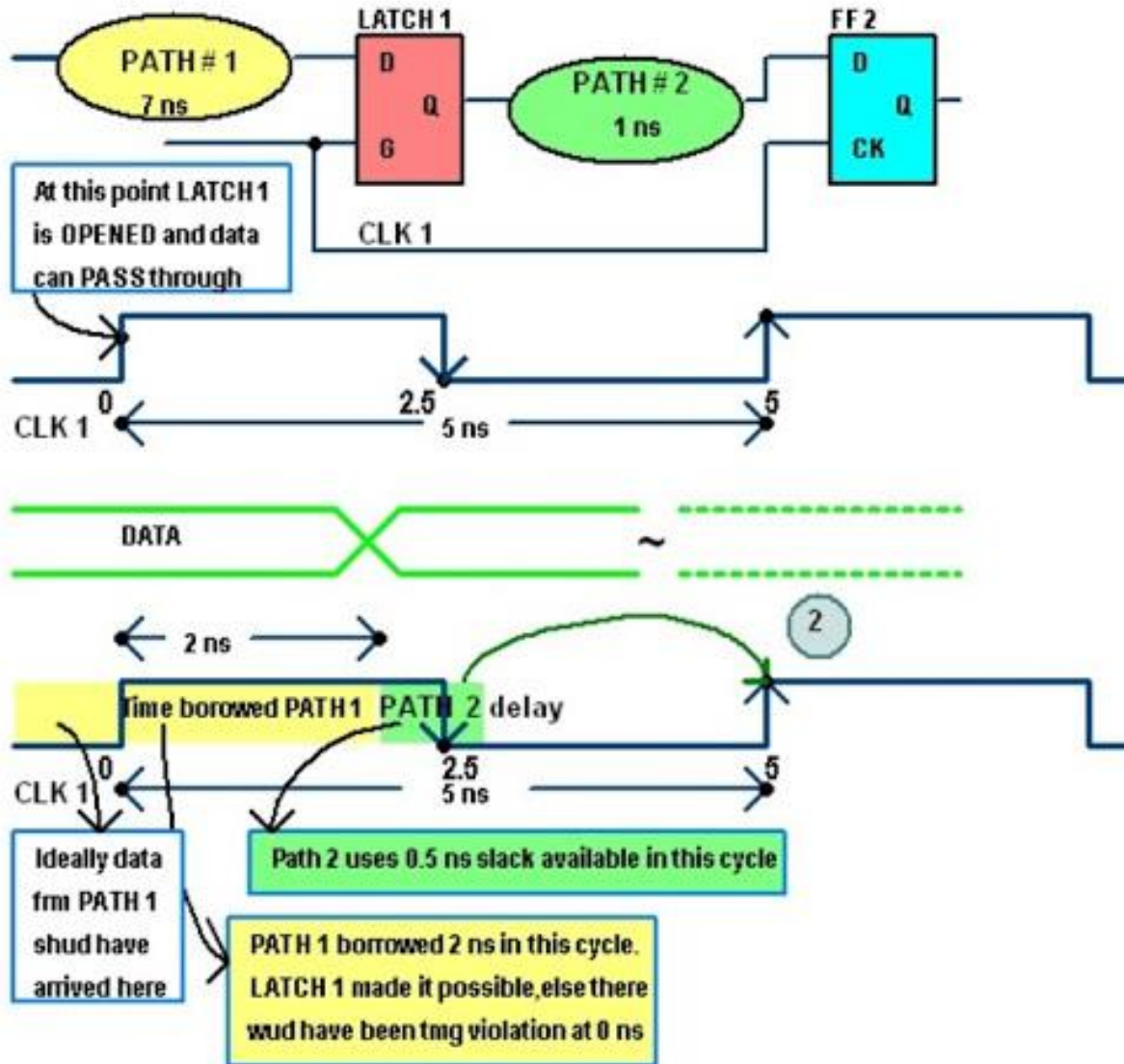
DS001_08_002100



Time borrow



Time borrow



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- **Folding & Pipeline**



Pipeline

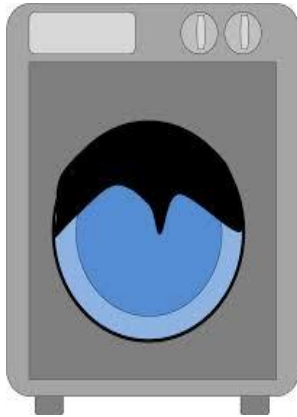
□ Acknowledgement:

- The following slides have been provided by Prof. Ward in September 2004.
- Reformatting of PowerPoint and addition of two more slide done September 2007 by Jens Sparsø.
- Slides are used in DTU course 02154 Digital Systems Engineering (fall 2008).
- Due to Joachim Rodrigues' position at DTU, I used some of the slides in EITF35.



