UNIVERSITY

# EITF35: Introduction to Structured VLSI Design 

Part 1.2.1: Finite State Machines

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## Outline

$\square$ FSM Overview
-FSM Representation

- examples
$\square$ Moore vs. Mealy Machine
- from circuits perspective


## FSM Overview

Ilt has at most a finite number of states
$\square$ Models for representing sequential circuits
-Used mainly as a controller in a large system
$\square$ Moore vs. Mealy machines



## Abstraction of state elements

$\square$ A FSM consists of several states. Inputs into the machine are combined with the current state of the machine to determine the new state or next state of the machine.
$\square$ Depending on the state of the machine, outputs are generated based on either the state or the state and inputs of the machine.


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$\square$ Depending on the state of the machine, outputs are generated based on either the state or the state and inputs of the machine.
$\square$ Divide circuit into combinational logic and state


## Outline

■FSMI Overview
-FSM Representation
■Moore vs. Mealy Outputs
■Exercise


## FSM Representation

$\square$ Can be represented using a state transition table which shows the current state, input, any outputs, and the next state.

| Input <br> Current State | Input $^{\text {o }}$ | Input $_{1}$ | .... Input $_{\text {n }}$ |
| :---: | :---: | :---: | :---: |
| State $_{0}$ State $_{1}$ .... State $_{\mathrm{n}}$ | Next State $/$ Output  <br> $\ldots$. $\ldots$. <br> $\ldots$. $\ldots$. <br> $\ldots$. $\ldots$. |  | Next State / Output .... $\qquad$ .... |



## FSM Representation

$\square$ It can also be represented using a state diagram which has the same information as the state transition table.

Input / Mealy Output
$\square$ Mealy Output
Outputs $=\mathrm{F}$ (Inputs, Current state) Next state $=$ F(Inputs, Current state)

Moore Output
Outputs $=F($ Current state $)$
Next state $=F($ Inputs, current state $)$


Input / Mealy Output

## Suggestion: do NOT mix Mealy and Moore in one design



## Example 1: A Mod-4 Synchronous Counter

$\square$ Function: Counts from 0 to 3 and then repeats; Reset signal reset the counter to 0 .
$\square$ lt has a clock (CLK) and a RESET input.
$\square$ Outputs appear as a sequence of values of 2 bits (q1 q0)
$\square$ As the outputs are generated, a new state (s1 s0) is generated which takes on values of 00, 01, 10, and 11.


## State Transition Table of Mod-4 Counter



One input is missing!

## State Transition Diagram for the Mod-4 Counter



## Use meaningful names for states



## Example 2: Lock

$\square$ Pushing: * $\{$ A; B; B; A \} => Open


- $A \& B$ never push at the same time
- Have to release the button before next pushing



## State Diagram for lock-FSM

$\square A$ and $B$ are never pressed at the same time ...
$\square$ Debounce before next pushing


Finish the state graph for the Lock-FSM (5min)

## State Diagram for lock-FSM

$\square A$ and $B$ are never pressed at the same time ... $\square$ Debounce before next pushing


Consider all the input possiblities at each state

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## Output Timing: Moore


$\square .$. a Moore machine is not able to produce A->1 until the next clock when it enters s1


## Output Timing: Mealy


$\square$ When in s0, a Mealy machine may produce A->1 immediately in response to R ->1

## Output Timing: Moore and Mealy


$R=\theta / A=0$


## Moore vs. Mealy (summary)

$\square$ A Moore machine produces glitch free outputs.
$\square$ A Moore machine produces outputs depending only on states, and this may allow using a higher-frequency clock.
$\square$ A Mealy machine can be specified using less states because it is capable of producing different outputs in a given state.
$\square$ A Mealy machine can be faster because an output may be produced immediately instead of at the next clock tick.
$\square$ Which one is better?
-Edge sensitive control
$\square$ E.g., enable signal of counter
$\square$ Both can be used but Mealy is faster
-Level sensitive control
$\square E . g .$, write enable signal of SRAM
$\square$ Moore is preferred for glitch free

?