Pipelining

□ Start again from laundry room



□ Small laundry has one washer, one dryer and one folder, it takes 110 minutes to finish one load:

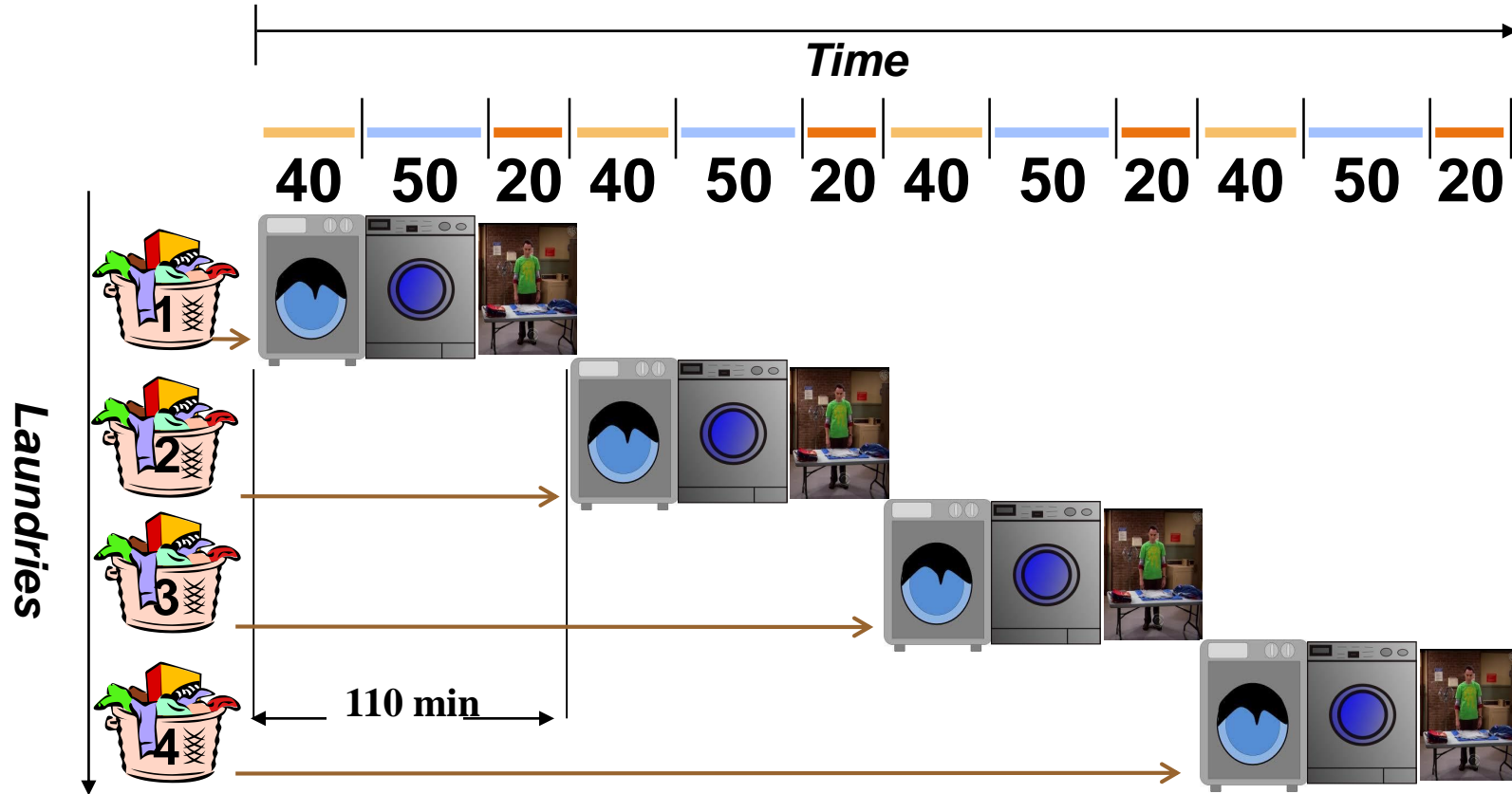
- Washer takes 40 minutes
- Dryer takes 50 minutes
- “Folding” takes 20 minutes



□ Need to do 4 laundries



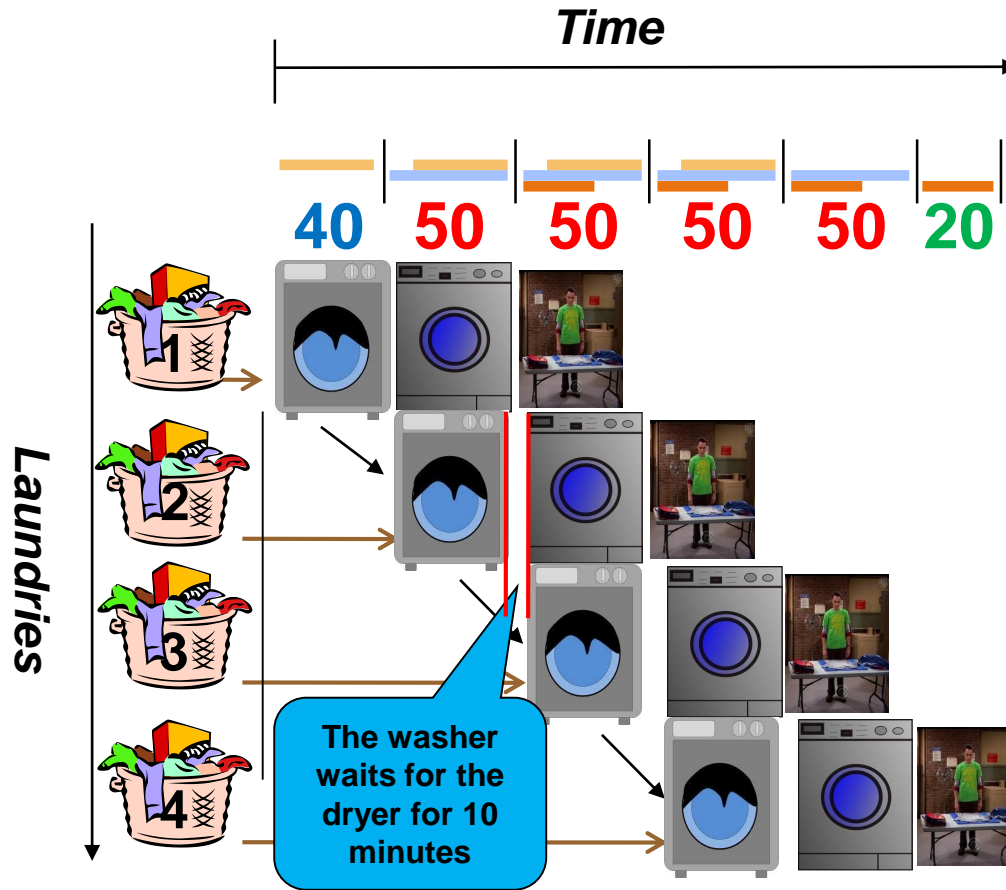
Not very smart way...



$$\begin{aligned} \text{Total} &= N * (\text{Washer} + \text{Dryer} + \text{Folder}) \\ &= \underline{\quad 440 \quad} \text{ mins} \end{aligned}$$



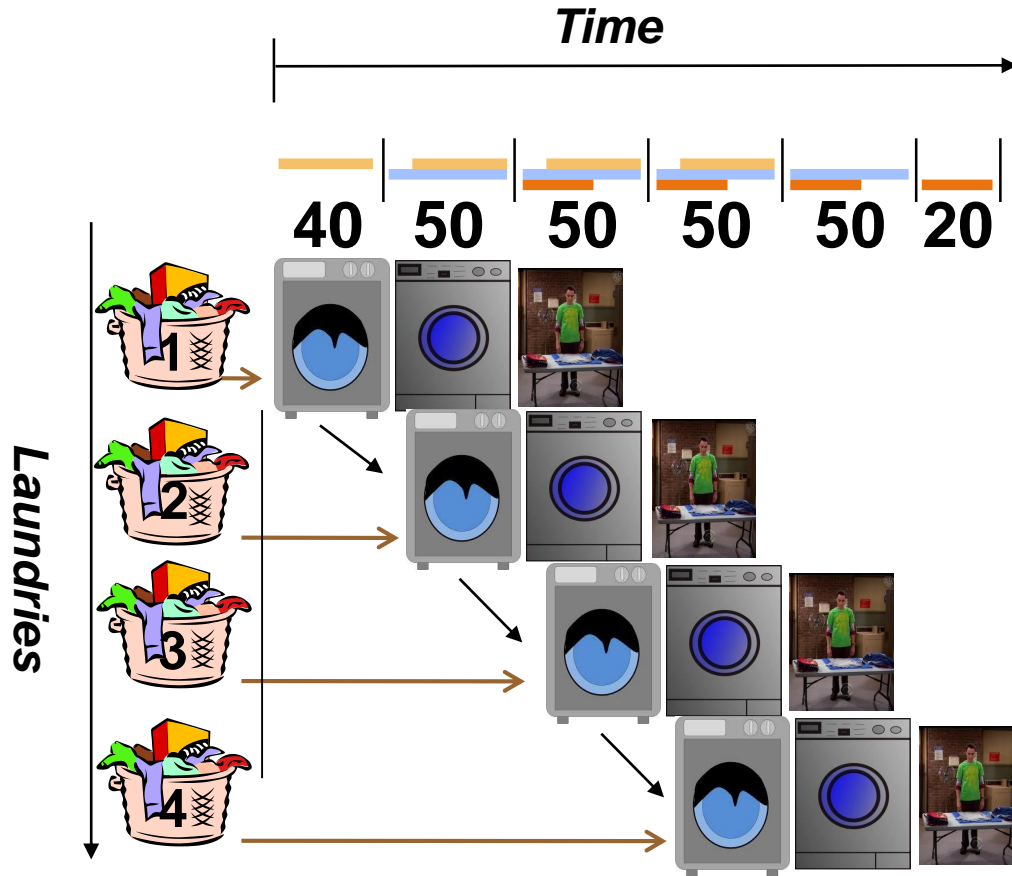
If we pipelining



$$\begin{aligned} \text{Total} &= \text{Washer} + N * \text{Max}(\text{Washer}, \text{Dryer}, \text{Folder}) + \text{Folder} \\ &= \underline{\quad 260 \quad} \text{ mins} \end{aligned}$$



Pipeline Facts



- Multiple tasks operating simultaneously
- Pipelining doesn't help **latency** of single task, it helps **throughput** of entire workload
- Pipeline rate limited by slowest pipeline stage**
- Unbalanced** lengths of pipe stages reduces speedup
- Potential speedup \propto **Number of pipe stages**



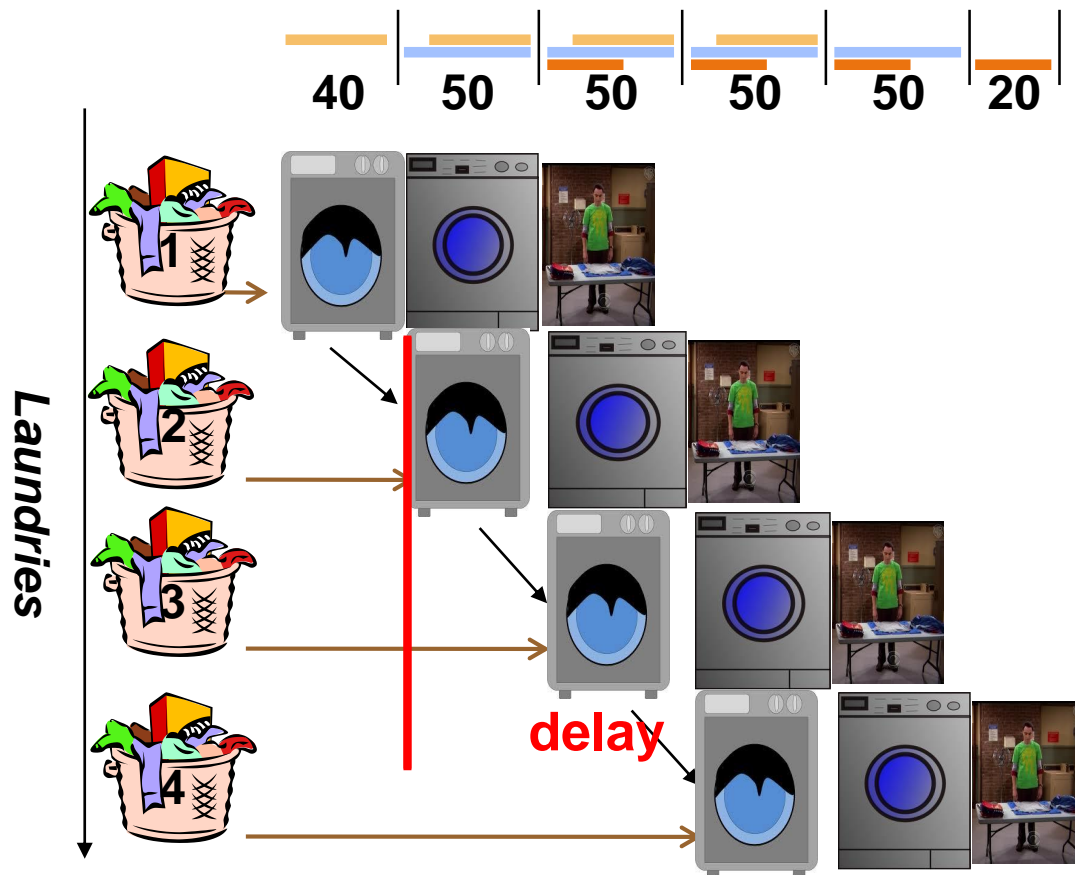
Some definitions

Very Important!

- **Latency**: The delay from when an input is established until the output associated with **that input** becomes valid.

(non-pipeline Laundry = 110 mins)

(pipeline Laundry = 120 mins)



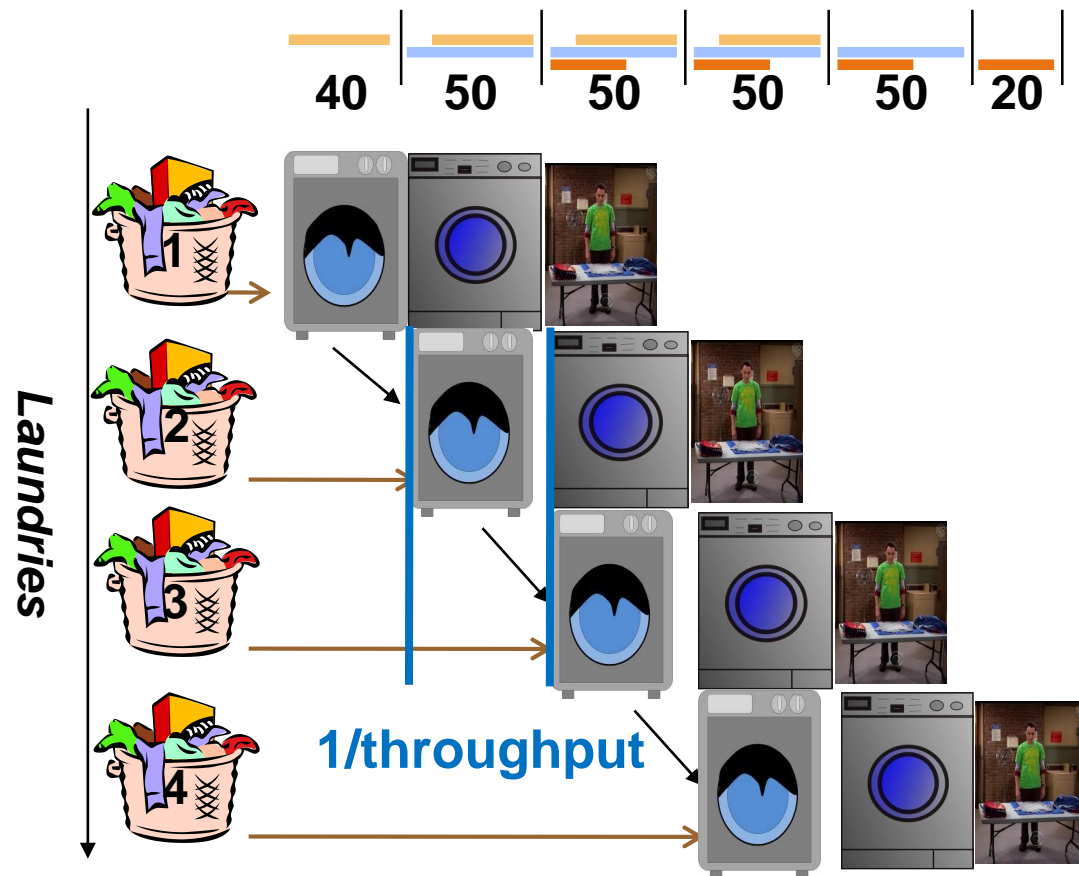
Some definitions

Very Important!

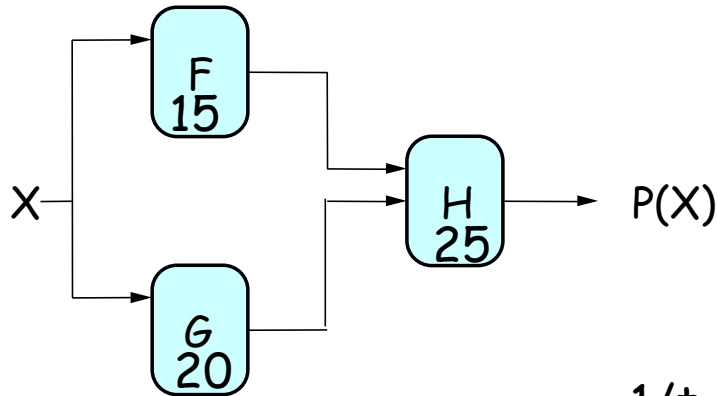
- **Throughput:** The rate of which inputs or outputs are processed or **how frequently** a laundry can be loaded

(non-pipeline Laundry = $\frac{1}{110}$ outputs/min)

(pipeline Laundry = $\frac{1}{50}$ outputs/min)



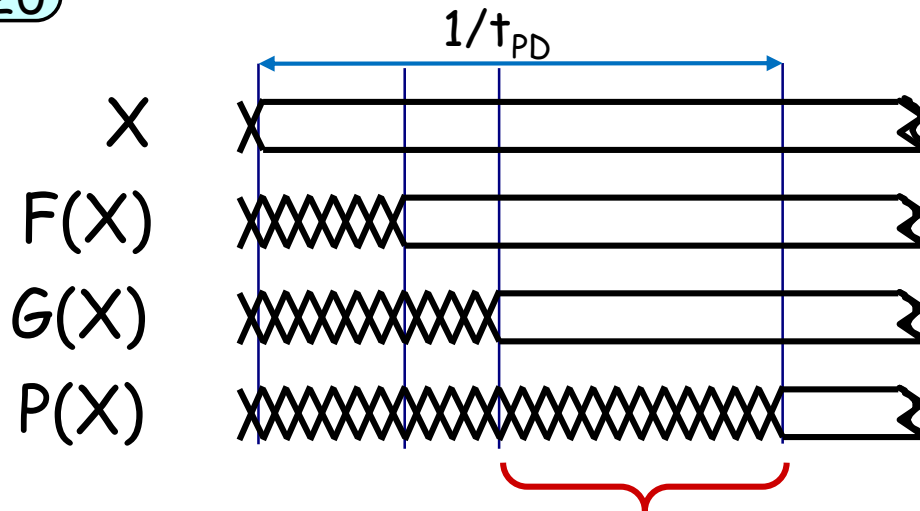
Okay, back to circuits...



Combinational logic:

$$\text{latency} = t_{PD},$$
$$\text{throughput} = 1/t_{PD}.$$

Can we use the hardware more efficiently?

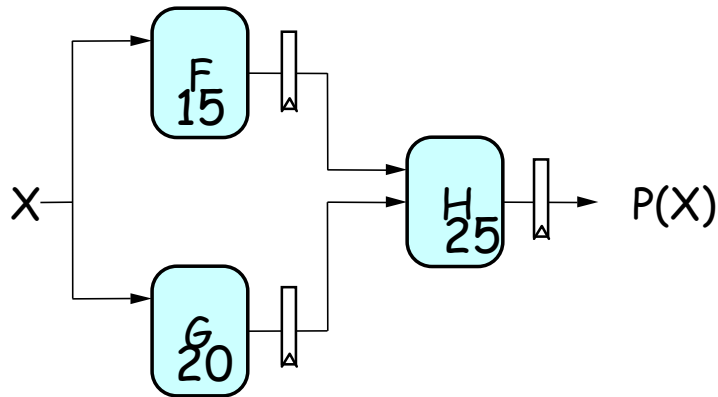


F & G are “idle”, just holding their outputs stable while H performs its computation



Pipelined Circuits

use registers to hold H's input stable!



□ Pipelined circuit:

- 2-stage *pipeline*: if we have a valid input X during clock cycle j , $P(X)$ is valid during clock $j+2$.
- Now F & G can be working on input X_{i+1} while H is performing its computation on X_i .

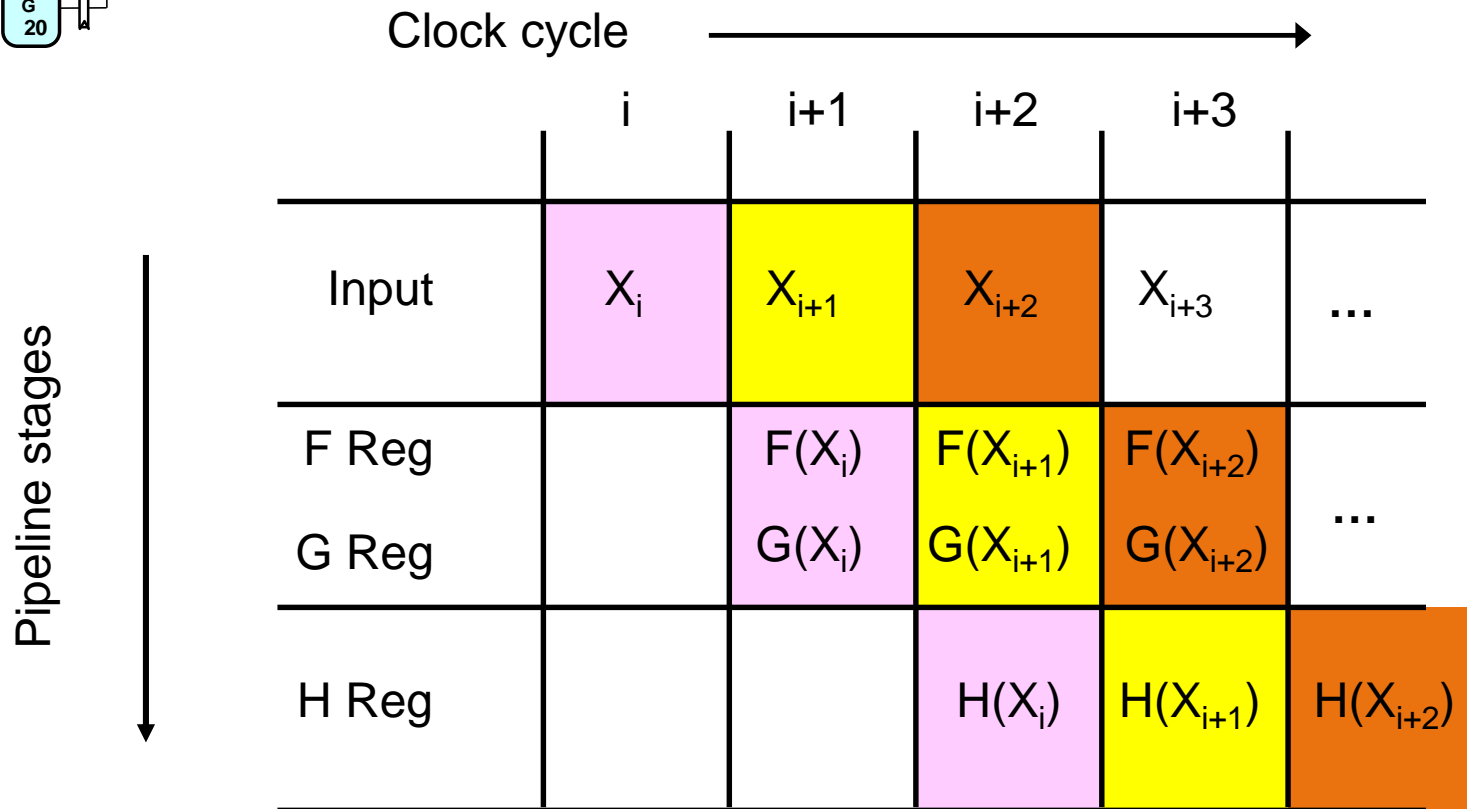
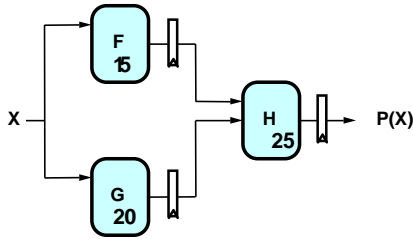
Exercise 1min

Suppose F , G , H have propagation delays of 15, 20, 25 ns and we are using ideal zero-delay registers:

	<u>latency</u>	<u>throughput</u>
un-pipelined	45	1/45
2-stage pipelined	<u>50</u>	<u>1/25</u>
	worse	better

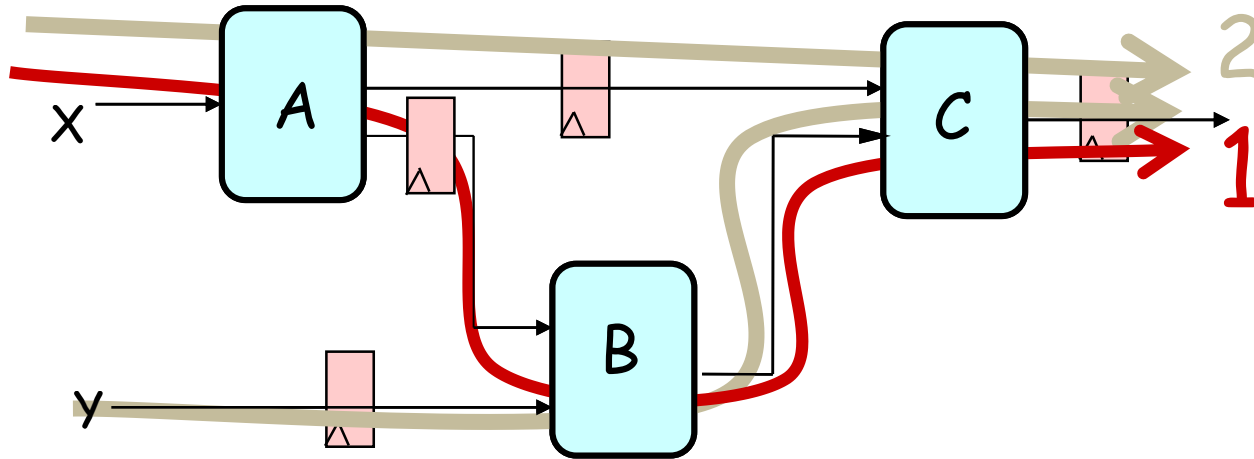


Pipeline timing diagrams



Ill-formed pipelines

Consider a BAD job of pipelining:



Problem:

Some paths from inputs to outputs had 2 registers, and some had only 1!

Make sure every paths have been pipelined with same stages



Combinational, Folding and Pipelined

□ Combinational Circuits

- **Advantage:** low latency
- **Disadvantage:** low throughput, more hardware, low utilization

□ Folding

- **Advantage:** less hardware, high utilization
- **Disadvantage:** high latency, limited application

□ Pipeline

- **Advantage:** very high throughput
- **Disadvantages:** pipeline latency, more hardware



Thanks!

